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A general database of hydrometeor single scattering properties at microwave and sub-millimetre wavelengths

Patrick Eriksson¹, Robin Ekelund¹, Jana Mendrok¹, Manfred Brath², Oliver Lemke², and Stefan A. Buehler²

¹Department of Space, Earth and Environment, Chalmers University of Technology, Gothenburg, Sweden

²Meteorological Institute, Department of Earth Sciences, Center for Earth System Research and Sustainability, Universität Hamburg, Hamburg, Germany

Correspondence: Patrick Eriksson (patrick.eriksson@chalmers.se)

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Abstract. A main limitation today in simulations and inversions of microwave observations of ice hydrometeors (cloud ice, snow, hail, etc.) is the lack of data describing the interaction between electromagnetic waves and the particles. To improve the situation, the development of a comprehensive dataset of such “scattering properties” has been started. The database aims at giving a broad coverage in both frequency (1 to 886 GHz) and temperature (190 to 270 K), to support both passive and active current and planned measurements, and to provide data corresponding to the full Stokes vector. This first version of the database is restricted to totally random particle orientation. Data for 34 particle sets, i.e. habits, have been generated. About 17 of the habits can be classified as single crystals, three habits can be seen as heavily rimed particles, and the remaining habits are aggregates of different types, e.g. snow and hail. The particle sizes considered vary between the habits, but maximum diameters of 10 and 20 mm are typical values for the largest single crystal and aggregate particles, respectively, and the number of sizes per habit is at least 30. Particles containing liquid water are also inside the scope of the database, but this phase of water is so far only represented by a liquid sphere habit. The database is built upon the netCDF4 file format. Interfaces to browse, extract and convert data for selected radiative transfer models are provided in MATLAB and Python. The database and associated tools are publicly available from Zenodo (<https://doi.org/10.5281/zenodo.1175572>, Ekelund et al., 2018b, and <https://doi.org/10.5281/zenodo.1175588>, Mendrok et al., 2018, respectively). Planned extensions include non-spherical raindrops, melting particles and a second orientation case that can be denoted as azimuthally random.

1 Introduction

1.1 Motivation

Atmospheric particles absorb, emit and scatter electromagnetic radiation. The optical properties governing these processes are not easily determined for an arbitrarily shaped particle (e.g. Min et al., 2006). Accordingly, these properties can not be calculated “on-the-fly” and radiative transfer simulations must frequently make use of tabulated values. At microwave wavelengths, the targets of a database of particle optical properties are hydrometeors, i.e. cloud and precipitating particles that consist of condensed water. The need to

consider particle shape in detail increases with frequency and is the highest for hydrometeors containing ice. Aerosols can in general be neglected for microwave radiative transfer, but measurements of volcanic ash are another potential application of sub-millimetre radiometry (Baran, 2012a).

Microwave particle optical properties, also often denoted as scattering data, are most obviously needed for measurements of precipitation and cloud properties. Active instruments, i.e. radars, perform such measurements by detecting backscattering of hydrometeors, but extinction of the signal must also be considered. Radars targeting rain operate at relatively low frequencies and are well established

(Doviak and Zrnic, 2014). For example, ground-based networks of precipitation radars are today found in many countries. The sensitivity to cloud particles and snow increases with frequency. The highest standard radar frequency today is 94 GHz (Kollias et al., 2007), used from both ground (e.g. Hogan et al., 2000) and aircraft (e.g. Bouniol et al., 2010) and by the first space-based cloud radar onboard CloudSat launched in 2006 (Stephens et al., 2008) as well as the CPR instrument onboard ESA's EarthCARE mission (Illingworth et al., 2015).

Rain and ice particles affect passive microwave radiances by scattering as well as by contributing to absorption and emission (e.g. Liou, 2002). The relative importance of absorption and emission is the highest for particles that are small compared to the wavelength, and also higher for liquid particles, compared to ice ones, due to differences in refractive index. The present set of operational microwave sensors covers frequencies of up to about 190 GHz (e.g. Weng et al., 2012). The main hydrometeor products of these measurements today are cloud liquid water and rain (Boukabara et al., 2011). Ice hydrometeor retrievals exist (e.g. Boukabara et al., 2013), but are less established and are often purely empirical using satellite radar data for “training” (Holl et al., 2014; Piyush et al., 2017).

At present, the sub-millimetre part of the microwave region is primarily used for limb sounding. These instruments target mainly the stratosphere and mesosphere, but can provide data on humidity and cloud ice down to about 10 km (Wu et al., 2008; Eriksson et al., 2014). Sub-millimetre measurements dedicated to the troposphere are so far only available for some aircraft instruments (Evans et al., 2012; Fox et al., 2017; Brath et al., 2018). Operational sensors, such as used for weather forecasting, making use of sub-millimetre wavelengths will be available from about 2022 (Kangas et al., 2012). The addition of this wavelength region will improve the general sensitivity of passive microwave measurements, particularly regarding ice hydrometeors. Adding this wavelength region should provide a better constraint on particle size of frozen hydrometeors and, not only the sensitivity, but also the accuracy of ice hydrometeor mass retrievals should be improved (Evans and Stephens, 1995; Buehler et al., 2007a).

Scattering data are not only important for the direct measurement of hydrometeors, but also essential to characterise the interference of clouds and precipitation on measurements targeting other quantities. One such example is the “cloud screening”, applied in humidity retrievals, based on channels around the 183 GHz water vapour spectral line (Buehler et al., 2007b). The addition of sub-millimetre channels should facilitate this cloud screening. Passive microwave data, particular using channels on the low-frequency end, are also used to estimate ocean surface variables, and even these retrievals are affected by hydrometeors. The characterisation of this interference can even involve polarisation effects (Adams et al., 2008).

In summary, microwave sensors offer information on cloud and precipitation, as well as surface variables, humidity and other gases with relatively low cloud interference (Kunzi et al., 2011). These advantageous aspects are today heavily used for both climate studies and weather prediction. However, the full potential of existing data is far from fully exploited (e.g. Guerbet et al., 2016), and preparations for future measurements are needed (e.g. Buehler et al., 2012; Birman et al., 2017). In both cases, progress is today strongly limited by a lack of hydrometeor scattering data (Geer and Baordo, 2014). Liquid particles can to a large extent be assumed to be spherical, and their scattering properties can be calculated efficiently by Mie theory. On the other hand, both cloud and snow ice hydrometeors exhibit a huge variability in shape (e.g. Lynch et al., 2002; Garrett et al., 2015; O'Shea et al., 2016), and to derive their scattering properties is a demanding calculation task. These complications have resulted in patchy coverage of ice hydrometeor microwave scattering properties.

1.2 Single scattering data

To be of a general character, scattering data must cover a number of attributes, as discussed in later sections. For a given particle, the scattering properties vary with frequency, polarisation, temperature and orientation. Furthermore, particle size and shape play a significant role where the comprehensive description of particle shape is less clear. Several measures on particle size are being used, but those represent a small complication in comparison to morphology classification. Traditional schemes, such as Magono and Lee (1966), offer a good starting point regarding the classification of pristine crystals. Ice hydrometeors above about 200 μm in maximum dimension tend to be aggregates of crystals (Schmitt and Heymsfield, 2014); hence, aggregates should in general dominate the scattering signatures in microwave data, which is mainly determined by particles larger than 100 μm (Eriksson et al., 2008). However, there is no established manner to categorise particle classes. So far aggregates are described in relatively crude terms, by, for example, effective density and degree of riming. A further complication is that both liquid and ice water can be found in a particle simultaneously. The so-called radar bright band is normally taken as a manifestation of the presence of melting ice hydrometeors (Sassen et al., 2007).

A review of existing microwave scattering data was done by Eriksson et al. (2015). At that point, the most general collection was provided by Liu (2008) despite it having been limited to totally random particle orientation, frequencies below 340 GHz and low complexity in particle morphology. The only source of data covering sub-millimetre wavelengths was Hong et al. (2009), but it was found to be based on an outdated ice refractive index parameterisation. More complex ice particles, i.e. particles of aggregate type, had been considered (Tyynelä and Chandrasekar, 2014), but then pro-

viding data with limited frequency coverage and mainly targeting radar applications. More recently, Kuo et al. (2016) presented data for a large number of habits, including many aggregate realisations, but the publicly available data lack detailed information and provided only parameters applicable in simplified radiative transfer. The data of Lu et al. (2016) have interesting features regarding particle shapes and orientation, but are not well suited for passive microwave applications since they are based on an obsolete, and inaccurate, refractive index parameterisation (see Sect. 4.1 for details). The data of Ding et al. (2017), which are an updated and extended version of the database by Hong et al. (2009), cover 1 to 874 GHz, at multiple temperatures, and can thus be considered to be the first to provide full coverage of the microwave region, but are still limited to totally random orientation and relatively simple habits.

Besides the production of databases, there are a number of investigations of relationships between particle properties and optical properties. For example, the data of Ding et al. (2017) were compared to the scattering properties of more complex, snow-like, particles by Baran et al. (2018). The impact of riming on scattering properties was studied by Leinonen and Szyrmer (2015), using a triple-frequency approach. A clear shift in radar signature was observed as riming was gradually applied to pristine aggregates. Also, data for melting particles have been reported (Ori et al., 2014; Johnson et al., 2016), showing an increase in extinction and backscattering at increasing melting fractions.

In summary, important progress has been made, but there are still important gaps in available data. Based on the findings in Eriksson et al. (2015), a decision was taken to gradually build up a database of microwave scattering properties, with the long-term goal of providing a comprehensive source of such data. The ambition is to provide data of a general character supporting both passive and active observations involving polarimetric information in a consistent manner. A secondary objective is to ensure that advanced scattering solvers (e.g. RT4 by Evans and Stephens, 1995 and MC by Davis et al., 2005) as included in the ARTS-2 forward model (Eriksson et al., 2011a; Buehler et al., 2018) can be fully utilised. In the following, we will hence refer to this data compilation as the “ARTS scattering database”.

The first version of the database is presented below. The database is not complete. This version lacks at least features found in some databases targeting radar applications, but this version is already more extensive than comparable efforts with a broad scope. The frequency coverage is high, very similar to the one of Ding et al. (2017), and multiple temperatures are covered. Full polarimetric data are given. A special emphasis has been given to improvements in the representation of aggregates; 34 ice hydrometeor habits of totally random orientation are included, with 16 of these being of aggregate type. Pure liquid particles are also covered, in the form of liquid spheres. Data for more specific orientations (such as particles with a preference for the horizontal plane)

are left for the next database version. Non-spherical liquid particles and melting particles are other planned database extensions.

An overview of the database content is found in Sect. 2. A number of software tools have been used to generate the database, and those are presented in Sect. 3. The various microphysical assumptions are summarised in Sect. 4. Example results are found in Sect. 5. Data format, interfaces and availability are discussed in Sects. 6 and 7. Finally, conclusions are found in Sect. 8.

2 Database content

This section gives an overview of the optical properties provided, and the coverage of the database in terms of frequency, size, temperature and habits.

2.1 Radiative properties

The optical properties of a particle can be reported in several ways. The ARTS database assumes that electromagnetic radiation is described using the Stokes formalism and provides the extinction matrix, the absorption vector and the phase matrix. These quantities are most easily introduced by considering the basic radiative transfer equation:

$$\frac{d\mathbf{I}(\nu, \mathbf{r}, \mathbf{n})}{ds} = -\mathbf{K}(\nu, \mathbf{r}, \mathbf{n})\mathbf{I}(\nu, \mathbf{r}, \mathbf{n}) + \mathbf{a}(\nu, \mathbf{r}, \mathbf{n})B(\nu, \mathbf{r}) + \int_{4\pi} \mathbf{Z}(\nu, \mathbf{r}, \mathbf{n}', \mathbf{n})\mathbf{I}(\nu, \mathbf{r}, \mathbf{n}')d\mathbf{n}', \quad (1)$$

where \mathbf{I} is the Stokes vector of the radiance, ν is the frequency, \mathbf{r} is the position, \mathbf{n} is the propagation direction, s is the distance along \mathbf{n} , \mathbf{K} is the extinction matrix, \mathbf{a} is the absorption vector, B is the Planck function, \mathbf{Z} is the phase matrix and \mathbf{n}' represents the propagation direction of radiation scattered towards \mathbf{n} . See Mishchenko et al. (2002) for an exact definition of the Stokes vector assumed, as well as for details regarding assumptions and relationships implied by the equation. Note that \mathbf{a} can be derived from \mathbf{K} and \mathbf{Z} , but is included in the database anyways in order to avoid numerical issues and ensure good accuracy of all three main quantities.

To be clear, \mathbf{K} , \mathbf{a} and \mathbf{Z} in Eq. (1) represent bulk properties, while the database provides these quantities on a particle basis, which are dependent on particle size and dielectric properties. Furthermore, the scattering is assumed to be incoherent between particles, and the bulk properties are simply obtained by summing up \mathbf{K} , \mathbf{a} and \mathbf{Z} of all particles inside the considered atmospheric volume. Information allowing radiative transfer with the full Stokes vector (length 4) is provided. However, transformations are used in order to save storage space, and some processing of the data is needed (Sect. 6.1) before they can be applied in Eq. (1).

The radiative transfer equation is not always expressed as in Eq. (1), but it should be possible to derive the quantities

found in other versions of the equation from the optical properties provided. For example, some “scattering solvers” operate with the single scattering albedo and the asymmetry parameter. These scalar quantities can be calculated from the elements in \mathbf{K} , \mathbf{a} and \mathbf{Z} matching the first Stokes component. The main quantity for simulations of radar measurements is backscattering, which essentially is the value of \mathbf{Z} representing the backward direction. For further details around these derived properties, see the database technical report (Ekelund et al., 2018a).

