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Optimising finite-time quantum information engines using Pareto bounds

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E-mail: henning.kirchberg@chalmers.se**Keywords:** quantum information, measurement and control, thermodynamics, performance quantifiers, Pareto optimisation

Abstract

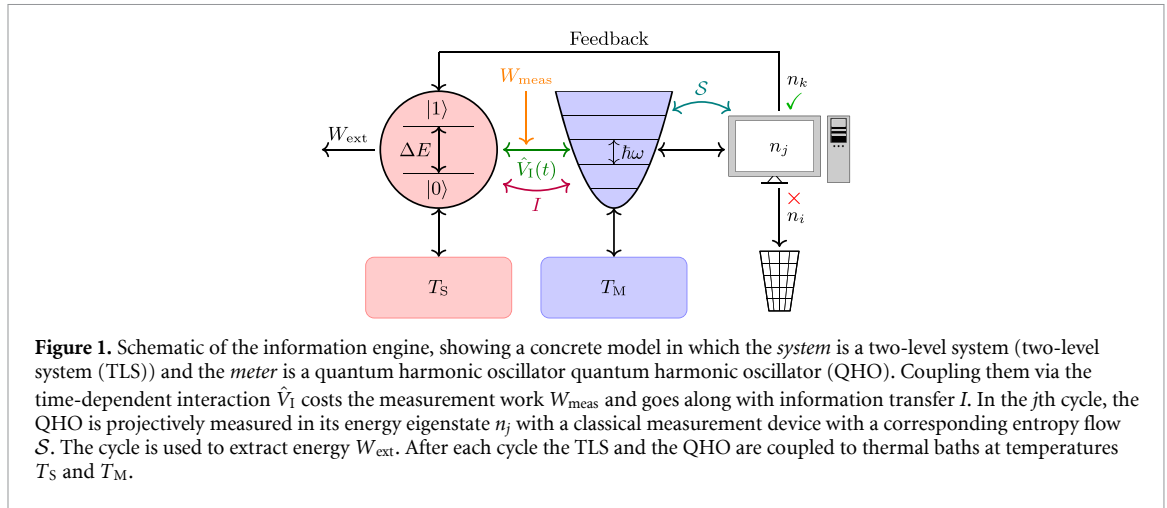
Information engines harness measurement and feedback to convert energy into useful work. In this study, we investigate the fundamental trade-offs between ergotropic output power, thermodynamic efficiency and information-to-work conversion efficiency in such engines, explicitly accounting for the finite time required for measurement. As a model engine, we consider a two-level quantum system from which work is extracted via a temporarily coupled quantum harmonic oscillator that serves as the measurement device. This quantum device is subsequently read out by a classical apparatus. We compute trade-offs for the performance of the information engine using Pareto optimisation, which has recently been successfully used to optimise performance in engineering and biological physics. Our results offer design principles for future experimental implementations of information engines, such as in nano-mechanical systems and circuit quantum electrodynamics (QED) platforms.

1. Introduction

Traditional heat engines convert thermal energy into mechanical work by operating between two heat reservoirs at different temperatures. In recent years, heat engines have been analysed in quantum and nanoscale systems, both theoretically and experimentally [1–5]. Information engines produce work not only by using heat as a resource, but also by exploiting information and feedback [6–8]. In contrast to standard heat engines, they can even extract energy from a single heat reservoir by processing information. It is the fundamental link between information and thermodynamics, exemplified by Maxwell's demon, that makes information engines possible [9–11]. The possibility to exploit information to convert energy to work has been studied theoretically [12–14] and it has been successfully demonstrated in experiments in the classical and quantum regime [15–18]. To analyse the performance of such an information engine, information has to be quantified as a resource, which is crucial to determine the efficiency of the engine [19, 20]. Even fluctuation relations including information [7, 21, 22] and the precision of information engines [20, 23] have been analysed.

A fundamental question arises regarding the duration of a measurement and, consequently, how quickly information can be acquired to perform feedback on the system to extract work [12, 24, 25]. This timescale may be particularly important in quantum information engines. Due to their small size, the *operation* time can be very short, making the measurement duration comparable to the engine's cycle time.

Consequently, the duration of the measurement becomes a key factor in the overall performance of the engine. In particular, the energy cost arising from the system-meter coupling but also the potential extracted work through measurement depend on the measurement time, which thus influences, *inter alia*, the efficiency of converting information into work and the operational power (i.e. the work extracted per measurement time).



This raises an important question when operating an information engine: what are the constraints on measurement time and how does it impact performance?

In this paper, we address this challenge and treat the measurement time as a crucial parameter, as it intrinsically links information acquisition, energy cost and extractable work. We thereby extend a previous study [25] and complement earlier work on finite-time cyclic information engines that consider bounds on their performance metrics with respect to the dissipation time into the heat reservoir [13]. Specifically, we present a comprehensive thermodynamic analysis of a quantum information engine, such as illustrated in figure 1, where we examine the time-dependent coupling between the quantum system and the quantum meter, focusing on their joint evolution. By placing the Heisenberg cut between the quantum meter and the classical apparatus, the study preserves quantum coherent evolution during measurement and enables analysis of measurement time and its associated energy costs. This is in line with von Neumann's framework [26], according to which a quantum measurement begins with a 'pre-measurement', which involves an interaction between the target system and a secondary system known as the 'quantum meter.' The quantum meter is then collapsed by a classical measurement apparatus, rendering the measurement outcome objective [27].

For this analysis, we here introduce the experimentally relevant system-meter configuration shown in figure 1: a two-level system (TLS) measured by a quantum harmonic oscillator (QHO). This setup is directly relevant to potential experimental platforms for quantum information engines such as nitrogen-vacancy centres, where spin degrees of freedom can be coupled and decoupled to a nano-mechanical oscillator by switching an external magnetic field on (coupling) and off (decoupling) [28]. Another example arises in quantum computing, where the state of a qubit is read out by coupling it to a microwave resonator [29, 30].

A key feature of our study is the identification of distinct thermodynamic regimes of operation. Depending on the measurement duration, the engine can function either as a heat engine—producing net work—or as a heat valve—transferring heat between reservoirs through work input.

To determine optimal engine configurations, a set of selected performance metrics must be optimised simultaneously, i.e. achieving both high power and high efficiency in converting information and energy into work via measurement. This is a challenging task, as all performance metrics are interdependent through the underlying engine parameters; achieving maximum power and maximum efficiency simultaneously is not possible. This interdependence gives rise to fundamental trade-offs—known as Pareto fronts—between the metrics [31]. Pareto optimality is well-established in economics [32] and engineering [33], and has begun to find applications in other domains, including stochastic thermodynamics [34–36], biological physics [37, 38], and, more recently, quantum heat engines [39, 40]. However, to our knowledge, it has not yet been employed in the optimisation of quantum information engines. In this paper, we apply multiobjective optimisation to explore these Pareto trade-offs in the context of information engines for the first time. We anticipate that this approach will provide practical guidance for jointly tuning experimental parameters to realise information engines operating in desired regimes.

The paper is organised as follows. In section 2, we introduce the general model for the information engine and describe its operational cycle. In section 3, we illustrate the implementation of the engine using a TLS coupled to a harmonic oscillator, where time-dependent information acquired through measurement is subsequently converted into work. Section 4 presents a detailed performance analysis, including the efficiencies of information-to-work and energy-to-work conversion, as well as the power

output, all as functions of the measurement time. In section 5 we analyse the Pareto-optimal trade-offs between the performance metrics—such as achieving maximum power at maximum efficiency—and determine optimal combinations of system-meter parameters and measurement duration. Finally, section 6 summarises our main results, outlines guidelines for experimental setups and lists potential research avenues for extending our Pareto optimisation in information-driven processes.

