# **AI-DRIVEN ACCELEROMETER-BASED** BIRD ACTIVITY RECOGNITION

# CONTEXT

- Track activities of migrating birds
  - Study activity patterns
  - Sensor on bird
- Problem
  - Little available energy
  - Little storage



- Classify activities on bird
  - Easily usable data/insights for biologists

GOAL

- Reduces communication amount
- Distinguish 4 activity classes using accelerometer data
  - Swimming



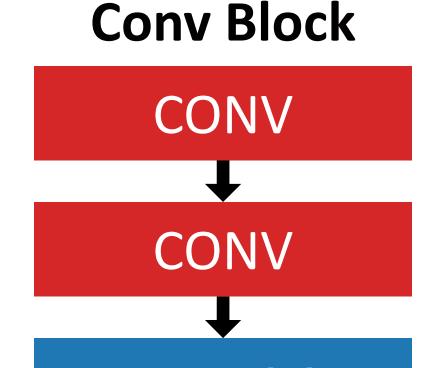
Compromise between uploading and collecting data

- Distance flight
- On ground (not moving)
- Foraging

## SETUP

#### • Data

- 60 accelerometer readings within 3 seconds every 5 minutes
- 10% of data labeled
- Use labeled data for training (supervised learning)
- Baselines
  - Decision Tree (max. depth 10)
  - Random Forest (50 decision trees)



# MODELS

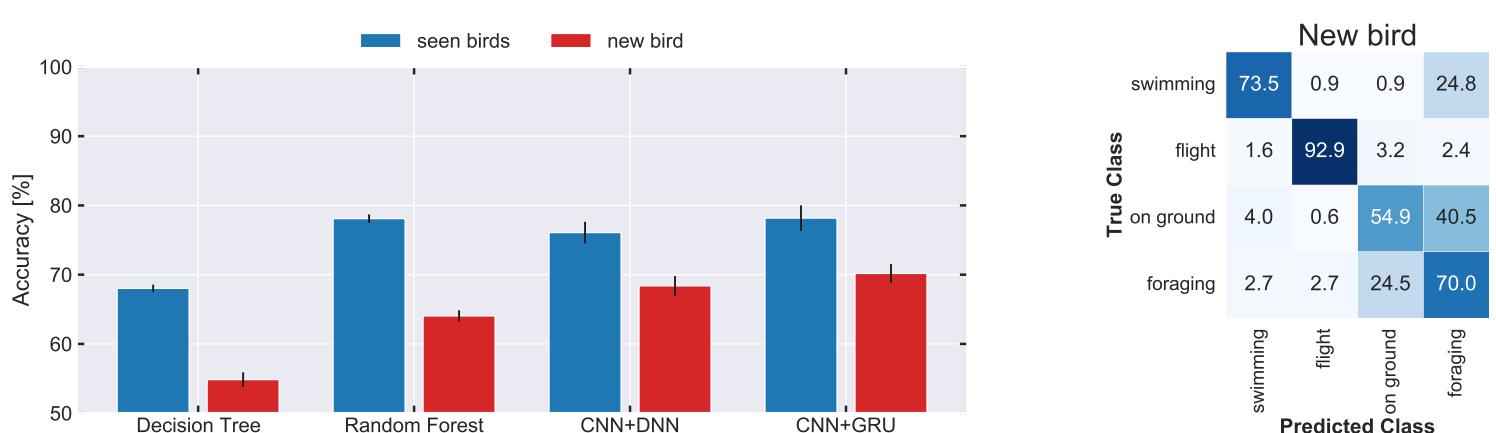
- Combination of Convolutional Neural Network (CNN) and Dense Neural Network (DNN)
  - 4 Convolutional blocks (two convolutions per block with 32+128, 32+32, 32+32, and 32+32 filters)
  - 4 Dense layers (32 neurons each)
- Combination of Convolutional Neural Network (CNN) and Recurrent Neural Network (RNN)
  - 2 Convolutional blocks (filters: 32+32) each followed by a dropout layer

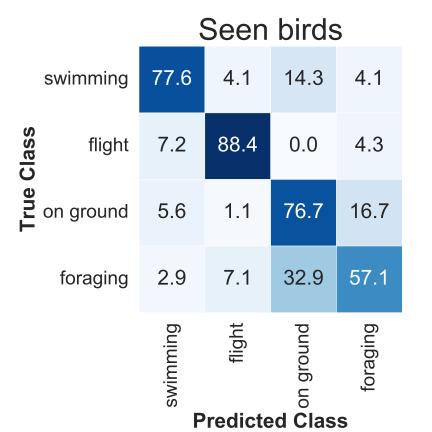
#### MAX POOL

#### 2 Gated Recurrent Unit (GRU) layers (64 outputs)

# INITIAL RESULTS

- 10 training runs
  - Decision Tree: 235 parameters
  - Random Forest: 11,813 parameters
  - CNN + DNN: 44,939 parameters (model used for confusion matrices)
  - CNN + RNN: 41,387 parameters





# **FUTURE WORK**

- Explore more approaches using unlabeled data
  - Semi-supervised learning
  - Unsupervised learning
- Split classes into subclasses
  - foraging and on ground are currently hardly distinguishable
  - Foraging is a combination of *flight* and *on ground*
- Collect data for longer periods of time
- Include previous activities
  - Get more context from available data
  - Learn how likely activities change

Random Fores CNN+DNN Predicted Class



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