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Logarithmic Perturbation Models in the Weak-Dispersion Regime with Applications to Passive Optical Networks

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Abstract *Three novel analytical models derived using logarithmic perturbation are presented. The best proposed model achieves a gain of 1.5 dB when comparing its normalised square deviation with other models in a passive optical network.*

Introduction

Perturbation models have been proposed in the literature to approximate the optical fibre propagation, which is governed by the nonlinear Schrödinger equation (NLSE)^{[1],[2]}. The NLSE can be described by attenuation, chromatic dispersion and the Kerr effect^[3]. The Kerr effect is characterised by a nonlinear coefficient, while the chromatic dispersion by the group-velocity dispersion (GVD) parameter. Perturbative models based on the nonlinear coefficient have been widely used in the literature to predict system performance^{[4],[5]} or design low-complexity receivers^[6], for example. Recently, we proposed a perturbative model on the GVD parameter^{[7],[8]}.

The most studied perturbative methods in optical fibre communications are the regular perturbation (RP) and the logarithmic perturbation (LP)^{[1],[9]}. RP has been presented in the literature for the nonlinear coefficient γ ^[2] and the GVD parameter β_2 ^[7], while LP has only been performed for γ ^{[1],[10]}. Therefore, in this paper, we present for the first time the LP on β_2 model. The performance of this model, however, can be improved by performing LP in the frequency domain, which is a new approach that we call frequency logarithmic perturbation (FLP). FLP should not be confused with the frequency resolved logarithmic perturbation (FRLP) proposed in^{[11],[12]}. FRLP still applies the LP method in the time domain, whereas FLP applies this method in the frequency domain. To the best of our knowledge, this is the first time that FLP models are presented in the literature.

In total, six models arise from the mentioned perturbations. Three of them were already known in the literature: RP on γ , RP on β_2 , and LP on γ . In this paper, we present three new other models: LP on β_2 , FLP on γ , and FLP on β_2 . We

compare these six models in terms of normalised square deviation (NSD) in a passive optical network (PON). This system presents low accumulated dispersion due to its short distance, which makes it more suitable for perturbations on the GVD parameter. In addition, the system can operate in the highly nonlinear regime due to high input powers. The results show that FLP on β_2 yields the best performance in the highly nonlinear regime.

Channel Model and Performance Metric

The normalised NLSE for noiseless propagation of an optical field E for a retarded time frame t and distance z is^[2]

$$\partial_z A(t, z) = - (j\beta_2/2)\partial_{tt} A(t, z) + j\gamma e^{-\alpha z} |A(t, z)|^2 A(t, z), \quad (1)$$

where α is the attenuation coefficient. The first term on the right-hand side of (1) represents the chromatic dispersion and the last term represents the Kerr nonlinearity.

A numerically very accurate solution of (1) is obtained by the SSFM and denoted by A . We denote the output of a model M by A_M and compare it with A in the time domain. The metric used for this comparison is the NSD, defined as^[2]

$$\text{NSD} \triangleq \frac{\int_{-\infty}^{\infty} |A_M(t, z) - A(t, z)|^2 dt}{\int_{-\infty}^{\infty} |A(t, z)|^2 dt}. \quad (2)$$

The NSD integrates the absolute error squared over the entire propagated time, and normalises it with the power of the signal A . The lower the NSD, the more accurate is the analytical model.

Regular Perturbation

The RP method consists of representing a signal by a power series of a certain coefficient. For the

first order RP on γ , this series is truncated after the first two terms. The resulting first order RP on γ model is then given by

$$A(t, z) \approx A_{\text{RP}}^{(\gamma)}(t, z) = A_0^{(\gamma)}(t, z) + \gamma A_1^{(\gamma)}(t, z), \quad (3)$$

where $A_0^{(\gamma)}$ and $A_1^{(\gamma)}$ represent the zeroth and first order RP on γ terms^{[1],[2]}. Analogously, the first order RP on β_2 is obtained by truncating the power series of the linear coefficient β_2 after the first two terms. The first order RP on β_2 is written as

$$A(t, z) \approx A_{\text{RP}}^{(\beta_2)}(t, z) = A_0^{(\beta_2)}(t, z) + \beta_2 A_1^{(\beta_2)}(t, z), \quad (4)$$

where $A_0^{(\beta_2)}$ and $A_1^{(\beta_2)}$ represent the zeroth and first order RP on β_2 terms^[7].

