

Intelligent vehicles and smart transportation



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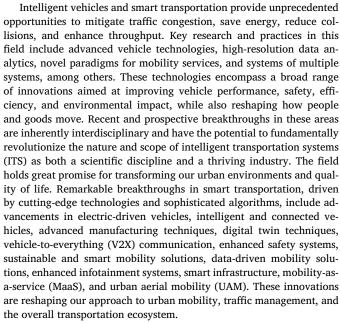


Editorial

Intelligent vehicles and Smart transportation



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Despite these advances, the application of intelligent vehicles and smart transportation systems is still in an exploratory stage, facing several significant challenges. These challenges include sensor reliability and accuracy, integration of technologies (V2X, AI, high-definition mapping), computing power and data processing, cybersecurity and data privacy, economic and business model challenges, regulatory and legal issues, infrastructure development, and social acceptance and ethical concerns, etc. Addressing these challenges requires a multifaceted approach involving technological innovation, regulatory frameworks, public engagement, and sustainable practices. Future work in this field is suggested in the following areas: (1) Multi-vehicle intelligence, a current development trend, should not only focus on achieving comprehensive

perception, driving decision-making, and control execution but also enhance intelligent road infrastructure, realize comprehensive intelligent cooperation, and improve commercial landing, thereby fostering the integrated development of vehicles and roads and advancing autonomous driving. (2) The application of AI algorithms in vehicle communication has become a new research hotspot. To improve the quality of datasets, reduce interference from emergencies, optimize control algorithms, and enhance ride comfort, further research is needed. (3) Research on highlevel autonomous vehicle test evaluation indices, models, and systems is still in its infancy. Future efforts should focus on test scenario classification, test task classification, improving the testing system, and accelerating the establishment of unified evaluation standards to strengthen the comprehensive evaluation system that integrates subjective and objective research.

This special issue of Fundamental Research on Intelligent vehicles and smart transportation collects eight papers: one review article and seven original research articles that showcase the latest achievements and envision the future of this field. Autonomous vehicles (AV) are rapidly becoming integrated into everyday life, with several countries anticipating their inclusion in public transport networks in the coming years. The AV domain is one of the fastest-growing areas due to rapid advances in computing, electronics, sensors, and communication technologies. Guo et al.[1] developed a domain adaptive semantic segmentation based on optimal transport in autonomous driving. Zhu et al.[2] proposed a bi-level ramp merging strategy for dense mixed traffic conditions to improve efficiency, emissions, and safety. Maksym et al. [3] developed an inverse motion planning technique for autonomous vehicles using integral nonlinear constraints. From the perspective of transportation electrification, Qu et al. [4] introduced an alternative pathway based on vehicle-to-vehicle (V2V) charging to reduce production costs and improve energy efficiency. Since CO₂ emissions from new energy vehicles (NEV) are non-negligible, Zhang et al. [5] proposed a framework for high-resolution well-to-wheel (WTW) CO₂ emission estimation for a full sample of vehicles, revealing the unique CO2 emission characteristics of different vehicle categories. With their high efficiency, zero

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pollution, and quiet operation, fuel cell vehicles (FCVs) have been promoted by many countries for green transportation. Yang et al.[6] optimized the hydrophobicity gradient of fuel cell gas diffusion media for vehicular applications. Urban Air Mobility (UAM) is an emerging transportation system that aims to revolutionize urban mobility. Liu et al.[7] reviewed the UAM system and the application of IT in UAM, discussing the major challenges and future potential of this transportation system. Zhang et al.[8] proposed a novel approach to improve the dynamic performance of software-defined vehicles (SDV) based on active structural transformation, which avoids rollover in critical situations and provides a more comfortable ride experience.

We hope this special issue will promote active scientific communication and spark further advancements in intelligent vehicles and smart transportation. Finally, as guest editors of this special issue, we extend our gratitude to all the authors for their outstanding contributions, to the editorial board members for their invaluable support and assistance, and to the referees for their thoughtful and helpful advice on these papers.

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