



From Pain to Design Recommendations for Assistive Robotics

Downloaded from: <https://research.chalmers.se>, 2026-08-11 18:14 UTC

Citation for the original published paper (version of record):

Walczak, N., De Cet, M., Romanowski, A. et al (2023). From Pain to Design Recommendations for Assistive Robotics. ACM International Conference Proceeding Series: 428-430.
<http://dx.doi.org/10.1145/3623809.3623950>

N.B. When citing this work, cite the original published paper.

From Pain to Design Recommendations for Assistive Robotics

Natalia Walczak*

natalia.walczak122@gmail.com
Lodz University of Technology
Lodz, Poland

Andrzej Romanowski

andrzej.romanowski@p.lodz.pl
Lodz University of Technology
Lodz, Poland

Martina De Cet*

martina.decet@studenti.unitn.it
University of Trento & Chalmers University of Technology
Rovereto, TN, Italy

Mohammad Obaid

mobaid@chalmers.se
Chalmers University of Technology
Gothenburg, Sweden

ABSTRACT

Assistive technologies are vital for individuals with physical limitations, and understanding the diverse impact of physical pain is crucial for designing effective assistive robotic solutions. Through an iterative study, we aim to develop comprehensive design recommendations that cover personalization, concealment, compatibility, ease of use, preventive measures, skin-friendliness, affordability, adaptability, and multimodal features. These recommendations prioritize user experience and acceptance, ultimately contributing to innovative and user-centric assistive robotic technologies.

CCS CONCEPTS

• Human-centered computing → User centered design.

KEYWORDS

assistive technology, design process, mobility enhancement

ACM Reference Format:

Natalia Walczak, Martina De Cet, Andrzej Romanowski, and Mohammad Obaid. 2023. From Pain to Design Recommendations for Assistive Robotics. In *International Conference on Human-Agent Interaction (HAI '23)*, December 04–07, 2023, Gothenburg, Sweden. ACM, New York, NY, USA, 3 pages. <https://doi.org/10.1145/3623809.3623950>

1 INTRODUCTION

Assistive robotic agents have shown their potential in supporting individuals with daily tasks to enhance comfort and convenience [5, 6]. Their applications span from aiding urban daily activities [11] and work-related tasks [12, 24], to assisting individuals with impairments [8, 25]. Developers and designers are motivated to find solutions for challenging daily activities, and physical pain, a universal experience, can significantly impact one's life [15, 22]. Regardless of whether pain is acute or chronic, it can manifest diversely and affect various aspects of well-being.

*Both authors contributed equally to this research.

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the owner/author(s).

HAI '23, December 04–07, 2023, Gothenburg, Sweden

© 2023 Copyright held by the owner/author(s).

ACM ISBN 979-8-4007-0824-4/23/12.

<https://doi.org/10.1145/3623809.3623950>

Understanding diverse physical pain and its effects is vital for designing effective assistive machines. Our user-centred iterative approach involves two research iterations with 97 young adults, across diverse urban perspectives, to uncover user needs and identify essential features for assistive robotic devices.

2 RELATED WORK AND APPROACH

Ringwald et al.'s literature review on assistive robot design [17] reveals that while humanlike features can benefit these robots, only a few appearance patterns gain high acceptance. The scarcity of comparable studies and the multifaceted nature of acceptance highlight the importance of understanding target group needs and involving them in the design process instead of adopting a one-size-fits-all approach.

Additionally, extensive literature covers various applications of assistive technologies [1, 7, 9, 13, 21]. For instance, powered and electrical solutions [10, 23] are increasingly introduced to support individuals facing daily challenges due to various disabilities. In the same time, robotic exoskeletons find numerous applications in the biomedical and surveillance fields [1].