2. Information-engine principles

2.1. General model

The core of the quantum information engine consists of a system, from which work is extracted, and a meter obtaining information about the system; see the sketch in figure 1 for the concrete implementation introduced in section 3. The system and the meter are coupled for a certain time period—the measurement time t_m [25]. Due to this coupling, the meter obtains information about the system, which is subsequently used to extract work. This system-meter setup is captured by the Hamiltonian

$$\hat{H} = \hat{H}_S + \hat{H}_M + \hat{V}_I(t) \quad (1)$$

where \hat{H}_S is the Hamiltonian of the system, \hat{H}_M is the Hamiltonian of the meter, and $\hat{V}_I(t)$ describes their time-dependent interaction. This interaction part of the Hamiltonian is finite in a time interval $t \in (0, t_m)$ and zero otherwise.

In time intervals in which system and meter are uncoupled from each other, the system interacts with a heat bath at temperature T_S while the meter interacts with a heat bath at temperature T_M . We refer to these two baths as the system bath and the meter bath.

2.2. Engine cycle

The engine cycle consists of the following steps, see also [25] where an analogous cycle was analysed.

a. Initialisation: The system (S) and the meter (M) are initially uncoupled and in thermal states

$$\hat{\rho}_S(0) = \frac{\exp(-\hat{H}_S/k_B T_S)}{\text{tr}\{\exp(-\hat{H}_S/k_B T_S)\}}, \quad (2)$$

$$\hat{\rho}_M(0) = \frac{\exp(-\hat{H}_M/k_B T_M)}{\text{tr}\{\exp(-\hat{H}_M/k_B T_M)\}}, \quad (3)$$

specified by the temperatures T_S and T_M of the respective baths they are initially coupled to. Here, k_B is the Boltzmann constant. The total initial state is hence captured by $\hat{\rho}(0) = \hat{\rho}_S(0) \otimes \hat{\rho}_M(0)$.

b. Unitary evolution: Next, the system and meter are decoupled from their respective baths. Then, for the period of time $0 < t < t_m$, which we refer to as the *measurement time*, the system and meter are coupled to each other. This coupling is reflected by $\hat{V}_I(t)$ being non-zero for times $0 < t < t_m$. Importantly, since $[\hat{V}_I(t), \hat{H}_M] \neq 0$, the states of the system and of the meter become correlated during the time period t_m . Assuming instant switching of the coupling Hamiltonian at times $t=0$ ('on') and at $t=t_m$ ('off'), the measurement work, namely the work spent to correlate the system and meter states, is

$$W_{\text{meas}}(t_m) \equiv \text{tr}\{[\hat{H}_S + \hat{H}_M](\hat{\rho}(t_m) - \hat{\rho}(0))\}, \quad (4)$$

where $\hat{\rho}(t) = \hat{U}(t)\hat{\rho}(0)\hat{U}^\dagger(t)$ with $\hat{U}(t) = \mathcal{T} \exp\left[-\frac{i}{\hbar} \int_0^t dt' \hat{H}(t')\right]$, while \mathcal{T} being the time-ordering operator and \hbar being the reduced Planck constant. Note that the Hamiltonian entering the expression in equation (4) is the *total* Hamiltonian at times $t=0$ and $t=t_m$, where the system-meter coupling is switched off, $\hat{V}_I=0$.

c. Projective measurement & information acquisition: At time t_m the coupling between system and meter is turned off. The state of the meter is determined by a projective measurement on the eigenstates $|n\rangle$ of \hat{H}_M by a classical meter [41]. This quantum-to-classical transition is the Heisenberg cut [26, 42, 43]. After the projective measurement we can formulate the conditional density matrix

$$\hat{\rho}_S(t_m|n) = \frac{\langle n|\hat{\rho}(t_m)|n\rangle}{\text{tr}_S\{\langle n|\hat{\rho}(t_m)|n\rangle\}} \equiv \frac{\langle n|\hat{\rho}(t_m)|n\rangle}{P(n, t_m)}, \quad (5)$$

which depends on the measurement outcome n . The conditional probability of finding the system in state $|i\rangle$, given the measurement outcome n , is given by the diagonal elements of $\hat{\rho}(t_m|n)$:

$$P(i|n, t_m) = \langle i | \hat{\rho}(t_m|n) | i \rangle. \quad (6)$$

Similarly, the joint probability of the meter being in state $|n\rangle$ and the system being in state $|i\rangle$ at time t_m is given by

$$P(i, n, t_m) = \langle i | \langle n | \hat{\rho}(t_m) | n \rangle | i \rangle. \quad (7)$$

Starting from equation (5), the conditional entropy $S_n(t)$ given the measurement outcome n reads

$$S_n(t) = -k_B \sum_n \hat{\rho}(t_m|n) \ln \hat{\rho}(t_m|n). \quad (8)$$

Averaging over engine cycles, the entropy S is

$$S(t) = \sum_n P(n, t) S_n(t), \quad (9)$$

with $P(n, t)$ as defined in equation (5).

Thus, we quantify the information gain, $I(t_m)$, during the measurement process by the entropy difference [25], see discussion in appendix A,

$$I(t_m) \equiv S(0) - S(t_m). \quad (10)$$

d. Work extraction: Given the measurement outcome in step c , useful work can be extracted from the system, specifically when the system is more likely to be found in the excited state. Conversely, no work is extracted if the system is more likely to be found in its ground state, as attempting to do so would lead to a net energy cost rather than a gain, see later discussion in section 3 (d). We determine the extractable work by ergotropy, the maximal work that can be extracted under unitary transformation [44, 45]

$$W_{\text{ext}}(t_m|n) = \text{tr} \{ \hat{\rho}_S(t_m|n) \hat{H}_S \} - \min_{\hat{U}_n} \text{tr} \{ \hat{U}_n \hat{\rho}_S(t_m|n) \hat{U}_n^\dagger \hat{H}_S \}. \quad (11)$$

The first term on the right-hand side of equation (11) is the energy of the system after measuring the outcome n , whereas the second term is the energy of the system after applying a unitary transformation \hat{U}_n . Preferably the unitary transformation, \hat{U}_n , makes the second term vanishingly small to yield a maximal W_{ext} . In the example case of a TLS, as discussed later in section 3, this unitary work extraction can be realised by stimulated emission by a π -pulse [46]. Calculating the ensemble average over many engine cycles yields for the maximally extractable work

$$W_{\text{ext}}(t_m) = \sum_n P(n, t_m) \left[\text{tr} \{ \hat{\rho}_S(t_m|n) \hat{H}_S \} - \min_{\hat{U}_n} \text{tr} \{ \hat{U}_n \hat{\rho}_S(t_m|n) \hat{U}_n^\dagger \hat{H}_S \} \right]. \quad (12)$$

e. Resetting: The system and the meter are coupled to their respective baths, allowing both to rethermalise, thus closing the information-engine cycle. We now consider the energy flow during the information-engine cycle as depicted in figure 2. Upon successful extraction of work W_{ext} , equation (12), from the system a given amount of heat Q_S is released into the system to restore it to its initial thermal state, as given in equation (2). For the latter process, we assume that all heat from the system bath can be extracted as work $W_{\text{ext}} \equiv Q_S$. The energy invested for the measurement W_{meas} , equation (4), (due to coupling and decoupling of system and meter as discussed above) flows as heat into the meter bath, $W_{\text{meas}} \equiv Q_M$.

In principle, we should also consider the cost of resetting the classical meter, as alluded to in section 1, where the state of the quantum meter is registered. This cost is captured by the Landauer erasure work $W_{\text{reset}} = T_{\text{reset}} S$ with S being the entropy transferred between the quantum meter and the classical meter [47]. However, as we describe the projective measurement step with a classical meter, its temperature T_{reset} can be chosen to be arbitrarily small such that we can neglect the erasure work W_{reset} [41, 46, 48].

Next, we consider the *cycle time*, which is the sum of times associated with measurement, projection, work extraction, and resetting. In this study, as alluded to in the introduction, we identify the measurement time t_m under step b , the time period for system-meter coupling, as the largest and therefore dominant time scale for the cycle. In order to motivate this, we examine other timescales related to different steps discussed above.