2.2 Particle orientation

The database considers orientation-averaged quantities only. In general, using the scattering matrix \mathbf{Z} as an example, orientation-averaged quantities are calculated as

$$\mathbf{Z}_o(\mathbf{n}', \mathbf{n}) = \int_0^{2\pi} \int_0^{2\pi} \int_0^{2\pi} p_\alpha(\alpha) p_\beta(\beta) p_\gamma(\gamma) \mathbf{Z}(\mathbf{n}', \mathbf{n}, \alpha, \beta, \gamma) \sin\beta \, d\alpha \, d\beta \, d\gamma, \quad (2)$$

where \mathbf{Z}_o is the orientation-averaged scattering matrix, α , β and γ are the three Euler angles describing the orientation of particles, and p_j are probability density functions describing the distribution of particle orientations.

The database currently only covers particles in one orientation mode: totally random, defined as the distribution where all particle orientations are equally probable. That is, p_α , p_β and p_γ are all uniform distributions. The database is designed and intended to also include what can be denoted as azimuthally random orientation. In this orientation case, the angles α and γ are fully random as for the totally random case, while the data are evaluated at some discrete tilt angle β (i.e. p_β is a Dirac delta function). By integrating over β , arbitrary fluttering distributions can then be determined. It turns out that azimuthally random orientation is much more costly with respect to both calculation burden and data storage, and this orientation mode is left for the next database version.

Also, a reference particle alignment must be defined, as it affects both our definition of aspect ratio (Sect. 2.3) and data for azimuthally random orientation. The reference alignment should be linked to how ice particles on average are oriented in the atmosphere. Accordingly, we align the particle with its maximum principal moment of inertia axis parallel to the z -axis. Furthermore, the minimum principal axis is aligned along the x -axis. This approximates the mean alignment of falling particles without performing extensive aerodynamics simulations. The definition is also stable in the sense that particular features, such as a narrow arm of a particle, will have less impact than the overall mass distribution of the particle.

2.3 Size and shape descriptors

Quantitatively characterising size and shape of irregularly shaped particles is a non-trivial task. We provide several de-

scriptive values on particle size. First of all, particle mass m is reported. Secondly, the volume equivalent diameter is given, which is related to mass by

$$D_{\text{veq}} = \left(\frac{6m}{\pi\rho} \right)^{1/3}, \quad (3)$$

where ρ is the actual density of the material found in the particle, in the case of ice set to 916.7 kg m^{-3} . Note that D_{veq} relates to the diameter of the volume-equivalent ice sphere, not of a mass equivalent melted sphere. The size parameter applied, x , is defined with respect to D_{veq} :

$$x = \pi D_{\text{veq}}/\lambda, \quad (4)$$

where λ is the wavelength.

Another common parameter is the maximum dimension D_{max} (sometimes used interchangeably with the maximum diameter), for which no standard convention exists. For instance, photography-based in situ measurements often derive the maximum dimension by the largest distance between two pixels in a 2-D image. Such a definition is highly dependent on the particle orientation with respect to the camera. In the ARTS database D_{max} is defined as the diameter of the minimum circumscribing sphere, which takes the whole 3-D structure into account. However, ice particles are often highly irregular, and since D_{max} is a measure of a particle's extreme points, it is an inherently ambiguous and ill-defined parameter.

Similarly, the aspect ratio (AR) is defined differently by different authors. In general it provides a measure of the non-sphericity of the particle of concern, thus affecting the particle's preferred orientation and its scattering properties (polarimetric quantities in particular). The definition of AR is ambiguous and ill defined, similar to D_{max} . Our definition of AR is linked to how the particle is oriented with respect to the horizontal plane. Based on the particles' reference orientation outlined in Sect. 2.2, we define AR as the ratio of the maximum particle span found in the XY -plane to the span along the z -axis.

Axial ratio is sometimes used interchangeably with aspect ratio. We restrict the use of this term to describe the shape of hexagonal prism columns and plates, with axial ratio defined as $L/(2a)$ where L is the height of the prism and $2a$ its diameter. With this definition, columns/plates have an axial ratio above/below unity.

The database also contains a simplistic measure of the aerodynamic cross-sectional area for each particle. The variable stored is the diameter of a circle with an area equal to the cross-sectional area when viewing along the zenith angle. For this calculation the particle orientation is assumed fixed in its reference position.

2.4 Habits

The term “habit” is frequently used in the context of particle shape. We define habit as a set of particles with a common ba-

Table 1. Habits included in the first version of the database. Habits marked with * have scattering properties calculated using Mie theory. The last column displays the software or source used to create the shape data of the given habit, with abbreviations being SFTK (SnowFlake ToolKit, Sect. 3.1.1), RC (RimeCraft, Sect. 3.1.2), RSP (Recreated Shape Data, Sect. 4.2) and ESP (External Shape Data, Sect. 4.3.1). See the text for further details.

Habits	Id	D_{\max} (μm)	D_{veq} (μm)	No. of sizes	a	b	Software used
Ice:							
Single crystals:							
Pristine:							
Plate type 1	9	13–10 000	10–2596	45	0.76	2.48	RSP
Column type 1	7	14–10 000	10–1815	45	0.037	2.05	RSP
Thin plate	16	25–5059	10–2000	35	30	3.00	RSP
Thick plate	15	16–3246	10–2000	35	110	3.00	RSP
Block column	12	13–2632	10–2000	35	210	3.00	RSP
Short column	13	17–3303	10–2000	34	110	3.00	RSP
Long column	14	24–4835	10–2000	35	34	3.00	RSP
Sector snowflake	3	20–12 000	20–1415	34	0.00081	1.44	RSP
Ice sphere*	24	1–50 000	1–50 000	200	480	3.00	Mie
ICON cloud ice	27	13–10 000	10–2929	45	1.6	2.56	SFTK
GEM cloud ice	31	10–3088	10–3000	45	440	3.00	SFTK
6-bullet rosette	6	16–10 000	10–2371	45	0.48	2.42	RSP
5-bullet rosette	2	17–10 000	10–2231	45	0.4	2.43	SFTK
Perpendicular 4-bullet rosette	10	18–10 000	10–2071	45	0.32	2.43	SFTK
Flat 4-bullet rosette	11	18–10 000	10–2071	45	0.32	2.43	SFTK
Perpendicular 3-bullet rosette	4	19–10 000	10–2137	45	0.44	2.47	SFTK
Flat 3-bullet rosette	5	20–10 000	10–1882	45	0.2	2.43	SFTK
Aggregates:							
Pristine:							
Evans snow aggregate	1	32–11 755	50–2506	35	0.20	2.39	ESP
Tyynelä dendrite aggregate	26	595–20 826	228–3328	35	0.10	2.25	ESP
8-column aggregate	8	19–9714	10–5000	39	65	3.00	RSP
Small column aggregate	17	105–3855	37–738	35	0.14	2.45	SFTK
Large column aggregate	18	368–19 981	128–3021	35	0.25	2.43	SFTK
Small block aggregate	21	100–7328	72–1665	35	0.21	2.33	SFTK
Large block aggregate	22	349–21 875	253–4607	35	0.35	2.27	SFTK
Small plate aggregate	19	99–7054	53–1376	35	0.077	2.25	SFTK
Large plate aggregate	20	349–22 860	197–4563	34	0.21	2.26	SFTK
ICON hail	30	120–5349	94–5000	35	380	2.99	RC
ICON snow	28	120–20 000	94–3219	35	0.031	1.95	RC
GEM hail	29	120–5031	94–5000	35	540	3.02	RC
GEM snow	32	170–10 459	94–5000	35	24	2.86	RC
Rimed:							
Spherical graupel	23	622–9744	454–5293	30	13	2.69	SFTK
ICON graupel	29	170–6658	94–5000	35	390	3.13	RC
GEM graupel	33	120–6597	94–5000	35	170	2.96	RC
Liquid:							
Liquid sphere*	25	1–50 000	1–50 000	200	523	3.00	Mie

sic morphology and following a rule on how the morphology varies with size. As an example, a common habit assumption is hexagonal columns having an aspect ratio that depends on size according to an analytic expression. Furthermore, the relationship between maximum diameter and mass of a habit is

commonly parameterised by two constants, a and b , as

$$m = a D_{\max}^b. \quad (5)$$

The a and b values reported below assume SI units. As a reference, a habit consisting solely of ice spheres has $a = 480$ and $b = 3$. The goal is that the database habits will follow

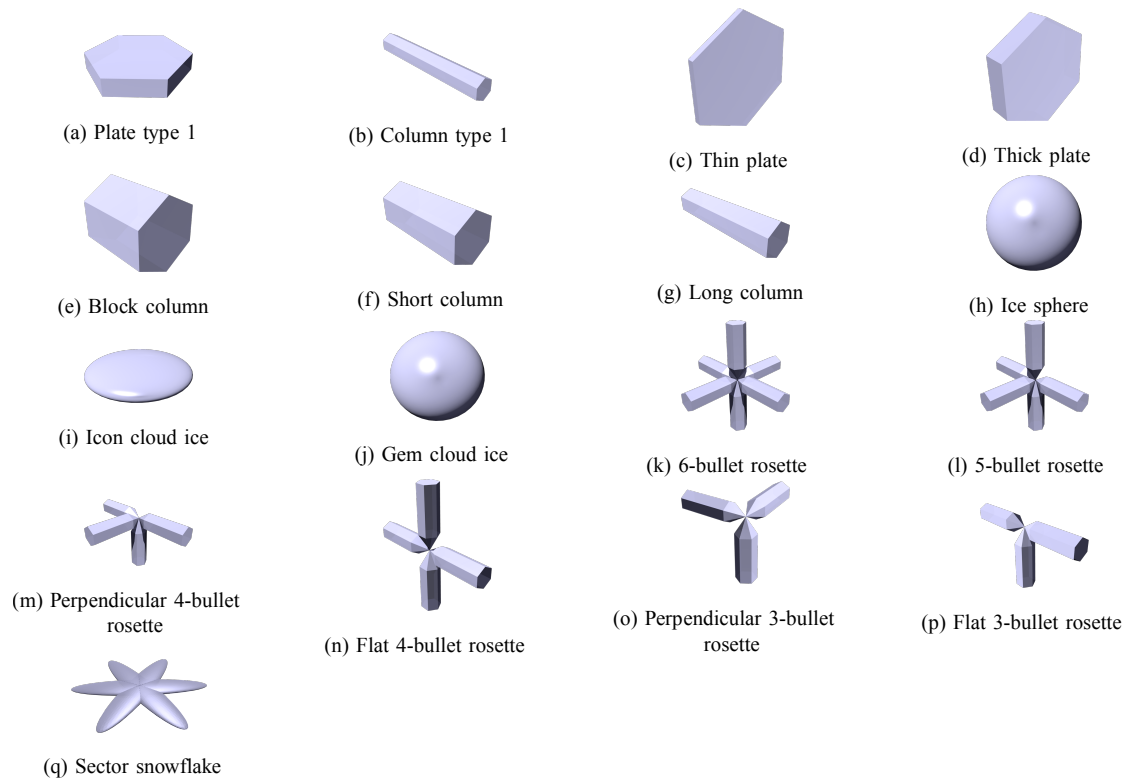


Figure 1. Single crystal habits included in the first database version. Shown particle orientation varies between the habits. Despite images (h) and (j) looking identical, they depict different particles; gem cloud ice (j) is a habit consisting of oblate spheroids with aspect ratio ≈ 0.92 .

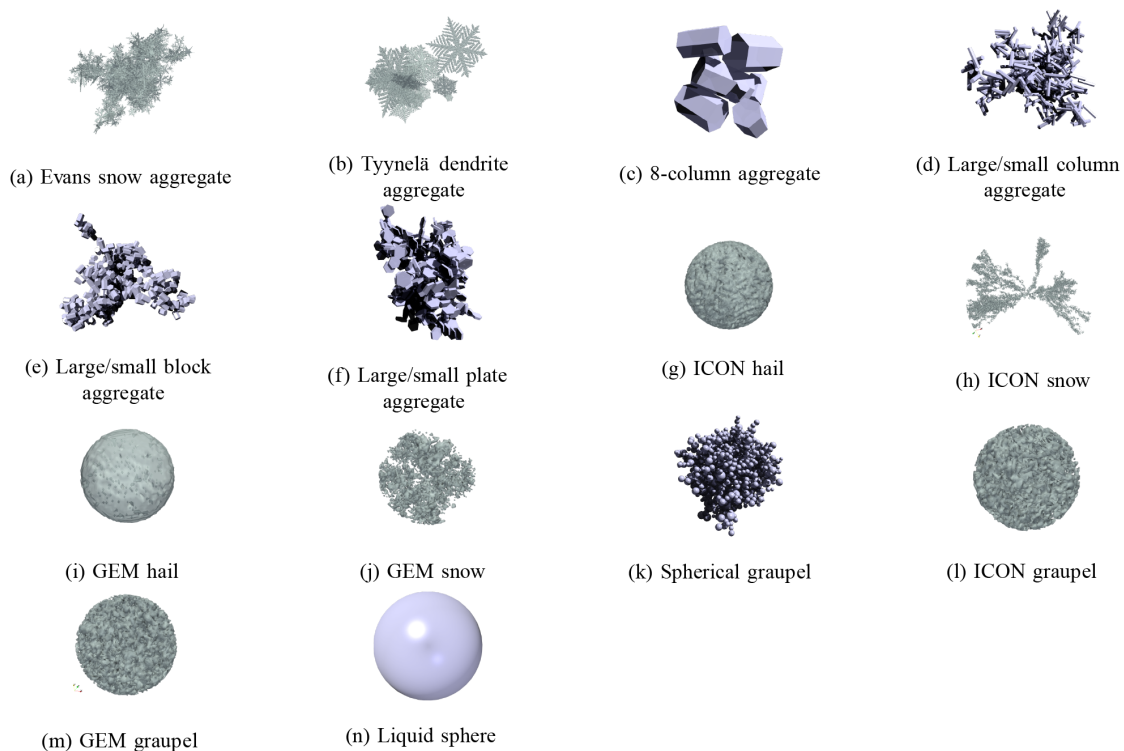


Figure 2. Aggregate and liquid habits included in the first database version. Shown particle orientation varies between the habits.