Furthermore, studies on the acceptance of assistive robotic technologies reveal promising outcomes. Carral et al. [2, 18–20] found that lower-limb exoskeletons were perceived as promising solutions for older people with mobility impairments and their caregivers. Chen et al. [3] emphasized considering emotional dimensions during assistive technology design, along with functionality and usefulness. Nertinger et al. [14] categorized daily activities by assistance levels. Examples of user-centred research include Power et al.'s [16] iterative design process for lower body exoskeletons and Golgothueh et al.'s [4] work on creating more flexible, light, and discrete assistive devices.

To our knowledge, limited research has explored general users' struggles in basic daily activities and how assistive technologies can support them. This motivated our user-centred approach, aiming to understand users' challenges in basic activities and address them using assistive robotic technology. We describe two iterative research phases in our approach and subsequently present a set of design recommendations for assistive technologies.

3 FIRST ITERATION - ONLINE SURVEY

An online survey included 77 participants (26M, 48F, 1NB, 2 did not respond) who answered open-ended and Likert scale questions. Participant ages ranged from 20 to 57 years (mean=34, SD 11.1). The

survey covered demographics and scenario-based inquiries related to mobility problems, frequency, and solutions. It was distributed in Poland (43 responses), Sweden (33 responses), and the UK (1 response).

3.1 Online Survey Results

Participants' mobility-related issues were collected and categorized into themes. They could share multiple struggles and rate them individually. The key insights were:

Commuting to work: Participants highlighted issues related to commuting to work or school, including road conditions, fuel costs, queues, and overcrowded public transport.

Sedentary lifestyle: Many discussed problems arising from a sedentary lifestyle, such as prolonged computer use leading to movement issues and feelings of laziness.

Physical pain: Affecting over half of the participants, revealed pain in body areas like the back, chest, hips, joints, and knees, along with pregnancy-related, injury-related, and post-operative pain.

Outdoor activities: Some faced difficulties in outdoor activities like sports and weightlifting, often due to physical limitations.

These themes were not evenly distributed between Poland and Sweden. Poland emphasized commute-related issues, while Sweden reported more sedentary lifestyle concerns. These findings influenced the subsequent interviews.

4 SECOND ITERATION - INTERVIEWS

The study employed two interview scenarios derived from the first study's thematic analysis. In these semi-structured interviews, participants discussed their daily mobility challenges and solutions, focusing on commuting decisions and end-of-workday struggles.

Twenty participants (8M, 12F), primarily students ($n=13$), aged 20 to 30 years (mean=24.4, SD 2.54), were interviewed for an hour. They used various transport modes, received public healthcare, and had limited prior experience with assistive technologies. The first iteration identified two main themes: 'Commuting to work' and 'sedentary lifestyle,' forming the basis for semi-structured interview scenarios. Participants imagined scenarios of preparing for work or school and an end-of-workday desk scenario. The interviews also explored participants' perceptions of potential assistive technologies addressing their identified problems, encouraging them to share visions and preferences for such technologies. They discussed key characteristics, willingness to use it for lower limb support, and thoughts on societal integration within a decade.

4.1 Results and Discussion

Thematic analysis was conducted by two coders on interviews from Sweden and Poland. The focus was on body pain during the day and proposed solutions. Themes included requirements, feedback, dimensions, well-being, visibility, affordability, and design choice. Participants also considered new technologies, often referring to existing solutions, and discussed their acceptance and potential target groups for assistive machines.

Pain: During interviews, participants frequently mentioned pain areas: Back-related pain, Head-related pain, and Limbs-related pain. Other pain points included muscle soreness, fatigue, pain due to obesity, injuries, and surgeries.

Design: Participants stressed the importance of well-designed, skin-friendly products with inconspicuous colours for societal acceptance.

Fit: Participants preferred discreet, comfortable, adaptable, lightweight, body-adhering solutions. Some favoured daily use, while others preferred temporary wear.

Visibility: Participants emphasized the importance of minimal visibility, non-intrusiveness, and imperceptibility.

Requirements and limitations: Users expressed interest in new technology but wanted assurance of safety and harmlessness. They sought information on testing and potential risks.

Feedback: Participants suggested technology reminders for breaks, posture correction, and standing up.