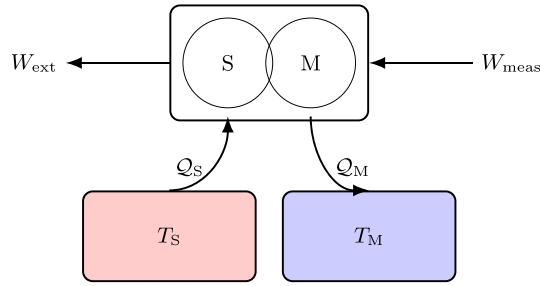


Figure 2. Energy flow diagram for the information engine operating between two heat baths at temperatures T_S , and T_M respectively. The engine is bipartite and consists of the system S from which energy W_{ext} can be extracted upon measurement and information acquisition by a meter M with energetic cost W_{meas} . The extracted work is compensated by the heat Q_S from the system's thermal bath while all energy invested for the measurement is released as heat Q_M into the meter bath.

First, we estimate the time for a projective measurement as described in step *c*. In principle, the quantum meter needs to be coupled and eventually decoupled from another quantum meter and so on, forming an infinite chain of meters, a well-known issue in measurement theory [49]. In our model, we use a classical meter to read out the quantum meter where the time can be estimated based on a decoherence mechanism [50]. This related decoherence time can be significantly shorter than t_m due to, for example, strong coupling or high complexity of the classical meter subspace as discussed in [41, 51].

Secondly, the time required for work extraction in step *e* can be estimated, e.g. for a TLS with energy splitting ΔE by the duration of stimulated emission under the influence of a π -pulse, which is on the order of the period time of the system and could be as short as $\hbar/\Delta E$ (ranging from 10^{-12} to 10^{-15} s in molecular systems [52] and 10^{-9} to 10^{-10} s for transmon qubits [29]). This process can be considered faster than t_m . In particular, in the operation of the information engine to produce net useful work, we find for the prototype engine studied in section 3 that the system energy is larger than the energy, $\hbar\omega$, associated with the quantum meter. Therefore, we have $(\Delta E/\hbar)t_m > \omega t_m$ which motivates the discussions of the measurement time in terms of ωt_m in sections 4 and 5.

Thirdly, considering the finite sizes of the system and meter, the reset time in step *f* (thermal relaxation) can be considered rapid when connected to heat reservoirs of infinite size [41] (approximately 10^{-12} seconds in condensed molecular systems [52]).

After outlining the detailed operational cycle of the quantum information engine, we now discuss possible performance metrics of the engine, with particular attention to the previously mentioned measurement time which dominates the cycle time.

2.3. Performance metrics

As measurement time, information acquisition, energy cost for measurement and the extracted work are interrelated, we consider the following three performance metrics: (A) the ratio of extracted work to information acquired from measurement, which we henceforth name information efficiency, (B) the power, and (C) the efficiency of converting the input energy to net extracted work, i.e. the thermodynamic efficiency.

(A) Measurement yields information, which in turn bounds the amount of work that can be extracted from the system. We define the information efficiency, i.e. the conversion of information to extracted work by the ratio

$$\eta_{\text{info}}(t_m) \equiv \frac{W_{\text{ext}}(t_m)}{T_S I(t_m)}, \quad (13)$$

where W_{ext} and I are defined by equations (12) and (10), respectively.

Since the maximal extractable work is given by the free energy difference after the projective measurement, as shown in appendix C and [25],

$$\Delta F(t_m) = \text{tr} \{ \hat{H}_S (\hat{\rho}(t_m) - \hat{\rho}(0)) \} + T_S I(t_m), \quad (14)$$

we have $W_{\text{ext}}(t_m) \leq \Delta F(t_m)$. However, for a non-demolishing measurement, i.e. $[\hat{H}_S, \hat{V}_I(t)] = 0$, we find that the first term in equation (14) vanishes, so that $W_{\text{ext}}(t_m) \leq T_S I(t_m)$ (see appendices C and D) and the information efficiency, equation (13), is bounded by $0 \leq \eta_{\text{info}} \leq 1$.

(B) The maximum power of the engine is given by

$$\Pi(t_m) \equiv \frac{W_{\text{ext}}(t_m) - W_{\text{meas}}(t_m)}{t_m} = \frac{W_{\text{net}}(t_m)}{t_m} \quad (15)$$

with the net extracted work defined by the difference between the extracted work, equation (12), and the measurement cost, equation (4). The measurement time t_m is considered the cycle time of the information engine as discussed in the previous section 2.2 and, thus, enters in the denominator of equation (15). We note that equation (15) represents an upper bound on the power output. First, the ergotropy which is used to quantify the extracted work W_{ext} is a bound as it describes the maximum work extracted under unitary transformation, see equation (12). Second, the measurement time t_m sets a lower bound to the total duration of the engine cycle.

(C) Finally, we consider the efficiency of converting the input energy Q_S to net extracted work $W_{\text{net}} = W_{\text{ext}} - W_{\text{meas}}$. We recognise that the engine can operate in various regimes, serving different thermodynamic purposes, namely as a heat engine if $W_{\text{net}} > 0$ or as a heat valve/pump if $W_{\text{net}} < 0$. For the thermodynamic efficiency, we limit our consideration to the heat engine regime, where $W_{\text{net}} \geq 0$. In this regime, heat flows from the bath at temperature T_S into the bath at temperature T_M , while the engine delivers a net positive amount of work. That is, heat flows from hot to cold, and work is extracted. As such we define the thermodynamic efficiency as

$$\eta_{\text{HE}}(t_m) \equiv \frac{W_{\text{ext}}(t_m) - W_{\text{meas}}(t_m)}{Q_S(t_m)} = 1 - \frac{W_{\text{meas}}(t_m)}{W_{\text{ext}}(t_m)}. \quad (16)$$

Note that we take $Q_S \equiv W_{\text{ext}}$ in equation (16), that is, all energy taken from the system heat bath can be extracted as work, as discussed under step e in section 2.2. Since $W_{\text{net}} \geq 0$ the efficiency, equation (16), is bounded by $0 \leq \eta_{\text{HE}}(t_m) \leq 1$.

3. TLS measured by a harmonic oscillator

To illustrate the general model introduced in section 2.2, we consider a quantum TLS with energy-level spacing ΔE as the system S and a QHO of frequency ω and mass \mathcal{M} as the meter, as shown in figure 1. The Hamiltonian of the system and the meter are given by

$$\hat{H}_S = \Delta E |1\rangle\langle 1|, \quad (17a)$$

$$\hat{H}_M = \frac{\mathcal{M}\omega^2}{2} \hat{x}^2 + \frac{1}{2\mathcal{M}} \hat{p}^2, \quad (17b)$$

where the energy of the $|0\rangle$ state is set to zero. The interaction Hamiltonian $\hat{V}_I(t)$ is switched on for the measurement time only, i.e.

$$\hat{V}_I(t) = \begin{cases} g|1\rangle\langle 1| \otimes \hat{p}, & t \in (0, t_m) \\ 0, & t \notin (0, t_m). \end{cases} \quad (17c)$$

For this specific example system, the generic information-engine cycle described in section 2.1 takes the following concrete form:

a. Initialisation: The initial state of the combined system and meter is

$$\begin{aligned} \hat{\rho}(0) &= \hat{\rho}_S(0) \otimes \hat{\rho}_M(0) \\ &= (a|0\rangle\langle 0| + b|1\rangle\langle 1|) \otimes \sum_{n=0}^{\infty} \frac{1}{Z_M} e^{-\beta_M \hat{H}_M} |n\rangle\langle n|, \end{aligned} \quad (18)$$

where $a = (1 + e^{-\beta_S \Delta E})^{-1}$ and $b = (1 + e^{+\beta_S \Delta E})^{-1}$ are the initial populations of the ground and excited states of the TLS and $\beta_S = (k_B T_S)^{-1}$ is the inverse temperature of the system bath. The initial meter state in equation (18) is thermal, defined by $\beta_M = (k_B T_M)^{-1}$ and the partition function $Z_M = \text{tr} \{ e^{-\beta_M \hat{H}_M} \}$.