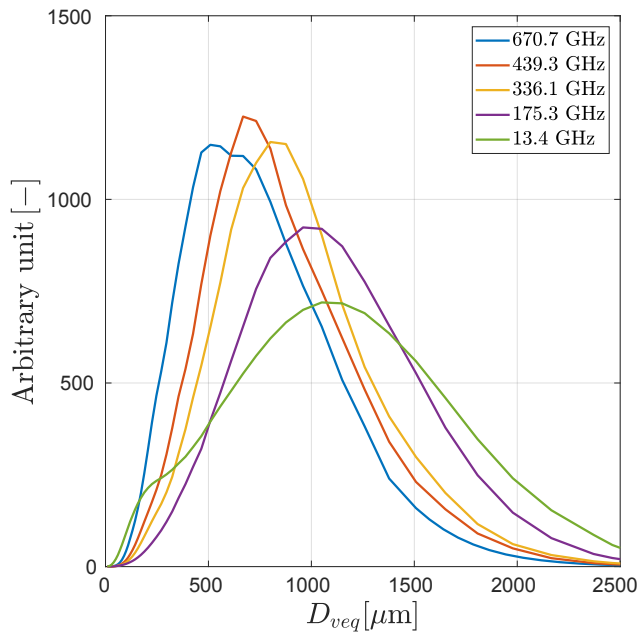


Figure 3. Contribution of differently sized particles to bulk extinction at a number of frequencies. The area under each curve has been normalised to unity. Calculated using the 6-bullet rosette habit and the tropical version of the Field et al. (2007) particle size distribution, assuming 270 K and an ice water content of 1 g m^{-3} .

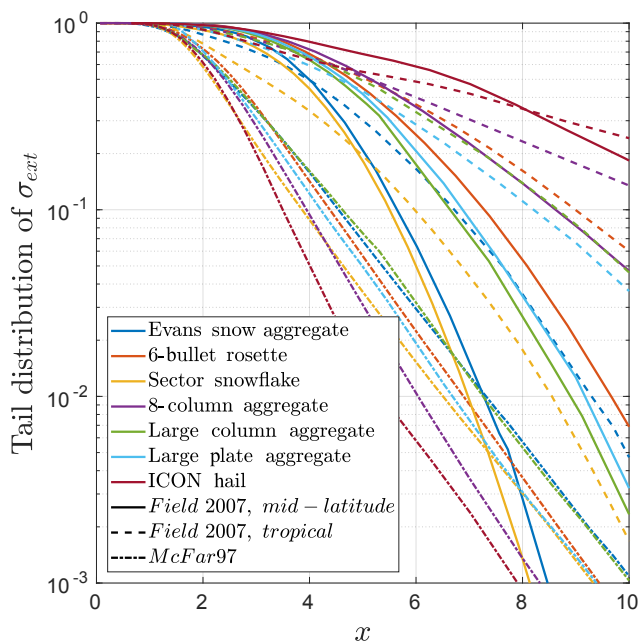


Figure 4. Tail distribution of extinction (see text for details), at 670.7 GHz and assuming 270 K and an ice water content of 1 g m^{-3} , for some combinations of habit and particle size distribution (PSD). Solid and dashed lines are results using the tropical and mid-latitude versions of Field et al. (2007) as the PSD, while dashed–dotted lines show results using the PSD of McFarquhar and Heymsfield (1997).

Table 2. Database habit classification and structure.

Habit classification	
Attribute	Possible cases
Orientation	Totally random
	Azimutally random
Phase	Ice
	Melting
	Liquid
Aggregation	Single crystal
	Aggregate
Riming	Pristine
	Rimmed

Eq. (5) as far as possible, but an exact fit is normally not possible, for example, when using third-party generated shape data. For $b < 3$, Eq. (5) can only be considered valid above some threshold size, normally of the order of $100 \mu\text{m}$, because Eq. (5) otherwise requires unphysically high densities (“superdensity”) for D_{max} below the threshold size.

In total, 34 habits divided into several subgroups are provided (Table 1). Each habit is assigned a unique Id number. Visualisations of the single crystal and aggregate habits are displayed in Figs. 1 and 2, respectively. The a and b parameters given in Table 1 were calculated by a least squares fit between $\log(m)$ and $\log(D_{\text{max}})$, including only particles having a $D_{\text{max}} \geq 200 \mu\text{m}$.

As mentioned, no totally general classification of particle shape exists, but for user friendliness the database is structured according to a rough categorisation of the habit type. The top category is “phase”: liquid, ice or melting. Melting is not covered by the current database version, but such habits are intended to be included in the future and the database structure is set up accordingly. The ice and melting habits are further divided between single crystals and aggregates. This classification level is not applied for liquid particles. Both single crystals and aggregates are classified as either pristine or rimed. Table 2 gives an overview of this categorisation. Further information on how the particles were generated is provided in Sect. 3.1.

2.5 Size grid

The number and range of sizes are not identical between the habits for a number of reasons. For some habits, mainly aggregates, it is not possible to generate shape data on a predefined size grid. Certain habits have been provided by third-party sources, where control of the size grid is limited. Furthermore, the methodologies of designing habits have evolved over the time of the database creation. Lastly, it makes sense to target different size ranges with single crystal and aggregate habits. However, the general strategies to set the size grids are similar.

The minimum number of sizes was set to 30, but single crystal data are still provided for 35 to 45 sizes. Aggregates have mainly 35 sizes. The size ranges of the habits (see Table 1) are not consistent, due to the diversity in methods to generate the shape data. However, target ranges were set to give a reasonable coverage of particle sizes reported in the literature. The single crystals' habits have sizes reaching either 2 mm in D_{veq} or 10 mm in D_{max} . The aggregates go up to 5 mm in D_{veq} or 20 mm in D_{max} . Exceptions are the aggregates consisting of relatively small crystals, where it was computationally too costly to reach the upper limit of any of the target ranges. The smallest single crystal particles are mostly $D_{\text{veq}} = 10 \mu\text{m}$. The smallest aggregates mainly have $D_{\text{veq}} < 100 \mu\text{m}$, but this criterion is not met when the constituting crystals are larger than this limit. Habits consisting of solid spheres (handled by Mie code) were allowed both to have more sizes (200) and cover larger size ranges, in order to allow detailed reference calculations using these habits. The final size range of all habits is found in Table 1. The general strategy to select intermediate sizes is to aim for an approximately equidistant linear spacing of up to $D_{\text{veq}} = 100 \mu\text{m}$ and equidistant spacing in the logarithm of D_{veq} above.

Additionally, an upper limit with respect to size parameter (x) was introduced for practical reasons since the computational burden to calculate the scattering properties increases strongly with x . That it is possible to apply a limit on x is due to the fact that the size range that contributes the most to bulk scattering properties is shifted towards smaller sizes when going up in frequency. That is, for a given (large) particle, x itself increases with frequency, but the particle becomes less influential for the scattering properties of the overall local particle mix. This effect is illustrated in Fig. 3 for extinction. An analysis of backscattering would give a similar result as extinction and backscattering are highly correlated (both increase with D^6 in the Rayleigh regime, etc.).

Figure 4 demonstrates that $x = 10$ is a reasonable limit. It shows the estimated relative error in the calculation of bulk extinction considering data to a given limit in x . Figure 4 presents a worst case scenario as a relatively high ice water content (1 g m^{-3}) and a frequency in the upper end of the database's coverage (671 GHz) are considered. Particles with $x < 1$ contribute marginally to the bulk extinction here indicated by the tail distribution staying close to 1 up to about $x = 1$. There are three cases in Fig. 4 where the tail distribution is well above 10 % even at $x = 10$. These cases are all combinations with the PSD of Field et al. (2007) and habits having $b = 3$. This PSD is intended for snow-type hydrometeors, where b around 2 is expected (Baran, 2012b). That is, these three cases of concern represent fairly unrealistic, or extreme, assumptions.

It is not unlikely that further problematic situations with respect to the PSD exist apart from those three cases presented above, and occasional errors above 10 % can not be ruled out. On the other hand, it should be remembered that the water vapour absorption at 671 GHz is high, giving a de-

creased sensitivity to lower altitudes, where most large particles are found most frequently, when observed by satellite instruments. In summary, our interpretation of Fig. 4 is that the error by applying a limit at $x = 10$ should in general be well below 10 %.

The size limit with respect to x is evaluated separately for each frequency. This means that, for example, at typical radar frequencies data are at hand for all sizes, while data can be lacking for large particles at higher frequencies. The limit was applied in such a way that, if possible, coverage up to $x = 10$ is maintained. That is, assuming that particles matching $x \geq 10$ are available, the smallest one exceeding the limit still got included.

2.6 Frequencies and temperatures

The overall frequency coverage was set to be 1–886.4 GHz. Inside this range, optical properties are given for 34 frequencies (Table 3). A majority of the frequencies were selected to bracket channel sets found on both existing and planned operational microwave sensors. These are in the following termed “channels” with arbitrary channel numbers assigned (see Table 3). For example, data are provided for 50.1 and 57.6 GHz, forming channel 3, which provides coverage of the standard set of microwave temperature sounding channels. Additional frequencies were picked to cover standard radar wavelengths, as well as to obtain a general coverage between 1 and 15 GHz. Above 200 GHz, the frequencies are mainly governed by the channels of the planned Ice Cloud Imager (ICI) mission (Kangas et al., 2012). The upper end at 886.4 GHz was set in order to support the ISMAR (Fox et al., 2017) and IceCube (Wu et al., 2015) instruments.

We stress that the database should be used with great care for frequencies outside the defined channel ranges. Whether interpolation between the channels can be applied must be judged from case to case. For example, interpolation to 170 GHz should not be problematic as the distance between channels 6 and 7 is small (in fact smaller than the width of channel 7 itself), while frequencies around, for example, 550 and 770 GHz can not be claimed to be properly covered by the database. The relevant measure to judge whether an interpolation can be performed should be the ratio between spacing and frequency, not the absolute size of the frequency spacing. As a general rule, only the closest database frequencies should be used when performing interpolation.

Optical properties are given for multiple temperatures, rather than a set of real and imaginary refractive index values. The reason for this is that the used parameterisations, Mätzler (2006) and Ellison (2007) for ice and water, respectively, should predict the refractive index with sufficiently high accuracy (Sect. 4.1). The selected set of temperatures contains 190, 230 and 270 K for hydrometeors consisting solely of ice. For pure liquid droplets, the temperatures are 230, 250, 270, 290 and 310 K. See Sect. 4.1 for further details regarding is-

Table 3. Included database frequencies. Frequencies above 18.6 GHz organised into channels (see text).

Channel	1	2	3	4	5	6	7	8	9	10	11	12
Freq. (GHz)	18.6 24.0	31.3 31.5	50.1 57.6	88.8 94.1	115.3 122.2	164.1 166.9	175.3 191.3	228.0 247.2	314.2 336.1	439.3 456.7	657.3 670.7	862.4 886.4
Other frequencies: 1, 1.4, 3, 5, 7, 8, 9, 10, 13.4, 15												

sues related to refractive index and to temperature interpolation.

3 Software and processing

This section provides an overview of the software used for the generation of the data. The generation of the database consists of two main steps. First, a description of the particle shape must be acquired, either from some analytic expression or by physical models of varying complexity (Sect. 3.1). Second, the actual single scattering properties are calculated (Sect. 3.2), mainly by the discrete dipole approximation (DDA) method (Sect. 3.2.1). The DDA calculations are complemented with a set of quality checks and modifications, with the purpose of ensuring high quality and consistency.

3.1 Shape data generation

3.1.1 Snowflake Toolkit

Particle shape data have mainly been generated using internally developed software (Rathsman, 2016)¹, called the *Snowflake Toolkit* (SFTK). The toolkit's main features are a format for representing crystal shapes in an analytic way, an algorithm for simulation of aggregation, and sampling routines for generating DDA input shape data.

The toolkit's shape format is used both internally in the simulation software and to specify output data. The format represents particles as polygon meshes. This makes it straightforward to not only represent simpler shapes, such as hexagons and bullets, but also aggregates of said crystals. Further, the same shape data file can be used both as input for dipole sampling or aggregate simulation. The dipole sampling routines can take both crystals or aggregates as input. An advantage of using a polygon representation along with a sampling routine is that the grid resolution can be set arbitrarily, depending on application. The grid accuracy can thus be adapted to frequency.