Wellbeing: Solutions related to back issues were prominent, with massage as a common suggestion. Users desired technology to reduce tension, track muscle fatigue, enhance strength, reduce anxiety, and support health monitoring.

Affordable: Participants highlighted the importance of cost accessibility for new technologies.

Technical solution: Various technical solutions were proposed, such as spine devices, vibrating mechanisms, sensors, adjustable speeds, and cable-driven technologies.

Specific existing solutions: Users discussed mobile apps, fitness trackers, stretching exercises, medication, warmers, electrical muscle stimulation, knee bands, robots, and exoskeletons.

Acceptance of new assistive technologies: Participants concerned about rapid advancements and side effects, recognizing its potential for enhancing self-sufficiency, experiencing emotions like shame, curiosity, and relief regarding its use.

Target group of assistive machines solutions: Identified target groups encompassed individuals with disabilities, older adults, those with chronic pain, stroke survivors, people recovering from injuries, industrial workers, healthcare professionals, manual labourers, and even recreational and sports enthusiasts, illustrating the broad potential impact of assistive machines.

5 CONCLUSIONS

Developing design recommendations for assistive technologies is valuable, but universal guidelines are complex due to diverse user needs. A user-centred approach, involving the target group throughout the design process is crucial, tailoring technologies to their requirements. Prioritizing lower limb and back pain issues, which emerged prominently, is essential, as these problems significantly impact daily life. Designers should focus on solutions that address these concerns, aiming to alleviate pain, enhance mobility, and support lower limb and back-related tasks, ultimately improving users' well-being.

This study's limitations include its focus on only two European countries and the younger generations, potentially limiting generalizability. Future research should gather data from a more diverse set of countries and include older adults to account for broader perspectives and age-related differences in needs. Implementing and validating design recommendations in practical projects, involving larger and more diverse participant groups, would enhance the applicability and impact of assistive machines, ensuring they address the needs of a wider user base.