b. Unitary evolution: During the time interval $t \in (0, t_m)$, the system and the meter evolve unitarily under the Hamiltonian $\hat{H}(t) = \hat{H}_S + \hat{H}_M + \hat{V}_I(t)$, resulting in an entangled state. The state of the full system at time t_m is thus given by

$$\hat{\rho}(t_m) = e^{-\frac{i}{\hbar} \mathcal{T} \int_0^{t_m} dt' \hat{H}(t')} \hat{\rho}(0) e^{\frac{i}{\hbar} \mathcal{T} \int_0^{t_m} dt' \hat{H}(t')}. \quad (19)$$

By evaluating the measurement cost, equation (4), for the case of a sudden switch of the system–meter interaction (17c), we find (see appendix E)

$$W_{\text{meas}}(t_m) \equiv \text{tr} \{ \hat{\rho}(t_m) \hat{H}(t_m) \} - \text{tr} \{ \hat{\rho}(0) \hat{H}(0) \} = b g_{\text{eff}}^2 (1 - \cos(\omega t_m)), \quad (20)$$

where $g_{\text{eff}}^2 = g^2 \mathcal{M}$ is the effective coupling strength.

c. Projective measurement & information acquisition: Using equation (7), the joint probabilities of finding the TLS in state $|i\rangle$ and the QHO in state $|n\rangle$ are given by (see appendix F)

$$P(0, n, t_m) = a (1 - e^{-\beta_M \hbar \omega}) e^{-\beta_M \hbar \omega n} \quad (21)$$

$$P(1, n, t_m) = b \sum_m P_m \left| \left(\frac{m!}{n!} \right)^{1/2} \alpha^{n-m} e^{-|\alpha|^2/2} L_m^{(n-m)}(|\alpha|^2) \right|^2 \quad (22)$$

where $L_m^{(n-m)}(x)$ are the generalised Laguerre polynomials, and

$$\alpha = \alpha(t_m) = \frac{g_{\text{eff}}}{\sqrt{2\hbar\omega}} (\sin(\omega t_m) - i(\cos(\omega t_m) - 1)). \quad (23)$$

The corresponding conditional probabilities are then given by $P(i|n, t_m) = P(i, n, t_m) / \sum_i P(i, n, t_m)$ according to equation (6).

Thus, we can calculate the information acquisition defined in equation (10). As we describe a non-demolishing measurement in this example, $[\hat{H}_S, \hat{V}_I] = 0$, the work extracted from the information engine is bounded by $W_{\text{ext}}(t_m) \leq T_S I(t_m)$ as discussed in section 2.3 (B) and appendices C and D.

d. Work extraction: Given a measurement outcome n of the meter, we consider the work extraction by ergotropy, equation (11), i.e. a unitary transformation is performed that maximises the extracted work according to equation (11). For a TLS this corresponds to population inversion, such that the extracted energy in this case is

$$W_{\text{ext}}(t_m|n) = \Delta E [P(1|n, t_m) - P(0|n, t_m)] \times \Theta(P(1|n, t_m) - P(0|n, t_m)), \quad (24)$$

where $\Theta(x)$ is the Heaviside function. Averaging over several engine cycles the ergotropy, equation (12), reads

$$\begin{aligned} W_{\text{ext}}(t_m) &= \sum_n P(n, t_m) W_{\text{ext}}(t_m|n) \\ &= \Delta E \sum_n P(n, t_m) [P(1|n, t_m) - P(0|n, t_m)] \times \Theta(P(1|n, t_m) - P(0|n, t_m)). \end{aligned} \quad (25)$$

To illustrate the behaviour of ergotropy and, thus, of work extraction in this setting, we show in figure 3 the conditional probabilities $P(i|n, t_m)$, as defined in equation (6) and calculated with equations (21) and (22). Here $i = 0, 1$ denotes the state of the TLS and n corresponds to the outcome of a projective measurement on the QHO at time t_m . At the initial time $t = 0$, the TLS and the QHO are uncoupled, implying that the conditional probabilities $P(0|n, t = 0) = a$ and $P(1|n, t = 0) = b$, see equation (18), are independent of the measurement outcomes n as shown by the solid straight lines in figure 3. This corresponds to a passive state, characteristic of thermal equilibrium, from which no work can be extracted when averaging over all cycles. At a later time $t = t_m$, the interaction between the system and the meter correlates them. Consequently, the conditional probabilities $P(i|n, t_m)$ of the TLS depend on the meter outcome n . For measurement outcomes $n \geq n'$, the conditional probability of finding the TLS in the excited state exceeds that of the ground state, i.e. $P(1|n, t_m) > P(0|n, t_m)$. This is a necessary condition for extracting work from the system, i.e. $W_{\text{ext}}(t_m|n) \neq 0$ in equation (24), by applying a π -pulse, see the white region in figure 3. Averaging over all cycles leads to an overall positive work extraction W_{ext} , equation (25).

e. Resetting: The information engine (IE) cycle is completed by resetting both the TLS and the QHO to their initial states by rethermalisation through interaction with their respective thermal reservoirs.

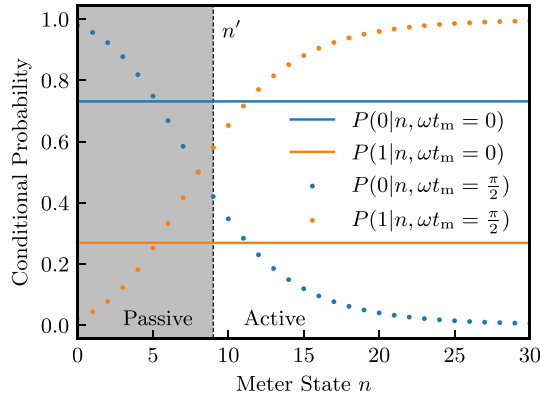


Figure 3. Conditional probabilities of the two-level system states $P(i|n, t_m = 0)$ for $i = 0, 1$ given a measurement outcome n . The solid lines show the conditional probabilities $P(i|n, t_m = 0)$ at time $t_m = 0$, i.e. when the system and meter are uncorrelated. The dotted lines show $P(i|n, t_m)$ at finite measurement time t_m which depend on the measurement outcome n . The dashed vertical line marks the first measurement outcome n' at which $P(1|n, t_m) > P(0|n, t_m)$. The chosen parameters are $\omega_{t_m} = \pi/2$, $\Delta E = k_B T_S = g_{\text{eff}}^2$, $\hbar\omega = 0.1\Delta E$, $T_M/T_S = 0.3$.

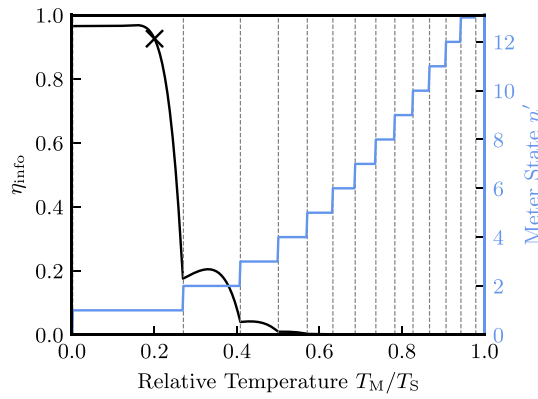


Figure 4. Information efficiency η_{info} (solid black line), equation (13), on the left vertical axis, and the lowest lying meter level n' (solid blue line) at which the condition $P(1|n, t_m) > P(0|n, t_m)$ is first satisfied on the right vertical axis. Both are plotted as functions of the relative temperature T_M/T_S . The chosen parameters are $g_{\text{eff}}^2/\Delta E = 0.1$, $\Delta E = 4k_B T_S$, $\omega_{t_m} = \pi/2$, and $\hbar\omega = 1.5k_B T_S$. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

4. Performance and measurement time

In this section, we study the performance metrics introduced in section 2.3 for the TLS measured by a QHO to investigate the interrelation between the extractable work, the information acquisition, the measurement time, and the energetic cost for this measurement.

4.1. Information-to-work conversion

The amount of work that can be extracted from the TLS is bounded by the information gained through measurement by the QHO (see also appendices C and D). Consequently, the efficiency of the engine in converting information to work is bounded by unity, $\eta_{\text{info}} \leq 1$, as shown in equation (13).