As mentioned, the software includes capabilities to simulate aggregation. A semi-physical model, inspired by Maruyama and Fujiyoshi (2005), is applied. The model can be considered to describe a small section in a cloud, with a number of ice particles inside the volume. Several events

can occur at each iteration: the aggregation of two particles, growth of a new crystal, particle melting or fallout of the cloud. The likelihood of these events depends on a number of factors such as size, estimated fall speed and control parameters. Contrary to most aggregate models used in the field, this model allows for the aggregation of two aggregates; the algorithm can consider aggregation between any particles that can be represented by the software's shape format.

Aggregation is modelled as if the two particles collide with each other at random angles and centre offsets. Aggregate sticking is only allowed to occur at particle faces, where the two involved surface normals are forced to be parallel (i.e. face-to-face sticking is ensured). This is achieved through rotation of the involved particles. For each candidate aggregation, it is checked if it has created any overlap between any combination of building blocks. If any overlap is found, the aggregation is discarded or a new try is made depending on the exact settings. The no-overlap condition is motivated by the fact that for pristine and compact crystals, little or no deformation should result from collisions and aggregation (by surface sticking). Also, volume calculations become significantly cheaper. There are a number of available control parameters. One such parameter is the number of particles allowed to populate the cloud at a given iteration. The available memory has to be taken into consideration here, but at least 5000 particles can be handled by a standard desktop computer. Growth, melting and drop-out ratio parameters are used to determine the relative likelihood of the different possible events.

As a complement, the aggregation of spheres is also handled. This version is more straightforward, but is less based on physics. The main application is for generating heavily rimed particles. The model describes a single aggregate particle, originally only a single sphere, onto which new spheres are added. Each new sphere is inserted from a random angle. It is allowed to let the spheres "tunnel" and reach the interior of the particle. The tunnelling feature is required to reach higher effective densities, but is not obligatory. It is also possible to set the angular distribution of the incoming spheres to be non-uniform, as a way of influencing the shape of the resulting aggregate. Other options and features available include maximum diameter (constraining the growth of the particle) and fill ratio (ensuring that a minimum effective density is achieved).

¹Code available at <https://github.com/milasudril/snowflake-toolkit> (last access: 11 July 2018).

3.1.2 RimeCraft

There is frequently a desire to generate particles fulfilling Eq. (5) for some predefined a and b . This task is hard to tackle with the Snowflake Toolkit, and, as an alternative, a small set of MATLAB functions was developed for this task (code can be obtained by contacting the authors). As the function set should also be useful for adding different degrees of riming, it was named *RimeCraft* (RC). It works by adding 3-D cubic blocks directly on the shape grid. Different rules can be defined for how to add blocks. Equation (5) is fulfilled by growing the particle inside subsequent thin layers, and calculating a fill ratio for each layer from the target a and b . The position of a new dipole is selected randomly, but weights can be specified to tune how a new dipole prefers to have “neighbours” or not. This controls the overall granularity of the particle. Finer details of the structure can be modified by setting different weights (that can be both positive and negative) with respect to face, edge and vertex neighbours. A complete habit can be created either by taking a snapshot at each intermediate size, as a single particle grows, or by re-running RimeCraft for each target D_{\max} .

An additional feature (not yet used for the database) is to simulate the melting of a particle. This feature largely follows the algorithm of Johnson et al. (2016). Here, an existing, gridded particle is used as starting point. The algorithm consists of two main steps at each iteration. First, all ice grid points are assigned weights based on the radius from the centre and their number of icy neighbours. A portion of the grid points with the highest weights are selected and converted to liquid. The liquid grid points are then allowed to move in order to mimic surface tension. The iterations continue until the desired melting fraction is achieved. A column particle, for example, would begin to melt at its tips, successively melt inwards and be converted to a drop.

3.2 Calculation of optical properties

3.2.1 ADDA

A vast majority of the scattering data have been produced by the Amsterdam DDA (ADDA), a DDA implementation developed by Yurkin and Hoekstra (2011). The basic idea of the DDA method is to represent the particle by a discretised equidistant Cartesian grid, where each grid point represents an electric dipole with polarisation \mathbf{P} . The DDA solution can be formulated as

$$\alpha_i^{-1} \mathbf{P}_i - \sum_{j \neq i} \bar{\mathbf{H}}_{ij} \mathbf{P}_j = \mathbf{E}_i^{\text{inc}}, \quad (6)$$

where α is the dipole polarisability, i and j are grid point indices, $\bar{\mathbf{H}}$ the total interaction term, and \mathbf{E}^{inc} the incoming electric field (Yurkin and Hoekstra, 2011). The equation is solved iteratively, and output quantities are derived via the resulting total electric field \mathbf{E}_i . This field can be derived when the polarisation field is known, using $\mathbf{P}_i = V_{\text{dp}} \chi_i \mathbf{E}_i$, where χ_i

is the susceptibility of the medium and V_{dp} the volume of a dipole. Without going into details, there are different formulations known for the susceptibility and the interaction terms. For this database, the “lattice dispersion relation” was used for the susceptibility and “interaction of point dipoles” for the interaction term (Draine and Flatau, 1994). The ADDA calculations are stopped when the relative norm of the residual, essentially the relative difference between the right and left parts of Eq. (6), reaches a user specified limit, denoted as ϵ_{DDA} . The selected value of ϵ_{DDA} thus determines the accuracy of the output and we have applied

$$\epsilon_{\text{DDA}} = 10^{-2}, \quad (7)$$

aiming for an accuracy of the order of a few percent.

The shape data, in the form of shape files, are the most important input required by ADDA. The discretised grid of a particle is defined in the shape file as three columns of grid coordinates. The grid is scaled such that only integer values are used as coordinates. An extra column can be added to index points with different refractive indices, which is only required for heterogeneous particles. Other essential input parameters are the particle volume equivalent radius (r_{veq}), radiation wavelength (λ), number of dipoles per wavelength (dpl), propagation vector of incoming radiation, the scattering grid, and orientation of the particle (Euler angles using zyz notation). The variable dpl is critical as it must be sufficiently large. We determine dpl such that we fulfil the standard criterion:

$$|m|kd < 0.5, \quad (8)$$

where m is the complex refractive index, k the wavenumber, and d the dipole size. The microwave refractive index of ice means that dpl should be ≈ 22 or higher. As an additional rule, the minimum number of dipoles was set to 1000, to enable the shape of particles of small x to also be resolved in a reasonable manner.

ADDA handles two orientation cases, either fixed or totally random. The later case is handled by Romberg integration (Davis and Rabinowitz, 1984). This method starts out with two scattering calculations, at orientation angles spaced 180° apart. The integrated average is then updated iteratively by adding scattering calculations at new angles, until convergence is achieved. This tends to happen faster for calculations of small size parameter x , whose scattering functions are less varying compared to large x . Note that while this averaging is expressed in Eq. (2) by three angles, only β and γ are varied in ADDA, as rotation over α is equivalent to rotation of the polarisation plane, which can be performed analytically. By effectively removing one dimension from the orientation “grid”, significant calculation time is saved. The convergence criterion refers here to maximum residual error of the averaging over each Euler angle, ϵ_{avg} . We have used

$$\epsilon_{\text{avg}} = 10^{-2} \quad (9)$$

for both Euler angles. All ADDA calculations found in the database so far have been calculated using ADDA's orientation averaging.

ADDA outputs the absorption cross section σ_a , extinction cross section σ_e , Mueller matrix \mathbf{M} , and amplitude scattering matrix \mathbf{S} . The Mueller matrix is a 4-by-4 matrix that relates the Stokes vector of incoming and scattered radiation, and is defined with respect to the scattering reference frame. The scattering cross section is related to the Mueller matrix by

$$\sigma_s = \frac{1}{k^2} \int_{4\pi} M_{11} d\mathbf{n}', \quad (10)$$

where k is the wavenumber. The amplitude scattering matrix relates also incoming and scattered radiation, but operates on the electric field. Both the Mueller and amplitude matrices have incoming and scattered angular dependence. Note that it is not possible to compute the amplitude matrix in conjunction with ADDA's orientation averaging option, as the amplitude matrix refers to coherent radiation and the averaging assumes incoherent interaction between the particles.

Some sanity checks, and possibly also some smaller corrections, are applied to the ADDA output.

1. Positivity. The cross sections σ_e and σ_a must be positive (≥ 0). The same applies to the M_{11} element at all angles. However, a violation of 1 % relative to the total extinction is allowed for σ_a , in which case σ_a is re-set to

$$\sigma_a = \sigma_e - \sigma_s. \quad (11)$$

2. Consistency. The extinction must be larger than both the scattering and absorption separately, i.e. $\sigma_e \geq \sigma_a$ and $\sigma_e \geq \sigma_s$. A violation of 1 % relative to σ_e itself is allowed. Furthermore, it is ensured that equivalent \mathbf{M} elements, i.e. M_{12} and M_{21} , and M_{34} and $-M_{43}$, do not deviate by more than 10 % from each other. If fulfilled, these elements are then re-set to the means of respective values for the purpose of consistency. For example, M_{34} is re-set to

$$M'_{34} = \frac{(M_{34} - M_{43})}{2}. \quad (12)$$

3. Energy conservation. The extinction must equal the sum of the absorption and scattering cross sections, i.e. $\sigma_e = \sigma_a + \sigma_s$. At this point, differences of up to 30 % have been allowed. This is an unsatisfactory situation, but issues around the sector snowflake habit forced us to apply this high value. These issues are likely associated with the extreme aspect ratios of large sector snowflakes, and we aim for having a more demanding limit in the next database version. The maximum deviation found among other habits is < 5 %.

DDA calculations that do not fulfil all of above criteria are recalculated with higher accuracy criteria.

Finally, the database quantities \mathbf{K} , \mathbf{a} and \mathbf{Z} are set as

$$\mathbf{a}_1 = \sigma_a, \quad (13)$$

$$\mathbf{Z} = \frac{1}{k^2} \mathbf{M}, \quad (14)$$

$$\mathbf{K}_{ii} = \sigma_e = \sigma_a + \sigma_s. \quad (15)$$

Other elements in \mathbf{a} and \mathbf{K} , i.e. $i \neq 1$ in \mathbf{a}_i and off-diagonal elements in \mathbf{K} , are set to zero according to the theory for totally randomly oriented particles (Mishchenko et al., 2002).

3.2.2 Mie theory

Two habits represented by spheres are included in the database, liquid and solid ice spheres. For the derivation of these scattering properties it is appropriate to make use of the well-established Mie theory, which provides an exact solution and is much more computationally efficient than DDA. The implementation in MATLAB by Mätzler (2002) was used. Two functions are used, `mie` and `mie_12`, where the former calculates scalar quantities, such as scattering efficiencies. The efficiency parameters are normalised scattering quantities with respect to the particle cross-sectional area, for example in the case of extinction

$$\sigma_e = \pi r^2 Q_e, \quad (16)$$

where r is the sphere radius. `mie_12` calculates the amplitude scattering matrix elements S_{11} and S_{22} . These elements describe the angular dependence of the plane-perpendicular and plane-parallel components of the scattered light relative to the incoming light. The S_{12} elements are zero since spheres cause no depolarisation. The amplitude scattering matrix is converted to the scattering matrix \mathbf{Z} using the wrapper code provided by the `Atmlab2` package.

4 Microphysical and dielectric data

This section deals with the microphysical and dielectric data employed for the database. Specifically, Sect. 4.1 discusses the refractive index models used, Sect. 4.2 and 4.3 describe single crystal and aggregate shape data, respectively, Sect. 4.4 explains how rime is included, and the subject of Sect. 4.5 is liquid particles.

4.1 Refractive index

Beside sizes and shapes of particles, single scattering properties are determined by the dielectric properties of the particle material. These are commonly described by the complex refractive index, where the real part mainly affects the scattering properties while the imaginary part primarily determines the absorption. The refractive index of liquid and

²<http://www.radiativetransfer.org/tools/> (last access: 11 July 2018)

frozen water at microwave frequencies varies significantly with frequency as well as with temperature.

A review of (water) ice refractive index models is shown in Eriksson et al. (2015), and a comparison between some models is also found in Fig. 5. The refractive index model by Ray (1972) is included in Fig. 5 as it strongly deviates from more recent parameterisations, based on a wider set of laboratory measurements, but it has still been applied in some recent studies (Lu et al., 2016; Gong and Wu, 2017). The most significant deviations are found for the imaginary part. This causes concern for at least passive measurements, as ice absorption has been shown to play a non-negligible role for such observations. (e.g. Eriksson et al., 2011b, 2015; Ding et al., 2017).

In Eriksson et al. (2015), the ice refractive index model by Mätzler (2006) was suggested as a good choice for the full microwave region (up to about 1 THz) and Earth atmospheric temperatures. Newer models (e.g. Warren and Brandt, 2008; Iwabuchi and Yang, 2011) refer or are essentially identical to Mätzler (2006). Hence, for our database, we set the refractive index of ice according to Mätzler (2006).

For liquid water, the model of Ellison (2007) is applied, which provides refractive indices for frequencies of up to 25 THz and temperatures between 0 and 100 °C based on empirical fits to an extensive collection of water refractive index data (Ellison et al., 1996). Deviations to the model by Turner et al. (2016), which focuses on super-cooled liquid water but does not cover sub-millimetre frequencies, remain smaller than 30 % even at the lowest temperatures of concern (−40 °C). Hence, although Ellison (2007) is, in the strict sense, not recommended for super-cooled liquid water, it is applied here at all temperatures.