Logarithmic Perturbation

LP is a mathematical technique similar to RP. LP on γ was first presented in^{[1],[10]} and can be shown to have a higher convergence ratio than RP on γ . LP functions can be obtained directly by the RP functions $A_k^{(\gamma)}$ or $A_k^{(\beta_2)}$. Following an approach similar to^[1], the first order LP on γ is written as

$$A_{\text{LP}}^{(\gamma)}(t, z) = A_0^{(\gamma)}(t, z) \exp \left(\gamma \frac{A_1^{(\gamma)}(t, z)}{A_0^{(\gamma)}(t, z)} \right), \quad (5)$$

where the terms $A_0^{(\gamma)}$ and $A_1^{(\gamma)}$ are the RP terms in (3). Since the LP only depends on the RP terms, LP on β_2 can also be derived following the steps in^[1], resulting in

$$A_{\text{LP}}^{(\beta_2)}(t, z) = A_0^{(\beta_2)}(t, z) \exp \left(\beta_2 \frac{A_1^{(\beta_2)}(t, z)}{A_0^{(\beta_2)}(t, z)} \right), \quad (6)$$

where $A_0^{(\beta_2)}$ and $A_1^{(\beta_2)}$ are the RP terms in (4).

Frequency Logarithmic Perturbation

The linearity of (3) and (4) with respect to the functions $A_k^{(\gamma)}$ and $A_k^{(\beta_2)}$, respectively, suggests another approach to obtain a different LP solution. The new approach consists on performing the same steps on the LP derivation presented in^[1] in the frequency domain, which we refer to as FLP. By using this approach, we can obtain two new models not yet presented in the literature, namely FLP on γ and FLP on β_2 . The first order FLP on γ is given by

$$\tilde{A}_{\text{FLP}}^{(\gamma)}(\omega, z) = \tilde{A}_0^{(\gamma)}(\omega, z) \exp \left(\gamma \frac{\tilde{A}_1^{(\gamma)}(\omega, z)}{\tilde{A}_0^{(\gamma)}(\omega, z)} \right), \quad (7)$$

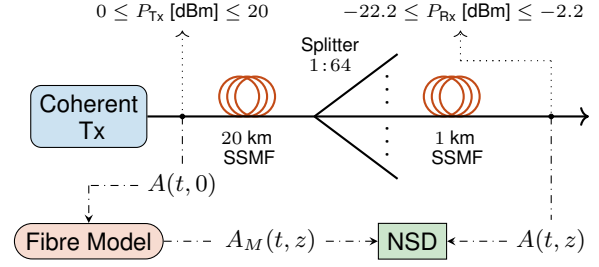


Fig. 1: System setup based on PONs. Due to the short transmission distance, the system has low accumulated dispersion. The range of input powers allow the system to operate in a highly nonlinear regime.

where $\tilde{A}_0^{(\gamma)}$ and $\tilde{A}_1^{(\gamma)}$ are the Fourier transforms of $A_0^{(\gamma)}$ and $A_1^{(\gamma)}$ in (3), respectively. The first order FLP on β_2 is given by

$$\tilde{A}_{\text{FLP}}^{(\beta_2)}(\omega, z) = \tilde{A}_0^{(\beta_2)}(\omega, z) \exp \left(\beta_2 \frac{\tilde{A}_1^{(\beta_2)}(\omega, z)}{\tilde{A}_0^{(\beta_2)}(\omega, z)} \right), \quad (8)$$

where $\tilde{A}_0^{(\beta_2)}$ and $\tilde{A}_1^{(\beta_2)}$ are the Fourier transforms of $A_0^{(\beta_2)}$ and $A_1^{(\beta_2)}$ in (4), respectively.

Numerical Results

Fig. 1 shows the PON system setup under consideration. As depicted in the figure, we consider a standard single mode fibre (SSMF) of 20 km, followed by a splitter of ratio 1:64 and a final fibre segment of 1 km. With this split ratio, the power budget is 22.2 dB. The fibre input power P_{Tx} varies from 0 to 20 dBm, which leads to a received power P_{Rx} between -22.2 and -2.2 dBm. The range of powers was chosen to cover launch powers for PON systems according to^{[13],[14]}. The SSMF has $\alpha = 0.2 \text{ dB} \cdot \text{km}^{-1}$, $\beta_2 = -21.67 \text{ ps}^2 \cdot \text{km}^{-1}$, $\gamma = 1.2 \text{ W}^{-1} \cdot \text{km}^{-1}$, and operates at a wavelength of 1550 nm (C-band). The symbol rate for the single transmitted channel was 10 Gbaud and the modulation format quadrature phase shift keying (QPSK). The considered pulse shape was root-raised cosine (RRC), with a roll-off factor of 0.1. We do not specify any particular receiver, since the study compares the waveforms at the output of the fibre.