Figure 4 shows the information efficiency η_{info} , equation (13), as a function of the relative meter temperature T_M/T_S for a fixed set of parameters. At low relative temperatures η_{info} approaches unity, indicating that nearly all information gained can be converted into work. This fact can be understood from the temperature-dependence of the population of the meter's states: at low temperatures the ground state—and generally the lowest lying states—have a significantly higher occupation than all states above a certain crossover energy; by contrast, at higher temperatures the meter's state population is more uniformly distributed over a range of relevant meter states. As a result, effects impacting the population distribution become less visible at high temperatures. Consequently, for low temperatures the meter exhibits an increased sensitivity which allows one to measure the state of the system more accurately.

Importantly, the decrease of η_{info} seen in figure 4 with increasing meter temperature is however non-monotonic and not smooth. This behaviour can be understood by examining both the numerator

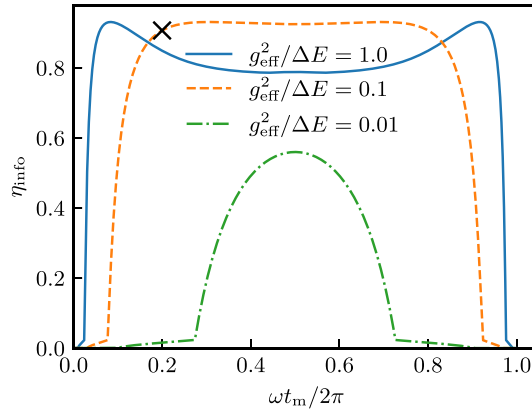


Figure 5. Information efficiency, equation (13), as a function of time for $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The other parameters are $T_M/T_S = 0.2$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

and denominator of η_{info} independently, given by W_{ext} , equation (25), and I , equation (10), respectively. Consider first W_{ext} . In order to have $W_{\text{ext}} \neq 0$ the condition $P(1|n, t_m) - P(0|n, t_m) \geq 0$ must be fulfilled. Given a fixed meter temperature this condition is met starting from a meter outcome $n \geq n'$ (see vertical dashed line in figure 3 for an example). With increasing meter temperature n' shifts to larger values in discrete jumps (see consecutive jumps of n' in figure 4). This explains the sharp kinks in the temperature-dependence of η_{info} (see also the resulting kinks for the extracted power in dependence of T_M/T_S in figure 16 in appendix B). Moreover, with increasing T_M/T_S the difference $P(1|n > n', t_m) - P(0|n > n', t_m)$ decreases. Thus, W_{ext} , the numerator of η_{info} , decreases.

Consider next the information I . The latter decreases with increasing T_M/T_S as less information can be obtained using a hot meter (see figure 14 in appendix A). Immediately following a jump in n' , W_{ext} initially decreases more slowly than the information I , resulting in an initial increase in the information efficiency η_{info} . However, the decline in information is monotonically saturating while the work extraction is continuously decreasing leading to a turnover and eventual decrease in the information efficiency η_{info} .

Figures 3 and 4 display results at a given measurement time $\omega t_m = \pi/2$. Next, we investigate, for a fixed set of parameters, the information efficiency η_{info} , equation (13), as a function of measurement time, shown in figure 5.

The information-to-work conversion efficiency, η_{info} , increases with measurement time, reaches either a local or global maximum, depending on the value of $g_{\text{eff}}^2/\Delta E$, and then decreases again (see discussion in the next paragraph). Note that, given the periodicity of the harmonic oscillator as meter, we observe a symmetry of η_{info} around $\omega t_m = \pi$. However, η_{info} shows a non-smooth evolution as a function of t_m . This can be understood from the non-smooth evolution W_{ext} with t_m entering the numerator of η_{info} . Given the condition $W_{\text{ext}} \geq 0$ we find for short times (i.e. $g_{\text{eff}} t_m \ll 1$ and $\omega t_m \ll 1$) that, see appendix G,

$$n' > \frac{\hbar\omega(a-b)}{2 \sinh^2\left(\frac{\beta_M \hbar\omega}{2}\right) (g_{\text{eff}} \omega t_m)^2 b}. \quad (26)$$

For a given set of system and meter parameters, the right hand side of equation (26) continuously decreases with measurement time. As n' can only decrease in integer values, t_m must increase until the next integer for n' is found. This discrete change in n' comes with a sudden jump in η_{info} , see figure 4 as discussed above.

Moreover, the dependence of η_{info} on measurement time is highly sensitive to the underlying parameters of the information engine—most notably, the system—meter coupling. A stronger coupling leads to a faster increase of the efficiency η_{info} , occurring at an earlier measurement time, as more information can be transferred between the system and the meter which can be exploited to extract work from the system within a given time interval. While η_{info} peaks at $t_m = \pi/\omega$ for a small system-meter coupling (see $g_{\text{eff}}^2/\Delta E = 0.01$ in figure 5), the maximum is shifted to smaller values of t_m with increased $g_{\text{eff}}^2/\Delta E$. Interestingly, for higher system-meter coupling a local minimum in η_{info} appears. Both the information (see figure 13 in appendix A) and the related extracted work (see figure 15 in appendix B) are increasing from zero with measurement time. With higher system-meter coupling, the extracted work and the

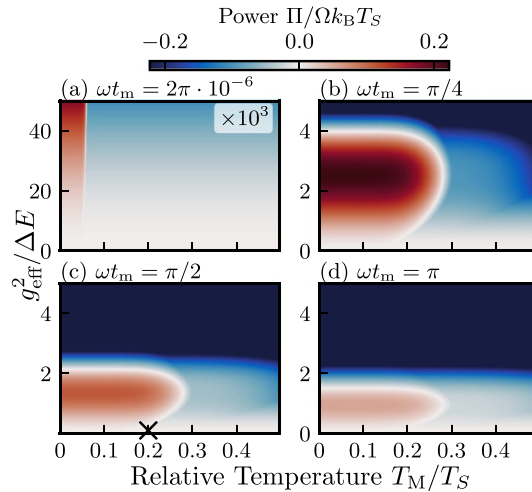


Figure 6. Power output (equation (15)) as a function of the relative temperature T_M/T_S and the effective relative coupling strength $g_{\text{eff}}^2/\Delta E$, shown at different measurement times. The fixed parameters are $\hbar\omega = 1.5k_B T_S$, and $\Delta E = 4k_B T_S$. Panels (a)–(d) correspond to $\omega t_m = 2\pi \cdot 10^{-6}$, $\pi/4$, $\pi/2$, and π , respectively. Red regions indicate positive power output (heat engine regime), while blue regions indicate negative power output (heat valve regime). The data in panel (a) has been multiplied by a factor of 10^3 to enhance visibility. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

information saturate at higher values. However, the extracted work saturates at a faster rate than the information, leading to an observed local minimum of their ratio described by η_{info} (see $g_{\text{eff}}^2/\Delta E = 0.1$ and $g_{\text{eff}}^2/\Delta E = 1$ in figure 5).

Overall, the behaviour of $\eta_{\text{info}}(t_m)$ clearly demonstrates that a finite measurement time within ωt_m modulo 2π is essential for converting acquired information into useful work.

4.2. Power

The information efficiency discussed above refers to the extracted work, but does not account for the measurement cost. The cost for the measurement impacts, however, the net power, equation (15), namely the *net* work per cycle (or equivalently per measurement) time.

Figure 6 shows the power Π as a function of the relative meter temperature T_M/T_S and the relative system-meter coupling strength $g_{\text{eff}}^2/\Delta E$. We introduce $\Omega = k_B T_S/\hbar$ as the inverse time scale to make the power unitless.

The power output of the proposed information engine is first evaluated at four different measurement durations as displayed in the heat maps in figure 6. This parameter manifold reveals distinct regions of positive (red areas in figure 6) and negative (blue areas) power production. A positive power output requires that the net work satisfies $W_{\text{net}} > 0$, as defined in equation (15). Importantly, to achieve a positive power output, a low relative temperature T_M/T_S is needed, as can be observed in all panels of figure 6. As discussed previously, this can be attributed to an enhanced sensitivity of the meter when the difference in state occupations around a given crossover energy is large. Naturally, in the limit of vanishing system-meter coupling, no power can be extracted anymore, as no information is exchanged between the system and the meter.