Finally, a smaller study on the required temperature grid for ice habits was performed. Assuming optical properties of solid Mie spheres, a number of forward calculations with varying temperature grid resolution were compared. Forward calculations using a 2.5 K spaced temperature grid covering 150 to 270 K were used as a reference. A number of coarser grids, all equally spaced between 190 and 270 K and applying linear interpolation and extrapolation in temperature, were compared to the reference set. Simulations were performed for all channels employed by the ISMAR airborne radiometer (Fox et al., 2017) and 5000 atmospheric scenarios contained in Eresmaa and McNally (2014), in order to maximise the temperature profile diversity. Deviation statistics over these 5000 cases and the 13 channels were derived. Figure 6 summarises the results, showing that for a setup with three temperature grid points, maximum deviations to the reference simulations over all scenarios and channels are < 2 K, and the 99.7 percentiles of differences are < 0.2 K. For five grid points, maximum deviations fall below 0.3 K and the 99.7 percentile below 0.05 K. The accuracy can be improved further by applying higher-order polynomial temperature interpolation. A three-point grid was judged as a

good compromise between attainable simulation accuracy and the calculation burden required to generate the database.

4.2 Ice crystal shapes

The single crystal habits provided by the database are summarised in the upper part of Table 1. Example visualisations are found in Fig. 1. The crystal shapes are mainly based on parameterisations taken from the literature (Liu, 2008; Hong et al., 2009), but some new crystal habits have also been defined. For completeness and as a reference, the ice sphere habit was also included.

For crystal habits, external data are restricted to numerical parameterisations of shape properties, while the actual shape data matching those parameterisations were generated by the Snowflake Toolkit. The long column, short column, block column, thick plate and thin plate, taken from Liu (2008), are all hexagonal and have axial ratios of 4, 2, 1, 0.2 and 0.05, respectively. These axial ratios were defined by Liu (2008) to be constant over all sizes. As a consequence, they all obtain $b = 3$. In contrast, plate and column type 1, with dimensions taken from Hong (2007), are defined to have a b of 2.48 and 2.05, respectively, implying an axial ratio that grows with mass. These definitions were based on measurements of ice crystal dimensions (Auer Jr. and Veal, 1970; Mitchell and Arnott, 1994; Yang et al., 2000). The sector snowflake, defined in Liu (2008), is an idealised representation of a snowflake, consisting of three intersecting ellipsoids with their mass centres positioned at the origin. This parameterisation was based on surface measurements of aggregates (Kajikawa, 1982).

The different bullet rosette habits all consist of hexagonal bullets connected at the tips. The crystal dimensions are taken from Hong (2007), based on measurements listed in that paper. All bullets grow in a similar fashion, in the sense that all bullets with equal mass will have the same dimensions regardless of the considered habit. Furthermore, in all versions, the bullets are aligned perpendicularly to each other. The flat 3- and 4-bullet rosettes have all their arms lying in a common plane. The perpendicular versions have one arm rotated 90°, resulting in more compact particles.

Two crystal habits were generated specifically to match the a and b assumed for cloud ice in two atmospheric models: GEM (Global Environmental Multiscale Model) and ICON (Icosahedral non-hydrostatic general circulation model). The GEM model was prepared for the EarthCARE mission (Côté et al., 1998) and the ICON model is a part of the German HD(CP)2 project³. The GEM values ($a = 440$ and $b = 3$) imply a habit with low and constant aspect ratio, and are in fact very close to the ones of solid spheres. Accordingly, it was decided to apply spheroids for GEM cloud ice. For simplicity and to have some additional reference spheroidal reference data, the same basic shape was selected for ICON cloud

³<http://hdcp2.eu> (last access: 11 July 2018)

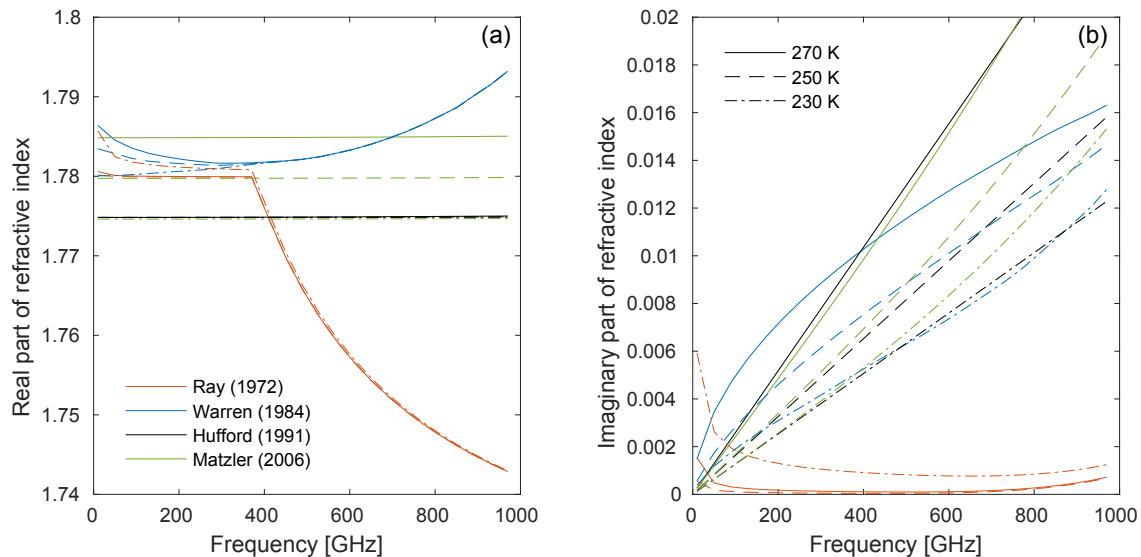


Figure 5. Real (a) and imaginary (b) parts of the refractive index of pure ice, for selected temperatures as a function of frequency, according to Ray (1972), Warren (1984), Hufford (1991), and Matzler (2006).

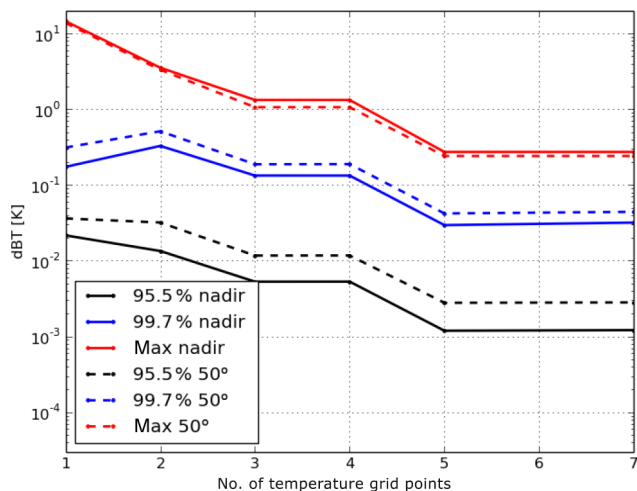


Figure 6. Error statistics of ISMAR observation simulations, given as a function of the temperature grid length used to represent ice hydrometeor scattering properties. The error (dBt) is estimated by comparison to reference calculations. The lines refer to the 95.5 % percentile, the 99.7 % percentile and the maximum value of the errors, for two different observation directions.

ice. The scattering properties of spheroids can be calculated efficiently by the T-matrix method, but for consistency reasons and to avoid possible numerical problems of T-matrix at higher size parameters (Mishchenko and Travis, 1998), also these habits were processed using the Snowflake Toolkit and ADDA.

4.3 Ice aggregate shapes

The ARTS database includes habits developed specifically both for this database and from third-party sources. For calculations at higher frequencies, aggregates are arguably lacking in the current scattering databases and the aim has been to include a relatively diverse set of aggregate habits.

4.3.1 Third-party data

Third-party aggregate data come in two forms, either in the form of shape data ready to be used in the DDA calculations, or as shape descriptions taken from the literature. The 8-column aggregate, originally defined by Yang and Liou (1998) and also represented in Hong et al. (2009), is of the latter case. It is constructed of eight columns of varying sizes. The aspect ratios and relative positions of the columns do not change with mass, and the habit has a $b = 3$. The a -value corresponds to an effective density of 13.5 %.

The Evans snow aggregate (Evans et al., 2012) and Tyynelä snowflake aggregate (Tyynelä, 2011) are both habits where explicit third-party shape data have been used. They both have features in common with the aggregates generated by the Snowflake Toolkit, in that they are generated in a stochastic manner, with multiple particles tracked at the same time. The algorithms used in Tyynelä (2011) and Evans et al. (2012) for generating the aggregates were both inspired by Maruyama and Fujiyoshi (2005), which is the case for the Snowflake Toolkit as well. The dendrites by Evans et al. (2012) were randomly oriented during aggregation events, and they were connected with an overlap of 5 % in volume. The Tyynelä aggregates were generated assuming a quasi-horizontal alignment for the dendrites, more pre-

cisely a Gaussian orientation distribution with a standard deviation of 2° . The publicly available shape data are of too low a resolution for large parts of the database. Higher-resolution data were obtained by correspondence to J. Tyynelä and applied here for these aggregates. The shape data by Tyynelä and Evans have a somewhat poor resolution ($dpl = 15$ at 664 GHz) and corresponding scattering data have likely limited accuracy above roughly 460 GHz.

4.3.2 Database specific

The aggregate simulator of the Snowflake Toolkit (Sect. 3.1.1) was used to create a number of aggregate habits. Throughout, hexagons have been used as constituent crystals. Separate simulations were performed using mean axis ratios of 5 for columns, 1.25 for blocks (short columns), and 1/6 for plates. Furthermore, dimensions of each constituent crystal, length L and side length a (Sect. 2.3) are not set with an exact fixed value, but are each selected randomly from Gamma distributions, done in such a way that the standard deviations become 25 % of the corresponding mean value. Since L and a are selected independently, the aspect ratios are randomly distributed as well, around the specified mean value. Separate simulations were also run for different constituent crystal mean maximum dimensions D_{\max} , for which two values, 100 and 350 μm , were chosen. The motivation for having two constituent crystal sizes is that the simulations could not provide large enough particles when using 100 μm crystals. Hence, habit versions with 350 μm crystals were created as well. In summary, six simulation runs in total were performed, using three aspect ratios and two crystal maximum dimensions. As described in Sect. 3.1.1, a high number of particles are generated in each run, with varying sizes. Accordingly, each run gives sufficient data to produce a full habit set.

The details of this set are summarised in Table 4, and example figures of the particles are shown in Fig. 2. A difference to the Evans aggregate is that no overlap between crystals is allowed: attaching crystals are connected with their faces against each other. Since each simulation generates thousands of particles, a filtering had to be applied. In line with the statement in Sect. 2.4 that habits should follow a single mass-size power law, we fit Eq. (5) to the set of particles of each run and make a somewhat ad hoc selection among the particles that best match the derived a and b to obtain a logarithmically spaced grid in D_{req} .

Furthermore, habits matching snow and hail hydrometeor assumptions in the GEM and ICON models were generated using the RimeCraft function set. The hail habits were initiated with a single cubic “block” and were allowed to grow inside a spherical volume. Together with the a and b of the GEM and ICON hail habits, this resulted in (macroscopically) quasi-spherical particles exhibiting some surface roughness and internal hollows. For the snow habits, some initial structure was needed to create a visual resemblance

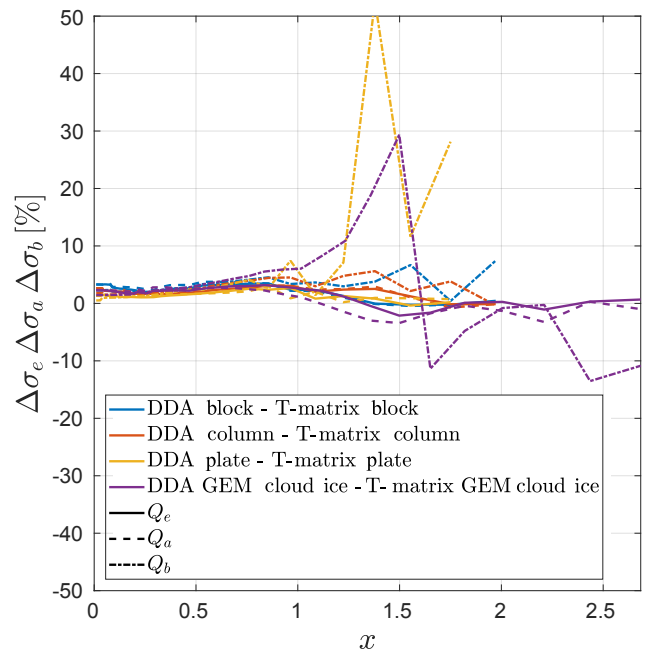


Figure 7. Comparison between the extinction, absorption and backscattering of short columns, block columns and thick plates in the database, and T-matrix results using cylinders having the same length and mass. Shown as a function of size parameter x , with relative difference calculated as $\Delta\sigma = 100 \% \cdot (\sigma - \sigma_{\text{Tmatrix}}) / \sigma_{\text{Tmatrix}}$. Temperature is 230 K and frequency is 94.1 GHz.

of snowflakes. Small 3-D and 2-D crosses with one-block thick arms were used for GEM and ICON habits, respectively. With $b \approx 3$, GEM snow-like hail was allowed to grow in a spherical volume, while for the ICON snow habit with $b \approx 2$ the allowed volume for growth was set to be plate-shaped.