To evaluate the impact of the nonlinearities, the NSD was calculated for the powers in the highly nonlinear regime specified in Fig. 1. Fig. 2 shows the NSD versus P_{Tx} for the six analytical models analysed in this paper. As shown in Fig. 2, both LP and FLP on γ outperform RP on γ . The NSD of FLP on γ crosses the 0.1% NSD threshold at a P_{Tx} 1.1 dB higher than RP on γ . Analogously, both LP and FLP on β_2 outperform RP on β_2 . These results support that, either in the time or

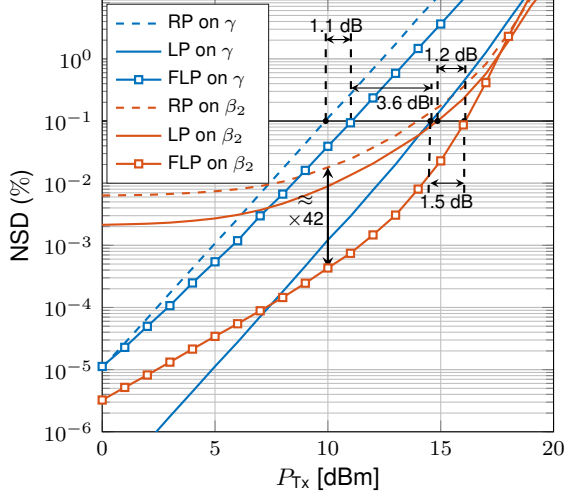


Fig. 2: NSD versus input power P_{Tx} for the six analytical models presented in this paper. The transmission is performed in C-band. A schematic of the system is shown in Fig. 1.

in the frequency domain, an (F)LP approach converges faster to the true solution of (1) than the standard RP approach.

The results in Fig. 2 also show that LP on γ is more accurate than FLP on γ , while FLP on β_2 is more accurate than LP on β_2 . For example, the NSD of LP on γ crosses the 0.1% NSD threshold at a P_{Tx} 3.6 dB higher than FLP on γ , while that of FLP on β_2 crosses the same threshold at a P_{Tx} 1.2 dB higher than LP on β_2 . We believe that the difference between β_2 and γ when comparing LP and FLP could be explained by the solution of (1) for only the chromatic dispersion effect or only the Kerr effect^[3]. The solution for the chromatic dispersion effect only is an exponential in the frequency domain, which resembles the FLP approach. Similarly, the solution for the Kerr effect only is an exponential in the time domain, which resembles the LP approach.

From the six models, FLP on β_2 is the one that presents best performance for P_{Tx} higher or equal 8 dBm. This result suggests that FLP on β_2 is more accurate for weak dispersion and high non-linearity. For a constant NSD of 0.1 %, FLP on β_2 shows a gain of 1.5 dB in terms of input power when compared to LP on γ . Larger gains are observed at lower NSDs.

The effects of the dispersion on the models' performance was also investigated. When reducing the accumulated dispersion, the models LP on γ , RP on β_2 , LP on β_2 , and FLP on β_2 converge to the true solution of (1). This convergence can be analytically proved by letting $\beta_2 \rightarrow 0$ in (4), (5), (6), and (8). However, their rate of convergence is different. Fig. 3 shows the NSD versus $|\beta_2|$ for

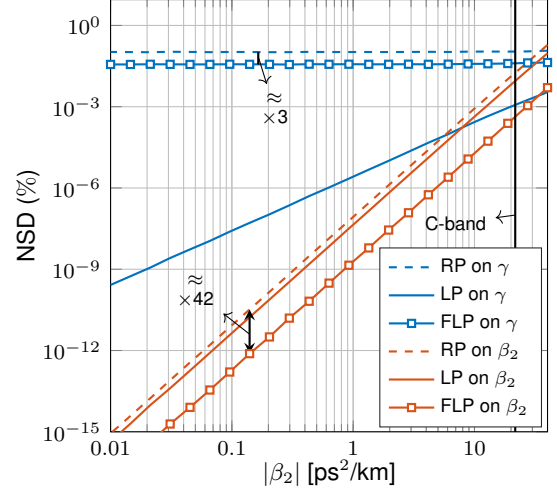


Fig. 3: NSD versus $|\beta_2|$ for the six analytical models presented in this paper. The input power is fixed at 10 dBm for the system shown in Fig. 1 with negative β_2 . The models present different rates of convergence when β_2 approaches to zero.

the six analysed models at $P_{Tx} = 10$ dBm and negative β_2 . As depicted in Fig. 3, RP on β_2 , LP on β_2 , and FLP on β_2 present a rate of convergence higher than LP on γ . While the NSD of the three former models increases by approximately 10^4 per decade, that of NSD for LP on γ increases by only 10^2 per decade. The NSD for FLP on β_2 is approximately 42 times lower than for RP on β_2 (see also Fig. 2). This gain is kept approximately constant for other values of β_2 . Only FLP on γ and RP on γ have approximately constant NSD over the shown range of β_2 . The NSD for FLP on γ was roughly 3 times lower than the NSD for RP on γ .

Conclusions

Three novel models based on logarithmic perturbation theory were presented. The validity of the models was investigated in the C-band for a passive optical network. The frequency logarithmic perturbation on β_2 model demonstrated higher accuracy in the highly nonlinear regime than the other models analysed in the paper. Building a receiver based on the proposed model and finding higher order perturbations are possible extensions of this work.

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