We now consider the impact of the measurement time on the whole parameter manifold in figure 6. At very short measurement times ($\omega t_m = 2\pi \cdot 10^{-6}$ in figure 6(a)), the power output is very small. Furthermore, to obtain these small (but finite) power outputs, the relative coupling strength $g_{\text{eff}}^2/\Delta E$ needs to be very large, reaching unphysical values for possible information engine setups. Typical values are $g_{\text{eff}}^2/\Delta E \sim 10^{-3}$ – 10^{-1} for both transmon qubits [53, 54] and optomechanical systems [28, 55].

As the measurement time increases, see panels figures 6(b) and (c), the magnitude of the power output also increases and the system-meter coupling strength required for positive power output reaches physically reasonable regimes as mentioned before.

However, when further increasing the measurement time, see panel figure 6(d), there is a substantial reduction in the parameter regime for the system-meter coupling yielding positive power. The reason for this is that at longer measurement times, the energetic cost of the measurement process W_{meas} , equation (20), which includes the coupling and decoupling of the system and meter, dominates the engine's performance—ultimately leading to net negative power production.

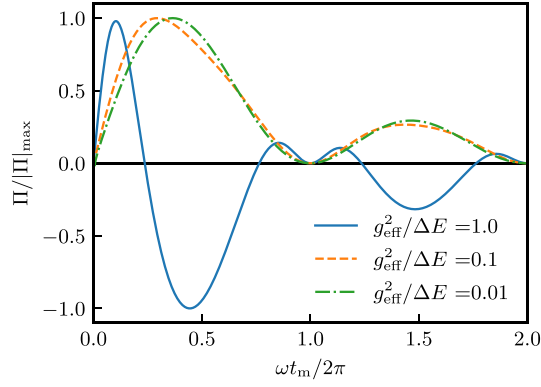


Figure 7. Power output normalised with its maximal absolute value, see equation (15), as a function of time for three values of the effective coupling strength, $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The chosen parameters are $T_M/T_S = 0.1$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$.

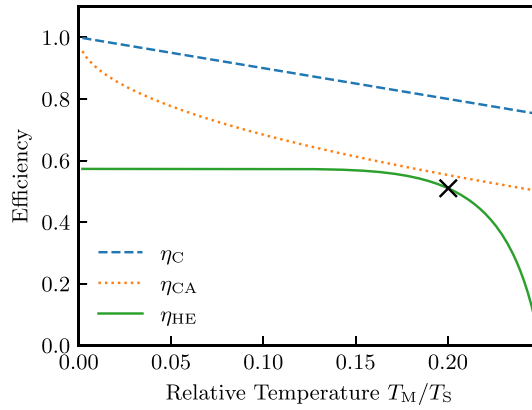


Figure 8. Efficiency, equation (16), as a function of relative temperature in the heat engine regime, defined by $T_M < T_S$ and $W_{\text{ext}} - W_{\text{meas}} > 0$. The Carnot efficiency, η_C , and Curzon–Ahlborn efficiency, η_{CA} , are shown for reference. Parameters are fixed as $\Delta E = 4k_B T_S$, $g_{\text{eff}}^2/\Delta E = 0.1$, $\omega t_m = \pi/2$, and $\hbar\omega = 1.5k_B T_S$. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

To investigate the measurement-time dependence further, we study next the power output *as a function* of measurement time for a fixed set of parameters, as shown in figure 7. As the measurement time increases, more power can initially be extracted from the system as more information about the system is obtained. However, the power Π exhibits an oscillatory behaviour, given the QHO as meter, reaching multiple local maxima before eventually declining. The overall decline of Π , equation (28), results from the fact that t_m enters in the denominator; the same amount of work is extracted over a longer period of time. The negative power output emerges for certain measurement times in particular for strong system-meter coupling (solid, blue curve in figure 7). This results from the substantial contribution of the measurement cost W_{meas} , equation (20), required to couple and decouple the meter with higher values of $g_{\text{eff}}^2/\Delta E$.

While a finite measurement time is necessary for obtaining non-zero power output, the optimal duration is highly sensitive to the system and meter parameters, most notably the system-meter coupling strength. All useful work extraction from measurement comes with a finite cost. Both must be optimally tuned by the measurement time to have Π positive. Another illustration of this sensitivity to system and meter parameters is provided in appendix H.

4.3. Thermodynamic efficiency

We finally examine the thermodynamic efficiency, η_{HE} , as defined in equation (16), accounting for the net extracted work compared to the absorbed heat. The result is shown in figure 8, where we plot the thermodynamic efficiency as function of the temperature ratio T_M/T_S , between meter and system. We compare the efficiency to the upper bounds given by Carnot efficiency and the Curzon–Ahlborn efficiency.

Firstly, it is noteworthy that η_{HE} is maximal at vanishing meter temperature and remains constant over a broad range of T_M/T_S . We start by investigating the value of η_{HE} in the limit of a vanishing meter

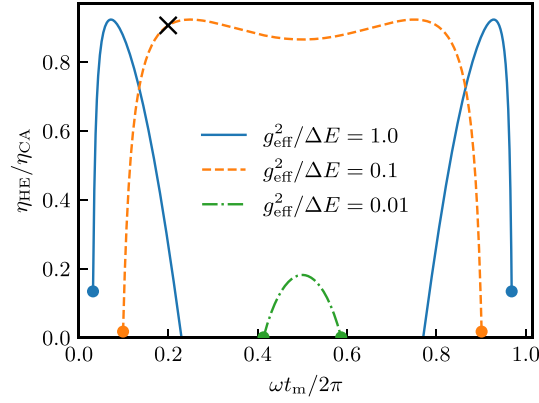


Figure 9. Thermodynamic efficiency, equation (16), as a function of time with $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The chosen parameters are $T_M/T_S = 0.2$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$. The points indicate the times for which $W_{\text{net}} < 0$ and the information engine is not producing net work. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

temperature, $k_B T_M \ll \hbar\omega$, with the measurement outcome $n' = 1$ (as seen in figure 4), as threshold to a positive net work extraction, W_{net} , equation (16) and, thus, $\eta_{\text{HE}} \geq 0$. In this limit, we find the thermodynamic efficiency, see appendix I, to be

$$\lim_{k_B T_M/\hbar\omega \rightarrow 0} \eta_{\text{HE}} = 1 - \frac{g_{\text{eff}}^2(1 - \cos(\omega t_m))}{\Delta E \left[1 - e^{-\frac{g_{\text{eff}}^2}{\hbar\omega}(1 - \cos(\omega t_m))} \right]}. \quad (27)$$

Utilising the system and meter parameters indicated in figure 8, we find $\eta_{\text{HE}} = 0.57$ in equation (27). Interestingly, in the limit of vanishing meter temperature, the thermodynamic efficiency in equation (27) maximises at $\omega t_m \rightarrow 0$ and reads $\eta_{\text{HE}} = 1 - \hbar\omega/\Delta E$ while the power $\Pi(\omega t_m \rightarrow 0)$, equation (15), vanishes. The result $\eta_{\text{HE}} = 1 - \hbar\omega/\Delta E$, which provides an upper bound on the thermodynamic efficiency, indicates that in the limit of a low meter temperature, the extraction of the maximum work ΔE from the TLS requires an investment of energy $\hbar\omega$ in the oscillator. By setting $\Delta E \gg \hbar\omega$, see discussion in appendix I, this maximum value can be tuned to unity, $\eta_{\text{HE}} \rightarrow 1$. In particular, in this parameter regime, having a high system temperature, the resulting relative temperature is vanishingly small, $T_M/T_S \rightarrow 0$, and the thermodynamic efficiency approaches the Carnot and Curzon–Ahlborn efficiencies, which serve as theoretical bounds, as discussed in the next paragraph, i.e. $\eta_{\text{HE}} \equiv \eta_{\text{CA}} \equiv \eta_{\text{C}}$. Continuing the discussion for η_{HE} in figure 8, a decline is observed at $T_M/T_S \approx 0.15$, or, when $k_B T_M$ is within one order of magnitude of $\hbar\omega$. This is attributed to the presence of discrete energy levels $\hbar\omega$ in the meter. When the meter temperature is low, $k_B T_M < \hbar\omega$, the ground state is more highly occupied, which enhances the change in the meter-state occupations due the system-meter coupling and consequently makes the measurement more precise. With a more precise meter, more information about the system can be obtained to extract its energy as useful work. Therefore, for a fixed measurement time and system temperature, η_{HE} declines to zero with increasing T_M/T_S as the meter becomes less sensitive.