4.4 Rimed particles

Three different habits designed to represent graupel are included in the database. All three can be considered heavily rimed particles, i.e. only composed of rime. The spherical graupel was generated using the Snowflake Toolkit module treating aggregation of spheres. The angle distribution of the incoming spheres was set to be isotropic, resulting in an overall spherical shape of these graupel particles. Furthermore, the constituting spheres have randomly distributed diameters, selected from a gamma distribution with a mean radius of 300 μm and a standard deviation of 75 μm . Furthermore, the habit was designed to have an effective density of approximately 140 kg m^{-3} in order to roughly match observations (Mitchell, 1996).

The ICON and GEM graupel habits were generated in the same general way as the ICON and GEM hail habits, but the settings were tuned to create a granular pattern when examining slices through the resulting graupels. Particles that can be

Table 4. Overview of aggregates produced using the Snowflake Toolkit. The columns axial ratio and D_{\max} refer to mean values of constituting crystals, while the last two columns refer to complete aggregates.

Habit name	Id	Axial ratio $L/(2a)$	Crystal D_{\max} (μm)	a	b
Small column aggregate	17	5	100	0.14	2.45
Large column aggregate	18	5	350	0.25	2.43
Small block aggregate	21	1.25	100	0.21	2.33
Large block aggregate	22	1.25	350	0.35	2.27
Small plate aggregate	19	1/6	100	0.077	2.25
Large plate aggregate	20	1/6	350	0.21	2.26

classified as lightly or moderately rimed can be generated by RimeCraft, and are intended to be included in a next database version.

4.5 Raindrops and liquid cloud drops

The liquid phase is so far limited to spherical drops, with scattering properties calculated by Mie theory (Sect. 3.2.2). The number of sizes was set to 200, and, as mentioned, data are provided for five temperatures between 230 and 310 K. Spherical drops should be an acceptable approximation for liquid cloud and drizzle particles, but not for larger raindrops, and liquid drops of non-spherical shape will be part of the next database version.

5 Results

This section presents example characteristics and results of the database. The ambition is to give a basic overview of the database. Exploration of all details of the scattering data provided is left for other publications and the users of the database.

5.1 Comparisons

A number of comparisons have been made in order to obtain a rough assessment of the accuracy of the data. At an early stage, dedicated tests were made to ensure that there is an acceptable agreement between our usage of ADDA and equivalent results obtained by the T-matrix implementation of Mishchenko and Travis (1998). Some deviations were unavoidable as T-matrix is a fully analytic method, while DDA is numerical and operates with discretised shape data. This is of special concern for particles where the properties vary quickly as a function of size (due to “Mie resonance features”). However, this should not be critical as these details are largely removed when averaging over size to obtain bulk properties.

Further, Fig. 7 compares the extinction of some hexagonally shaped particles with T-matrix calculations for cylinders. The T-matrix cylinders were given the same length or height and the same cross-sectional area; i.e. volume

(and hence also mass) is maintained. The ADDA results for backscattering mainly agree with the T-matrix, but also show indications of some instability. A closer examination of the poorer cases revealed that high deviation in backscattering is associated with low number of orientations used by ADDA, indicating that its iteration criterion is not optimal with respect to this quantity. That is, the Romberg scheme has stopped prematurely with respect to backscattering. On the other hand, an acceptable accuracy appears to have been reached for extinction. As expected, the extinction deviates between ADDA and T-matrix, but not strongly: the difference is throughout below 4 %. These results give additional indications on the accuracy of the database, but also indicate that the microwave extinction of ice particles primarily follows overall particle properties, such as mass and maximum size, while surface features, such as roughness, have a relatively low impact. That is, if plates and columns are treated to be hexagonal or cylindric has only a marginal impact on microwave optical properties.

For habits, where external shape definitions have been used, comparison with their source databases (Liu, 2008; Hong et al., 2009) is possible. However, these comparisons involve interpolation in temperature, frequency and size, and again a perfect agreement can not be expected. In order to minimise the impact of these interpolations, close matches in frequency and temperature between the databases have been selected. Discrepancies will also depend on differences in DDA convergence criteria selected as well as on the exact sampling methodology used when discretising the particle shapes. Of concern is also that Hong et al. (2009) set dipole sizes following our Eq. (8), while Liu (2008) used a stricter criterion resulting in a factor of 2 smaller dipole size. Both performed DDA calculations for a set of specific particle orientations and based the orientation averaging on these data, but the number of orientation angles differ. Tests to estimate the impact of these later factors are reported by both Liu (2008) and Hong et al. (2009).

As we do not have access to the discretised shape data used in other databases, it is not possible to assess applied particle shapes on that level, but reported masses can be compared. The masses obtained by us show insignificant deviations to

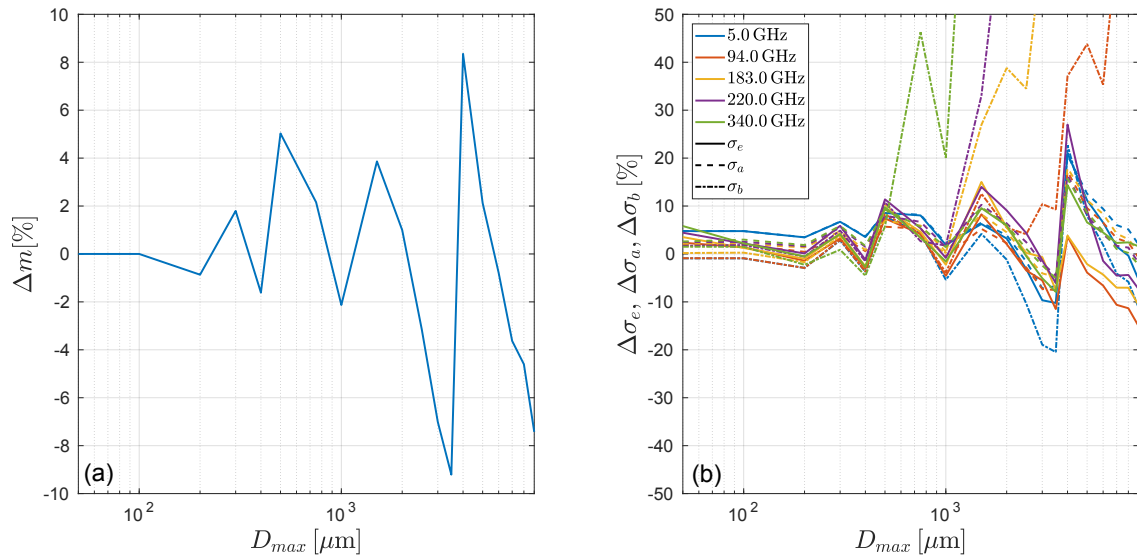


Figure 8. Comparison of sector snowflake data from Liu (2008) and this paper. (a) Relative differences in mass. (b) Relative differences in extinction (solid lines), absorption (dashed lines) and backscattering (σ_b ; dot-dashed) cross sections. Shown as functions of D_{max} and using the data from Liu (2008) as a reference. Differences are reported as $\Delta m = 100 \% \cdot (m - m_{\text{Liu}}) / m_{\text{Liu}}$, etc. The comparison was made for one temperature (233.15 K) and sizes covered by Liu (2008).

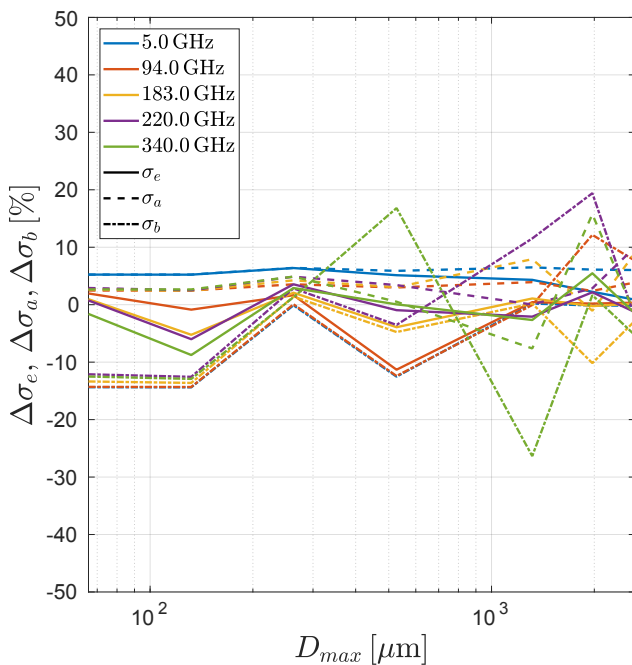


Figure 9. Comparison with block column data of Liu (2008). Otherwise as the right panel of Fig. 8.

the corresponding values reported by Liu (2008) and Hong et al. (2009), with the exception of the sector snowflakes. For this habit, discrepancies in mass of up to 9 % are found (Fig. 8). A simple discretisation of the particle shape normally results in a change in the particle mass. Our strategy

has been to apply a rescaling of the discrete data to ensure that the final data correspond to the target mass. Already, Geer and Baordo (2014) noted that the sector snowflake habit in Liu (2008) shows a non-smooth variation in mass, and it seems that no similar rescaling was applied by Liu (2008). The discretisation is a particularly critical issue for the sector snowflake habit, as these particles have the highest aspect ratios and can be only a few dipoles thick. Just the decision to place dipole centres at $\dots, -l, 0, l, \dots$ or $\dots, -\frac{l}{2}, \frac{l}{2}, \dots$ (where l is the dipole size) has here a significant impact, both for the effective mass after discretisation and the final optical properties.

The differences in the mass of sector snowflakes give a direct imprint in the extinction reported for this habit by the two databases (Fig. 8), but it is also noticeable that the difference in extinction is for some sizes considerably larger than the mass difference. However, the most striking feature is the high deviation in backscattering. Again, the sector snowflake stands out, and, as a much more representative example, a comparison for the block column habit is shown in Fig. 9. The agreement is better for the block columns in overall terms, but the backscattering still frequently deviates by 10 % or more.

A comparison with data of Hong et al. (2009) is found in Fig. 10. Clear systematic differences originating from the different refractive index models applied can be recognised. The scattering data of Hong et al. (2009) are based on the refractive index of Warren (1984). This parameterisation deviates significantly from more recent ones (Sect. 4.1), particularly regarding the imaginary part. The deviations in the refractive index are such that the data of Hong et al. (2009) exhibit

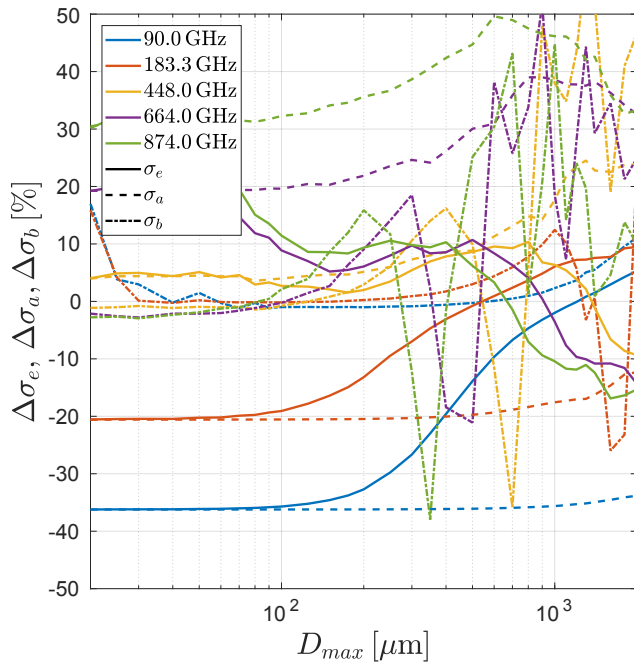


Figure 10. Comparison to Hong et al. (2009) of 8-column aggregate data: relative differences in extinction (solid lines), absorption (dashed lines) and backscattering (dot-dashed). Differences are reported as $\Delta\sigma = 100\% \cdot (\sigma - \sigma_{\text{Hong}}) / \sigma_{\text{Hong}}$. The comparison was made for one temperature (243.15 K) and sizes covered by Hong et al. (2009).

a higher/lower absorption below/above about 400 GHz. The difference in the real part of the refractive index is much less pronounced and there is a fairly good agreement on the extinction due to scattering. The same is true for the backscattering at 90 GHz, while the backscattering at, for example, 664 GHz deviates significantly for millimetre-sized particles. Putting aside deviations that should be caused by the older refractive index data used by Hong et al. (2009), the remaining data indicate a good underlying agreement between the two sets of DDA calculations.

The difference in refractive index with respect to Hong et al. (2009) is relatively small at 448 GHz. With this in mind, the combined interpretation of Figs. 7, 9 and 10 is that the calculation of extinction disagrees by 10 % at most, but is generally inside 5 %. Larger differences are found for backscattering, particularly at higher frequencies. If only the radar frequencies of today (i.e. < 100 GHz) are considered, then the general agreement for backscattering is also of the order of 10 %, with a strong exception in the sector snowflake habit and some data points with early stop of the Romberg scheme.

The results found for backscattering give a direct indication on the accuracy of the phase matrix for the direct backward direction. This is likely the direction with the highest calculation errors. However, the finer details of the phase matrix should not be critical for passive measurements as the ra-

diation field is relatively smooth (except around the limb direction), and the overall accuracy of the phase matrix should be similar to the one of the extinction. To study the effective accuracy of the phase matrix data provided would require full radiative transfer simulations, which are beyond the scope of this article.