REFERENCES

- [1] C. A. A. Sharma, A. S. K. Sai Vishnu Kumar, A. Prasad, R. Begum, G. S. Sharvani, and A. E. Manjunath. 2018. Multifaceted bio-medical applications of exoskeleton: A review. In *2018 2nd International Conference on Inventive Systems and Control (ICISC)*. 11–15. <https://doi.org/10.1109/ICISC.2018.8399053> Journal Abbreviation: 2018 2nd International Conference on Inventive Systems and Control (ICISC).
- [2] María del Río Carral, Vanlisa Bourqui, Noémie Vuilleumier, Amalric Ortieb, and M. Bouri. 2021. Are Functional Measures Sufficient to Capture Acceptance? A Qualitative Study on Lower Limb Exoskeleton Use for Older People. *International Journal of Social Robotics* 14 (2021), 603 – 616. <https://doi.org/10.1007/s12369-021-00810-9>
- [3] Ke Chen. 2018. Assistive Technology and Emotions of Older People – Adopting a Positive and Integrated Design Approach. In *Human Aspects of IT for the Aged Population. Acceptance, Communication and Participation*, Jia Zhou and Gavriel Salvendy (Eds.). Springer International Publishing, Cham, 21–29.
- [4] Alireza Golgouneh, Eric Beaudette, Heidi Woelfle, Bai Li, Niharikha Subash, Amanda J. Redhouse, Mark Jones, Tom Martin, Michele A. Lobo, Brad Holschuh, and Lucy E. Dunne. 2021. Design of a Hybrid SMA-Pneumatic Based Wearable Upper Limb Exoskeleton. In *Proceedings of the 2021 ACM International Symposium on Wearable Computers (ISWC '21)*. Association for Computing Machinery, New York, NY, USA, 179–183. <https://doi.org/10.1145/3460421.3478838> event-place: Virtual, USA.
- [5] K. Yamazaki, R. Ueda, S. Nozawa, Y. Mori, T. Maki, N. Hatao, K. Okada, and M. Inaba. 2010. System integration of a daily assistive robot and its application to tidying and cleaning rooms. In *2010 IEEE/RSJ International Conference on Intelligent Robots and Systems*. 1365–1371. <https://doi.org/10.1109/IROS.2010.5653614> Journal Abbreviation: 2010 IEEE/RSJ International Conference on Intelligent Robots and Systems.
- [6] K. Yamazaki, Y. Watanabe, K. Nagahama, K. Okada, and M. Inaba. 2010. Recognition and manipulation integration for a daily assistive robot working on kitchen environments. In *2010 IEEE International Conference on Robotics and Biomimetics*. 196–201. <https://doi.org/10.1109/ROBIO.2010.5723326> Journal Abbreviation: 2010 IEEE International Conference on Robotics and Biomimetics.
- [7] Kiwan Han, J. Lee, and W. -K. Song. 2013. Application scenarios for assistive robots based on in-depth focus group interviews and clinical expert meetings. In *IEEE ISR 2013*. 1–2. <https://doi.org/10.1109/ISR.2013.6695679> Journal Abbreviation: IEEE ISR 2013.
- [8] Roberto J. López-Sastre, Marcos Baptista-Ríos, Francisco J. Acevedo-Rodríguez, Soraya Pacheco-da Costa, Saturnino Maldonado-Bascón, and Sergio Lafuente-Arroyo. 2021. A Low-Cost Assistive Robot for Children with Neurodevelopmental Disorders to Aid in Daily Living Activities. *International Journal of Environmental Research and Public Health* 18, 8 (2021). <https://doi.org/10.3390/ijerph18083974>
- [9] M. Shoaib, E. Asadi, J. Cheong, and A. Bab-Hadiashar. 2021. Cable Driven Rehabilitation Robots: Comparison of Applications and Control Strategies. *IEEE Access* 9 (2021), 110396–110420. <https://doi.org/10.1109/ACCESS.2021.3102107>
- [10] Stephen J. Macdonald and John Clayton. 2013. Back to the future, disability and the digital divide. *Disability & Society* 28, 5 (July 2013), 702–718. <https://doi.org/10.1080/09687599.2012.732538> Publisher: Routledge.
- [11] Rachel Macrorie, Simon Marvin, and Aidan While. 2021. Robotics and automation in the city: a research agenda. *Urban Geography* 42, 2 (Feb. 2021), 197–217. <https://doi.org/10.1080/02723638.2019.1698868> Publisher: Routledge.
- [12] Harsh Maithani, Juan A. Corrales Ramon, Laurent Lequievre, Youcef Mezouar, and Matthieu Alric. 2021. Exoscarne: Assistive Strategies for an Industrial Meat Cutting System Based on Physical Human-Robot Interaction. *Applied Sciences* 11, 9 (2021). <https://doi.org/10.3390/app11093907>