Secondly, given that the proposed quantum information engine operates between two temperatures, $T_M \equiv T_{\text{cold}}$ and $T_S \equiv T_{\text{hot}}$, we compare its thermodynamic efficiency with the Carnot efficiency, $\eta_{\text{C}} = 1 - T_{\text{cold}}/T_{\text{hot}}$ [56, 57], and the Curzon–Ahlborn efficiency, $\eta_{\text{CA}} = 1 - \sqrt{T_{\text{cold}}/T_{\text{hot}}}$ [57, 58]. While the Carnot efficiency represents the theoretical maximum efficiency for heat engines operating in the adiabatic limit of infinite cycle time, the Curzon–Ahlborn efficiency provides a bound for engines operating under finite cycle times and finite power extraction. For the selected parameters, η_{HE} approaches η_{CA} , indicating the potential for efficient operation of the proposed quantum information engine at finite measurement time.

To assess how closely the quantum information engine can approach the Curzon–Ahlborn efficiency, we analyse the ratio $\eta_{\text{HE}}/\eta_{\text{CA}}$ as a function of measurement time in figure 9. This ratio increases with measurement time, reaches a (local) maximum, and subsequently decreases. This qualitative behaviour with respect to measurement time is also observed in figure 5 for the information efficiency under the chosen system–meter parameters, suggesting that, from the perspective of measurement time, both thermodynamic and information efficiencies are optimised by the same choice of parameters. It is important to note that a finite measurement time is needed for the information engine to produce work, i.e. $W_{\text{net}} = W_{\text{ext}} - W_{\text{meas}} > 0$, indicated by the solid points in figure 9. This highlights the necessity

of a finite, optimised measurement duration for achieving efficient operation in finite-time information engines. Interestingly, for the chosen set of parameters and a system-meter coupling strength of $g_{\text{eff}}^2/\Delta E = 0.1$ and $g_{\text{eff}}^2/\Delta E = 1$, the engine achieves a maximum value of $\eta_{\text{HE}}/\eta_{\text{CA}} \sim 0.95$, indicating that it can operate near the Curzon–Ahlborn efficiency. Interestingly, for intermediate system–meter coupling, the ratio $\eta_{\text{HE}}/\eta_{\text{CA}}$ remains nearly constant over a range of measurement times. This provides greater flexibility in designing experimental information engines with respect to the choice of measurement time. However, for these strong system-meter couplings, the high measurement cost must be accounted for. In particular, for $g_{\text{eff}}^2/\Delta E = 1$, the measurement cost eventually exceeds the extracted work. Note that the periodic behaviour of $\eta_{\text{HE}}/\eta_{\text{CA}}$ comes from the harmonic oscillator as meter.

5. Optimal engine design using Pareto fronts

For our proposed quantum information engine, it is desirable to achieve both a high rate of work extraction—characterised by a large positive power Π , equation (15)—and high efficiency in converting both input energy and information into useful work, respectively given by the thermodynamic efficiency η_{HE} , equation (16), and the information efficiency η_{info} , equation (13). However, these performance metrics depend on a shared set of system and meter parameters: the system and meter temperatures T_S and T_M , system and meter energy level spacings ΔE and $\hbar\omega$, their coupling strength g_{eff}^2 and, of particular interest here, the measurement time t_m . Changing the engine’s parameters thus influences all performance metrics concurrently and leads to the emergence of trade-offs between them, which need to be optimised in particular for experimental realisations of the proposed engine.

In this section, we compute a simultaneous optimisation of our metrics by determining Pareto-optimal trade-offs, also called Pareto fronts: a set of engine configurations where improving one metric necessarily compromises at least one other. Standard optimisation methods generally either compute only a single optimum e.g. high power or efficiency. Pareto fronts, however, represent the best possible balance between different metrics simultaneously. While originally developed in the context of economics and engineering, Pareto optimisation has been increasingly used in fields such as biology [35, 37] and stochastic thermodynamics [36]. However, to the best of our knowledge, Pareto optimisation has not previously been applied in the context of quantum information engines. A more technical description of Pareto-optimal fronts is given in appendix J.

While Lagrangian methods involving, e.g. optimal transport processes are known to be able to simultaneously minimise several known cost functions [59, 60], they generally involve convex combinations of the various objectives [39], effectively finding only the convex hull of the trade-off. For this reason, as well as due to the complexity of our performance metrics, we compute the fronts numerically using a variant of the elitist genetic algorithm NSGA-II [61], which is able to accurately determine non-convex parts of the fronts. In particular, we will focus on pairwise trade-offs between power, thermodynamic efficiency and information efficiency.

We consider first the Pareto trade-off between power and thermodynamic efficiency in figure 10(a). For a given arbitrary power output—e.g. $\Pi = (10/\pi)\Omega k_B T_S$, marked by the horizontal dashed line—the Pareto front defines the range of efficiencies (bounded by vertical dashed lines) over which the quantum information engine can operate. Points on the front with efficiency $\eta_{\text{HE}} \leq 0.5$, starting from the left of point A, correspond to the minimum efficiency attainable at a fixed power level, while points with $\eta_{\text{HE}} \geq 0.5$, starting from the right of point A (such as point B), indicate the maximum achievable efficiency for the same output power. Each point on the Pareto front thus corresponds to a specific set of engine parameters that yield an optimal trade-off between power and efficiency. For example, points A, B, C in figure 10(a) illustrate such configurations, with the corresponding parameters listed in table 1.

Configurations lying below this Pareto front are achievable but suboptimal. One representative suboptimal point below the Pareto front, marked by ‘×’ in figure 10(a), corresponds to the parameter set we used in the figures 4, 5, 6, 8, and 9 of the preceding section 4, and figure 17 in appendix H, where this point is also marked with the same symbol. By appropriately tuning the system and meter parameters, this point can be shifted toward the Pareto front, thereby increasing both power output and thermodynamic efficiency. For instance, fixing the efficiency of the point at $\eta_{\text{HE}} = 0.5$, as given in table 1, the parameters can be judiciously tuned such that the power increases without changing η_{HE} , approximately up to the point A. Conversely, no engine designs above the front are physically possible within our current formulation of the quantum information engine. However, when operating close to the Pareto front, the chosen free parameter space for the engine to have a non-vanishing efficiency might be limited, e.g. due to short measurement times as shown and discussed in appendix K.

Moving along the Pareto front from point A, where the power is maximal, to point C, where the thermodynamic efficiency is maximal, the engine parameters vary to preserve an optimal combination