5.2 Effective density

Figure 11 displays effective densities for a selection of habits. The effective density is defined as

$$\rho_e = \frac{6m}{\pi D_{\text{max}}^3}, \quad (17)$$

i.e. the mass divided by the volume of the minimum circumsphere. It is linked to the a and b coefficients of a habit as

$$\rho_e = \frac{6aD_{\text{max}}^{b-3}}{\pi}, \quad (18)$$

where the m has been replaced by Eq. (5). Accordingly, the data in Fig. 11 should ideally end up along straight lines. This is also the case for habits having an analytic description of the shape, while deviations are observed for habits having stochastically generated shape data.

The effective density is governed by two main factors, the particle's “fluffiness” and aspect ratio. Habits having throughout a high ρ_e are generally dense particles with a spherical appearance. Particles with low values either have a high aspect ratio (such as the sector snowflake) or are very porous. Habits with $b < 3$ have negative slopes in Fig. 11 and tend to grow differently in the spatial dimensions, e.g. the plate type 1 habit has an increasing aspect ratio with size. However, $b < 3$ can also correspond to particles that increase in fluffiness with increasing distance to the particles' centre, e.g. the GEM snow habit.

The legend of Fig. 11 is divided into groups of habits, with single crystals having solid lines, aggregate and snow particles dashed lines, and dense graupel or hail-type particles dot-dashed lines. The ice sphere habit serves as an upper bound, while the long column, the flat 3-bullet rosette and the sector snowflake exhibit the lowest density, depending on the D_{max} range. More generally, the graupel and hail habits occupy the upper part of the plot, being the densest habit group. The aggregates and crystals tend to share the same area in the middle to lower parts of the graph. It will be seen later on that the effective density has a noticeable impact on the observed optical properties.

5.3 Extinction and backscattering

Example data of extinction and backscattering efficiencies are displayed in Fig. 12 for some selected frequencies and habits. The habits and legends are the same as in Fig. 11, i.e. single crystals have solid lines, aggregate or snow particles dashed lines, and dense graupel or hail-type particles

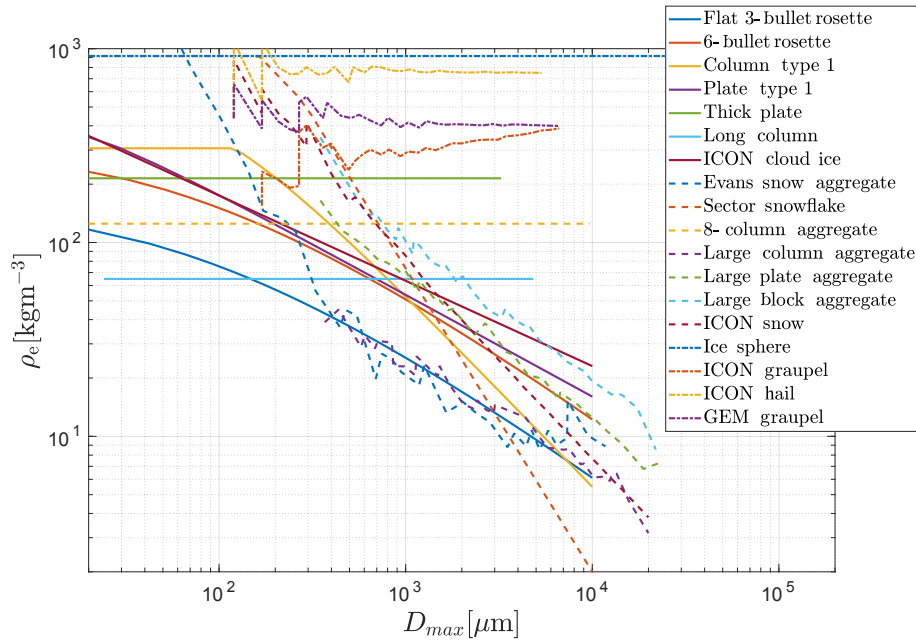


Figure 11. Effective densities ρ_e of a selection of habits as a function D_{\max} .

dot-dashed lines. The extinction and backscattering efficiencies are calculated as

$$Q = \frac{4\sigma}{\pi D_{\text{veq}}^2}, \quad (19)$$

where σ is the given cross section. That is, both x and Q are defined with respect to D_{veq} . A related remark is that efficiencies are thus compared in Fig. 12 between particles with the same mass (as a given x implies a specific mass).

A few characteristics can be observed in Fig. 12. Firstly, the groups tend to cluster. For example, the aggregate habits tend to have low extinction at 175 GHz and high extinction at 670 GHz. An opposite tendency can be observed for the dense particles given dot-dashed lines, which have relatively high and low extinction at 175 and 670 GHz, respectively. The crystal habits (solid lines) have efficiencies similar to heavy/dense particles at 175 GHz, but varying, intermediate, extinction values at 670 GHz. Similar observations can be made for backscattering; dense particles tend to have high backscattering, and aggregates low backscattering. Interestingly, the features observed for effective density in Fig. 11 are to a large degree transferred to the scattering properties in Fig. 12, but exceptions are also noted. For example, the spheres and ICON hail have comparatively low extinction at $x > 3$ at 175 GHz, and several crystal habits have higher backscattering at 94.1 GHz than the dense particles. Overall, the effective density can be considered an important parameter, but other aspects, such as exact particle shape, can exert influence as well. This discussion refers to how extinction and backscattering are related to particle mass. Other rela-

tionships can be found if the comparison is made with respect to D_{\max} .

5.4 Triple-frequency signatures

A common manner to evaluate scattering properties in the radar community is the triple-frequency signature (Kneifel et al., 2011). This is a multi-frequency bulk backscattering analysis involving three frequencies with data reported as two dual-wavelength ratios (DWR). The approach involves the effective reflectivity factor Z_e :

$$Z_e = 10^{18} \frac{\lambda^4}{\pi^5 \cdot |K|^2} \int_0^\infty \sigma_b(D_{\max}) N(D_{\max}) dD_{\max}, \quad (20)$$

where $\sigma_b(D_{\max})$ is the backscattering cross section, $N(D_{\max})$ the number of particles of size D_{\max} , and K is calculated as $K = (m^2 - 1)/(m^2 + 1)$, with m being the complex refractive index of liquid water. The DWR for two wavelengths λ is then obtained as

$$\text{DWR}_{\lambda_1, \lambda_2} = 10 \cdot \log \left(\frac{Z_e(\lambda_1)}{Z_e(\lambda_2)} \right). \quad (21)$$

Example triple-frequency results are shown in Fig. 13, using three standard radar frequency bands. Refractive index of water (m) was taken from Ellison (2007), assuming a reference temperature of 270 K. Further, an exponential PSD, defined over D_{\max} ,

$$\frac{dN}{dD_{\max}} = N_0 \exp^{-\Delta D_{\max}}, \quad (22)$$

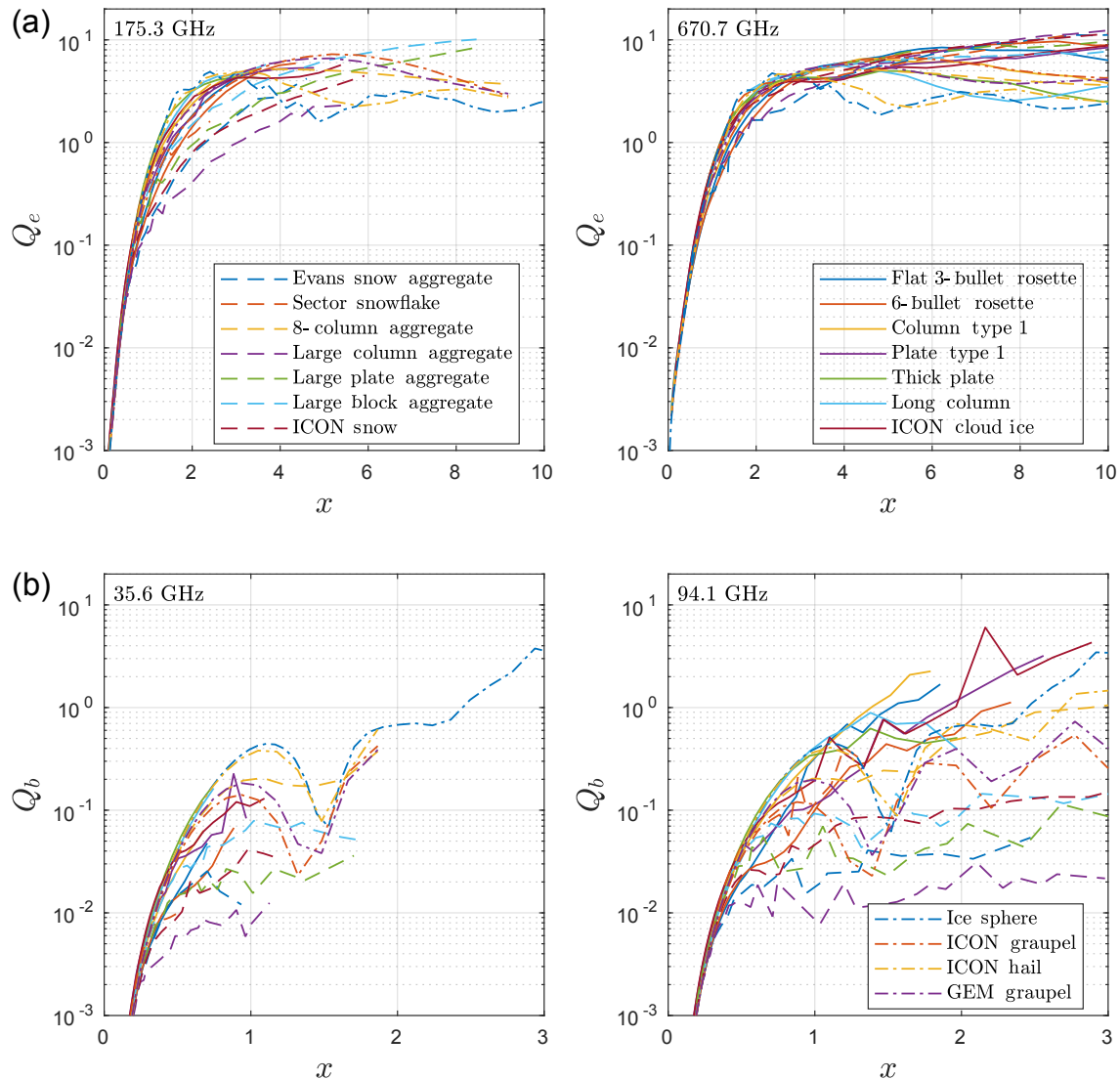


Figure 12. Example extinction (a) and backscattering (b) efficiencies (Eq. 19) as a function of the size parameter (Eq. 4). Legends are valid across all panels.

was selected. This PSD is identical to the one applied by Kneifel et al. (2011) and Kulie et al. (2014). N_0 is set to a constant value of 1, which is of no consequence since this constant is cancelled out in Eq. (21). In order to not let truncation issues influence strongly, Δ was varied for each habit separately, in such a way that the mean size of the PSD ranges from 1.5 times the smallest available D_{\max} to 1/3 times the largest available D_{\max} .

Effective reflectivity is defined in such a way that if all particles scatter according to Rayleigh theory, Z_e is independent of frequency. This has the consequence that most high slope parameters (Δ), which correspond to low ice water contents, give rise to zero or low DWR. The other end of each triple-frequency curve corresponds to the highest Δ that could be accommodated with the size range available for the habit.

The triple-frequency signatures have been shown to act as an indication of effective density, frequently linked to the degree of riming (Kneifel et al., 2015; Yin et al., 2017). Figure 13 shows that the backscattering of the database habits matches the general expectations. First of all, the data span the same general ranges of DWR as reported by Kneifel et al. (2011) and Kulie et al. (2014). Further, the single crystal habits (solid lines), which are of comparatively low effective density (see Fig. 11), tend to occupy the left part of the graph. On the other hand, the dense graupel and hail habits (dot-dashed lines) are found in the rightmost part of the graph. The aggregate-type habits generally occupy the space in between the crystals and denser habits.