- [13] N. Karavas, A. Ajoudani, N. Tsagarakis, and D. Caldwell. 2013. Human-inspired balancing assistance: Application to a knee exoskeleton. In *2013 IEEE International Conference on Robotics and Biomimetics (ROBIO)*. 292–297. <https://doi.org/10.1109/ROBIO.2013.6739474> Journal Abbreviation: 2013 IEEE International Conference on Robotics and Biomimetics (ROBIO).
- [14] Simone Nertinger, Robin Jeanne Kirschner, Abdeldjalil Naceri, and Sami Hadadin. 2022. Acceptance of Remote Assistive Robots with and without Human-in-the-Loop for Healthcare Applications. *International Journal of Social Robotics* (Oct. 2022). <https://doi.org/10.1007/s12369-022-00931-9>
- [15] Moon Young Park, Doyeon Han, Jung Ho Lim, Min Kyung Shin, Young Rok Han, Dong Hwan Kim, Sungsoo Rhim, and Kyung Sook Kim. 2019. Assessment of pressure pain thresholds in collisions with collaborative robots. *PLOS ONE* 14, 5 (May 2019), e0215890. <https://doi.org/10.1371/journal.pone.0215890> Publisher: Public Library of Science.
- [16] Valerie Power, Leonard O'Sullivan, Adam de Eyto, Samuel Schüle, Corien Nikamp, Christoph Bauer, Jeannette Mueller, and Jesús Ortiz. 2016. Exploring User Requirements for a Lower Body Soft Exoskeleton to Assist Mobility. In *Proceedings of the 9th ACM International Conference on Pervasive Technologies Related to Assistive Environments (PETRA '16)*. Association for Computing Machinery, New York, NY, USA. <https://doi.org/10.1145/2910674.2935827> event-place: Corfu, Island, Greece.
- [17] Marina Ringwald, Paulina Theben, Ken Gerlinger, Annika Hedrich, and Barbara Klein. 2023. How Should Your Assistive Robot Look Like? A Scoping Review on Embodiment for Assistive Robots. *Journal of Intelligent & Robotic Systems* 107, 1 (Jan. 2023), 12. <https://doi.org/10.1007/s10846-022-01781-3>
- [18] Linda Shore, Adam de Eyto, and L. O'Sullivan. 2018. Investigating Perceptions Related to Technology Acceptance & Stigma of Wearable Robotic Assistive Devices by Older Adults - Preliminary Findings. *DRS2018: Catalyst* null (2018), null. <https://doi.org/10.21606/DRS.2018.477>
- [19] Linda Shore, A. de Eyto, and L. O'Sullivan. 2020. Technology acceptance and perceptions of robotic assistive devices by older adults – implications for exoskeleton design. *Disability and Rehabilitation: Assistive Technology* 17 (2020), 782 – 790. <https://doi.org/10.1080/17483107.2020.1817988>
- [20] Linda Shore, V. Power, A. D. Eyto, and L. O'Sullivan. 2018. Technology Acceptance and User-Centred Design of Assistive Exoskeletons for Older Adults: A Commentary. *Robotics* 7 (2018), 3. <https://doi.org/10.3390/ROBOTICS7010003>
- [21] Linda Shore, Valerie Power, Bernard Hartigan, Samuel Schüle, Eveline Graf, Adam de Eyto, and Leonard O'Sullivan. 2020. Exoscore: A Design Tool to Evaluate Factors Associated With Technology Acceptance of Soft Lower Limb Exosuits by Older Adults. *Human Factors* 62, 3 (May 2020), 391–410. <https://doi.org/10.1177/0018720819868122> Publisher: SAGE Publications Inc.
- [22] Nahema Sylla, Vincent Bonnet, Frédéric Colledani, and Philippe Fraisse. 2014. Ergonomic contribution of ABLE exoskeleton in automotive industry. *International Journal of Industrial Ergonomics* 44, 4 (July 2014), 475–481. <https://doi.org/10.1016/j.ergon.2014.03.008>
- [23] Katharina Vornholt, Patrizia Villotti, Beate Muschalla, Jana Bauer, Adrienne Colella, Fred Zijlstra, Gemma Van Ruitenbeek, Sijr Uitdewilligen, and Marc Corbière. 2018. Disability and employment – overview and highlights. *European Journal of Work and Organizational Psychology* 27, 1 (Jan. 2018), 40–55. <https://doi.org/10.1080/1359432X.2017.1387536> Publisher: Routledge.
- [24] Astrid Weiss, Andreas Huber, Jürgen Minichberger, and Markus Ikeda. 2016. First Application of Robot Teaching in an Existing Industry 4.0 Environment: Does It Really Work? *Societies* 6, 3 (2016). <https://doi.org/10.3390/soc6030020>
- [25] Ya-Huei Wu, Victoria Cristancho-Lacroix, Christine Fassert, Véronique Faucounau, Jocelyne de Rotrou, and Anne-Sophie Rigaud. 2016. The Attitudes and Perceptions of Older Adults With Mild Cognitive Impairment Toward an Assistive Robot. *Journal of Applied Gerontology* 35, 1 (Jan. 2016), 3–17. <https://doi.org/10.1177/0733464813515092> Publisher: SAGE Publications Inc.