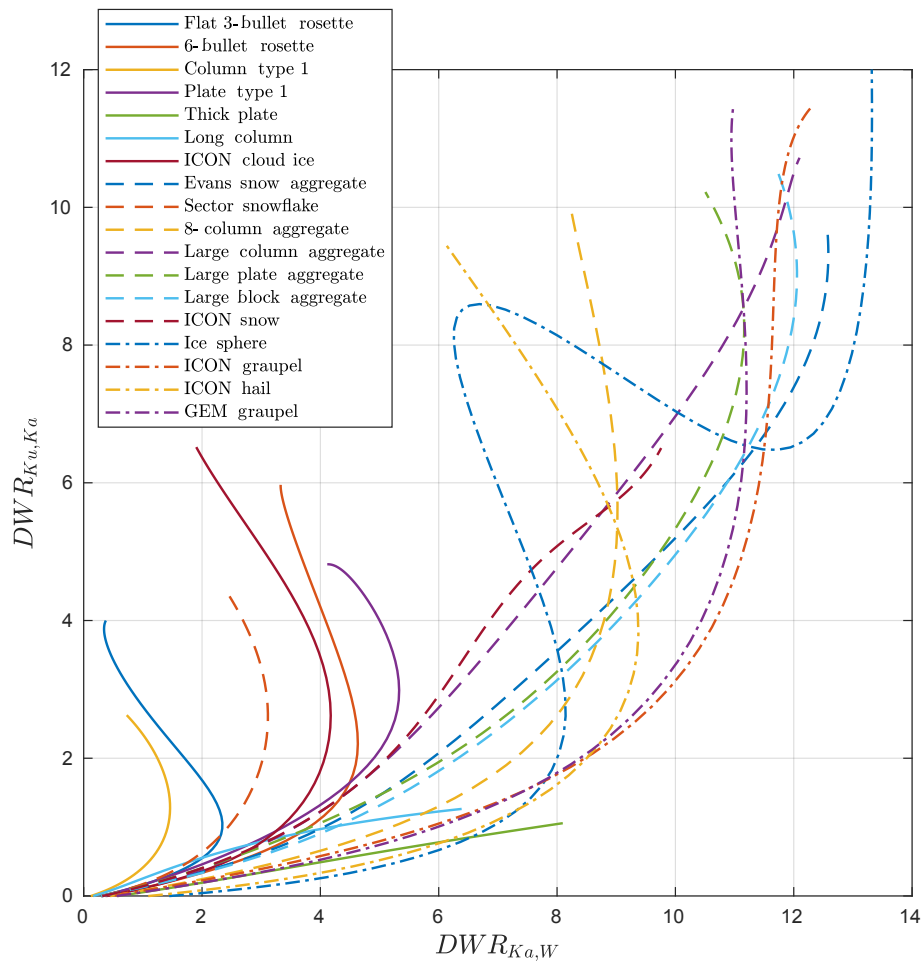


Figure 13. Triple-frequency signatures of selected habits, assuming an exponential particle size distribution (Eq. 22) and radar frequencies of 13.4 (K_u band), 35.6 (K_a band) and 94.1 (W band) GHz. The x-axis displays DWR between K_a and W bands and the y-axis shows DWR between K_u and K_a bands.

6 Database: format and access

This section outlines database format and accessibility, while the detailed documentation is provided with the database itself.

6.1 Format

The database is structured in a folder hierarchy, following the habit classification displayed in Table 2. At the bottom of the folder structure, there is one folder for each habit. These folders contain auto-generated pdf documents and text files that summarise the scattering data as well as a “habit logo” figure (Figs. 1 and 2). The actual data are also found in these folders, with one netCDF4 file for each particle size of the habit. Inside each netCDF4 file, there is an internal folder structure to organise the data according to frequency and temperature. These folders contain the scattering data, as well as particle shape and processing information. The stored variables

and their attributes are summarised in Table 5. The variable names should hopefully all be self-explanatory, but for clarity they are accompanied by a description tag.

The `SingleScatteringData` group contains not only the core scattering properties (\mathbf{Z} , \mathbf{K} , and \mathbf{a}), but also information on frequency, temperature, and angular grids. The `ShapeData` group provides information on the particle behind the scattering properties, such as mass, D_{\max} , D_{veq} , aspect ratio, aerodynamic area equivalent diameter, and refractive index. The `CalculationData` group contains ADDA settings and log data (DDA residual error used, date of completion, etc.). In particular, an identifier of the used shape file is given, and these files are part of the database. Thus, each scattering calculation is fully reproducible.

For orientation-averaged scattering properties, the optical properties exhibit features that can be used to reduce the overall data volume. For example, the scattering matrix has only six unique, non-zero, elements: Z_{11} , Z_{12} , Z_{22} , Z_{33} , Z_{34} and Z_{44} . The extinction matrix has only one such

Table 5. Summary of the core data format.

Attributes:	date, version
Groups:	
SingleScatteringData:	
Attributes:	orient_type
Dimensions:	aa_scatter, za_scatter, aa_inc, za_inc, scatMat_row, scatMat_col, phaMatElem, extMatElem, absVecElem
Variables:	frequency, temperature, aa_scatter, za_scatter, aa_inc, za_inc, phaMat_index, extMat_index, absVec_index, phaMat_data, extMat_data, absVec_data
ShapeData:	
Attributes:	description, source, refrIndex_model, habit_file_id, habit_id, phase, refrIndex_homogenous_bool, density_homogenous_bool
Variables:	diameter_max, diameter_vol_eq, aspect_ratio, diameter_area_eq_aerodynamical, mass, dpl, N_dipoles, refrIndex_real, refrIndex_imag, alpha, beta, gamma
CalculationData:	
Attributes:	method, software, software_version, system, n_nodes, n_cores, date_completion, ADDA_eps, ADDA_avgParam_file, ADDA_scatParam_file

element, K_{11} . Similarly, only one element of the absorption vector, a_{11} , is non-zero. Only these unique elements are stored, together with information on how full matrices and vectors will be populated. For example, the scattering matrix is stored in the database as a tensor (phaMat_data) with dimensions (aa_scatter, za_scatter, aa_inc, za_inc and phaMatElem), where phaMatElem corresponds to the six stored values (Z_{11}, Z_{12}, \dots). Information on how to reconstruct the full matrix is provided separately, in phaMat_index that contains the position matrix

$$\begin{pmatrix} 1 & 2 & 0 & 0 \\ 2 & 3 & 0 & 0 \\ 0 & 0 & 4 & 5 \\ 0 & 0 & -5 & 6 \end{pmatrix}. \quad (23)$$

The numbers correspond to the indices of phaMatElem in phaMat_data, i.e. where to place those values in the matrix. The indexing is 1-based, where zero flags mean that the matrix is zero at that position. A negative number means the database value will be multiplied by -1 before it is inserted into the matrix. Corresponding systems are used for the extinction matrix and the absorption vector.

6.2 Interface and standard habits

The scattering data described above can easily be extracted using any netCDF or HDF5 interface. However, for enhancing the user friendliness, two data interfaces are distributed with the database. The interfaces are implemented in MATLAB and Python. The aim has been to keep the function-

ality as similar as possible between the two interfaces (but details of the programming languages used make some differences unavoidable). The MATLAB interface should function with any relatively new MATLAB version. The Python interface should function with both Python 2 and Python 3, but Python 3 (≥ 3.5) is recommended for full functionality. There are no extensive requirements on the interfaces. The Python interface requires the netCDF4, numpy and os packages, and the MATLAB interface the netcdf package.

The functionalities provided by the two interfaces are exploration of the database content, extraction of selected parts of the data (with respect to habit, size, frequencies and temperature), interpolation of data in temperature, frequency, size and angles, preparation of habit mixes and calculation of bulk properties.

The interfaces also provide support for converting data to the format used by the ARTS (Eriksson et al., 2011a) and RTTOV-SCATT (Bauer et al., 2006) forward models. Both interfaces can deal with the ARTS scattering format, on the condition that the Atmlab (MATLAB) and Typhon (Python) packages⁴ are installed. Only the Python interface supports RTTOV, i.e. conversion of the database scattering properties to data tables that can be digested by RTTOV-SCATT's Mie coefficient module. (This requires an update of the Mie coefficient module developed along with the ARTS database. This will be part of future RTTOV releases, but is also available as a patch file provided with the database.)

⁴Both available at <http://www.radiativetransfer.org/tools/> (last access: 11 July 2018).

To allow a quick introduction to the database, a set of “standard habits” has been generated and provided in both the ARTS and RTTOV-SCATT formats. These habits should cover a range of conditions, such as cloud ice, snow, graupel, and hail. Most of these habits are a direct compilation of the database content, but some can be denoted as habit mixes. These combinations were created to simplify the usage of some of the aggregate and rimed habits that do not give full coverage in size. In order to also cover the lower size range, those habits were complemented with data from some crystal habit. Further details about the standard habits are provided in the accompanying ReadMe file.

7 Data availability

The database and its interfaces are publicly available at Zenodo, a free-of-charge research data repository hosted by CERN. The interfaces and the database itself are available under different uploads due to different licensing, with separate DOIs. The database DOI is <https://doi.org/10.5281/zenodo.1175572> (Ekelund et al., 2018b) and the interfaces’ DOI is <https://doi.org/10.5281/zenodo.1175588> (Mendrok et al., 2018). This article refers to the data stored at Zenodo. As the database will be extended gradually, there is also a “development version” where the new data will be added until a new official version is released. This version is located on an ftp server hosted by Hamburg University, accessible through the ARTS homepage (<http://www.radiativetransfer.org/tools/>, last access: 11 July 2018). The database itself is provided under the CC BY-SA licence (<https://creativecommons.org/licenses/by-sa/4.0/>, last access: 11 July 2018), allowing the user to share and adapt the material, under the conditions that appropriate credit is given and indication of any changes made is given. Also, distribution of any modified or built-upon content must be done under the same licence. All source code falls under the GPL (<http://www.gnu.org/licenses/gpl-3.0.en.html>, last access: 11 July 2018) (General Public License).

8 Conclusions

The first version of a general, and fully publicly available, database of hydrometeor optical properties is presented. The database covers frequencies of 1 to 886 GHz, i.e. the full microwave region is targeted. This initial version is restricted to totally random particle orientation and focuses on particles consisting solely of ice. A variety of particle shapes, organised into “habits”, are provided, in order to allow representation of cloud ice, snow, graupel and hail in radiative transfer simulations. In total, 34 ice hydrometeor habits are provided, and, as a complement, data for liquid spheres are included. Considered temperatures are 190, 230, and 270 K for ice, and 230, 250, 270, 290, and 310 K for liquid water. The data fully

support polarimetric applications of both passive and active type.

The “ARTS database” presented here is the most extensive one at hand for totally random orientation. All except one of the existing databases (Lu et al., 2016) are also restricted to this particle orientation case. Only some main remarks are given here; for a review, see Sect. 1 and Ekelund et al. (2017). Only Ding et al. (2017) offer the same wide frequency coverage. In comparison to those data, the ARTS database includes a considerably higher number of habits (34 vs. 12) and a somewhat higher coverage in particle size. As all the aggregate habits in Ding et al. (2017), as well as in Hong et al. (2009), have $b = 3$ (see Eq. 5), it can be claimed that the ARTS database provides the first publicly available realistic representation of snow aggregates at microwave frequencies above 200 GHz. For lower frequencies, a broader coverage of snow is provided by the database of Kuo et al. (2016).

The aggregates of Ding et al. (2017) can potentially work as a proxy for hail and heavily rimed particles. The ARTS database contains a more diverse set of particle shapes for these classes, but also covers the 8-column aggregate part of both Hong et al. (2009) and Ding et al. (2017). A large part of the effort behind the database is the development of tools to generate realisations of these particle types. Regarding column and plate ice crystals, it was noted that such habits in Liu (2008) all have $b = 3$, and for these particle categories the data provided with the variation of aspect ratio taken from Hong et al. (2009) should be more realistic. The “update” of the data of Hong et al. (2009) using a better parameterisation of the refractive index resulted in changes of up to 50 % (Fig. 10), as well as a broader coverage in frequency, temperature and sizes.

All optical properties, except some reference data for spheres calculated by Mie code, were derived by discrete dipole approximation (DDA) handling arbitrarily shaped particles. Considering the high calculation burden of DDA (particularly at higher size parameters), it was not possible to both provide extremely accurate data and a broad database. It was decided at this stage to aim for a moderate accuracy, in order to first get a relatively broad overview. The basic idea is to explore the general properties of the data generated (manuscript in preparation), in order to better understand which particle shape properties govern the optical properties. It is not feasible, or desirable, to have data for every possible particle shape, but at this moment it is not clear to what extent for example micromorphological aspects like the shape and size of the crystals inside an aggregate need to be considered.

Comparisons to T-matrix, Liu (2008) and Hong et al. (2009) indicate that accuracy of the data is in general within 10 % (Sect. 5.1). This potential inaccuracy must not be ignored, but should today be relatively small compared to all other uncertainties involved in full simulations and retrievals. For example, Baran et al. (2017) reasoned in the same way and were also content with a 10 % accuracy. However, much

higher discrepancies were found occasionally, particularly regarding backscattering. Further tests will be performed to better characterise the accuracy of the optical properties provided by the database, and, if found necessary, data will be recalculated with more demanding settings to provide more accurate backscattering.

The calculation burden of DDA also resulted in a cutoff around size parameter (x) 10 being introduced, but it is argued that this in general has an insignificant or low impact on bulk properties (Sect. 2.5). In other works, the need for calculations to much higher x is discussed, but it is here essential to notice how x is defined. We calculate x based on volume equivalent diameter (D_{veq}), while, for example, in Baran et al. (2017) it is defined with respect to maximum diameter (D_{max}), resulting in a higher x for a given particle (except for spheres).

Besides accuracy improvements, the next version of the database is planned to also incorporate data for melting and moderately rimed particles. A more major addition will be to include data for oriented particles. Such data are today very sparse and limited to a few frequencies below 200 GHz (e.g. Tyynelä and Chandrasekar, 2014). Initial calculations for “azimuthally random orientation” have been performed, with the conclusion that these calculations are much more demanding than the totally random case, with respect to both calculation burden and final data storage. Thus, practical hurdles must be overcome, and it is essential to carefully analyse the data at hand to guide the future calculations towards the most representative habits, as well as determining how many frequencies, temperatures and sizes the database must cover to be of practical use.

Author contributions. PE initiated the database, has acted as project leader, coded RimeCraft and the MATLAB interface, and written the article’s text. RE has produced all data, designed the database structure and written the article’s text. JM developed the RTTOV and Python interfaces, provided feedback on data and methods, and contributed parts of the article’s text. MB, OL and SAB participated in planning of the database, have contributed to data and text, and started the production of the data for oriented particles that will be a main addition of the next database version.

Competing interests. The authors declare that they have no conflict of interest.

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