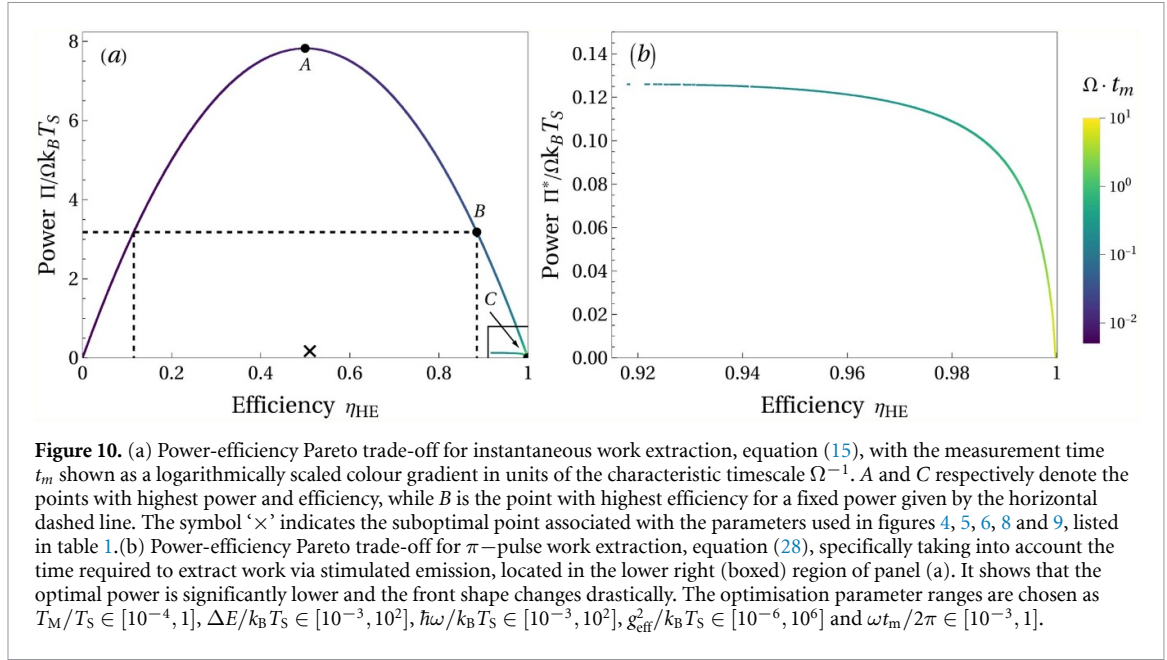


Figure 10. (a) Power-efficiency Pareto trade-off for instantaneous work extraction, equation (15), with the measurement time t_m shown as a logarithmically scaled colour gradient in units of the characteristic timescale Ω^{-1} . A and C respectively denote the points with highest power and efficiency, while B is the point with highest efficiency for a fixed power given by the horizontal dashed line. The symbol ‘x’ indicates the suboptimal point associated with the parameters used in figures 4, 5, 6, 8 and 9, listed in table 1. (b) Power-efficiency Pareto trade-off for π -pulse work extraction, equation (28), specifically taking into account the time required to extract work via stimulated emission, located in the lower right (boxed) region of panel (a). It shows that the optimal power is significantly lower and the front shape changes drastically. The optimisation parameter ranges are chosen as $T_M/T_S \in [10^{-4}, 1]$, $\Delta E/k_B T_S \in [10^{-3}, 10^2]$, $\hbar\omega/k_B T_S \in [10^{-3}, 10^2]$, $g_{\text{eff}}^2/k_B T_S \in [10^{-6}, 10^6]$ and $\omega t_m/2\pi \in [10^{-3}, 1]$.

Table 1. Pareto-optimal engine parameters corresponding to the labelled points A, B, C and ‘x’ in figures 10 and 11.

	η_{HE}	$\Pi/\Omega k_B T_S$	T_M/T_S	$\Delta E/k_B T_S$	$\hbar\omega/k_B T_S$	$g_{\text{eff}}^2/k_B T_S$	Ωt_m
A	0.50	7.82	2.66×10^{-3}	2.22	6.32×10^{-1}	4.02×10^4	9.95×10^{-3}
B	0.89	3.18	2.00×10^{-3}	2.24	1.45×10^{-1}	9.36×10^3	4.32×10^{-2}
C	1.0	0	1.53×10^{-4}	1.44×10^1	5.05×10^{-3}	1.23×10^{-3}	8.22
x	0.50	0.0107	2.00×10^{-1}	4.00	1.50	6.32×10^{-1}	1.05

of maximal power and efficiency. A key parameter in this trade-off is the measurement time, which we highlight using a colour scale in figure 10(a) and which we investigate in terms of the inverse time scale $\Omega = k_B T_S/\hbar$. This variation is shown consistently in both figure 10(a) and in figure 11, where points A, B, C are marked according to table 1. Point A indicates the overall maximum power that is reached at a thermodynamic efficiency $\eta_{HE} \approx 0.5$ where a measurement time $t_m = 9.95 \times 10^{-3} \Omega^{-1}$ is required. The measurement time increases continuously when going from $A \rightarrow C$ along the front. As expected, when the thermodynamic efficiency of converting input energy to useful work is reaching its global maximal value in point C, the maximally achievable power output vanishes. Conversely, when the power output increases the thermodynamic efficiency decreases, i.e. following $C \rightarrow A$. This Carnot-like behaviour at C, namely maximum achievable efficiency at vanishing output power, can be understood from the fact that, due to the long measurement time and thus the time to complete the cycle of the information engine, the process becomes adiabatically slow. In the present context, a sufficiently long measurement time is required to obtain enough information about the system to transduce all energy into work per cycle. Since the measurement time sets a lower bound on the engine cycle duration, the Pareto front shown in figure 11 can be interpreted as the speed limit of the investigated quantum information engine for producing net useful work.

We consider next the other parameters along the Pareto front. Moving from A to C entails decreasing the relative meter to system temperature, the effective coupling and the oscillator frequency, while simultaneously increasing the TLS energy level spacing and the measurement time, see table 1. In fact, close to the point C, increasing $\Delta E \gg k_B T_S$ leads to a very small population of the excited state of the system which we measure and from where we want to extract work. Similarly, the decrease of T_M/T_S leads to meter state occupations that peak sharply in the ground state. The decrease in the effective coupling strength between system and meter leads to a reduced measurement cost, which consequently produces only a very low amount of heat in the meter bath. Together, these combined effects lead to an overall decrease in losses when converting energy to useful work and drive the engine towards an efficiency of $\eta_{HE} = 1$. Note that near point C, the Pareto-optimal parameters naturally reproduce the condition $k_B T_M \ll \hbar\omega$ underlying the approximation in equation (27), see section 4.3 and appendix I, as can be readily confirmed in table 1. Additionally, moving toward unit efficiency in equation (27) is also confirmed by the Pareto-optimised parameters, which lead to the required conditions that $\Delta E \gg \hbar\omega$ and

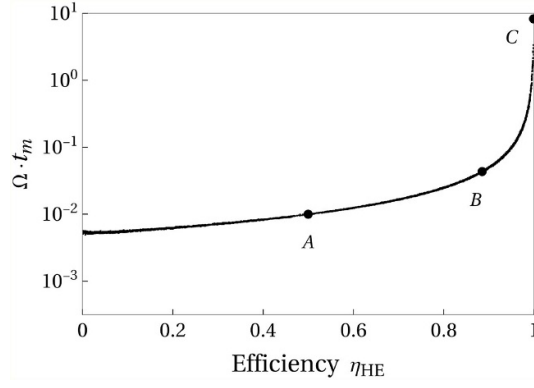


Figure 11. Measurement time along the power-efficiency Pareto front of figure 10(a) plotted against thermodynamic efficiency η_{HE} . The optimisation parameter ranges are $T_M/T_S \in [10^{-4}, 1]$, $\Delta E/k_B T_S \in [10^{-3}, 10^2]$, $\hbar\omega/k_B T_S \in [10^{-3}, 10^2]$, $g_{eff}^2/k_B T_S \in [10^{-6}, 10^6]$ and $\omega t_m/2\pi \in [10^{-3}, 1]$.

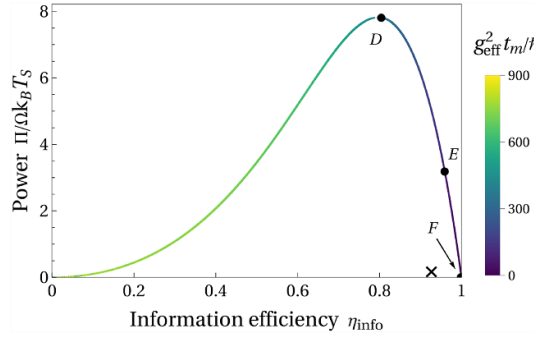


Figure 12. Power-information efficiency Pareto trade-offs for instantaneous work extraction, equation (15), with the coupling strength normalised measurement time $g_{eff}^2 t_m / \hbar$ shown as a colour gradient. *D* and *F* respectively denote the points with highest power and information efficiency, while *E* is the point with highest efficiency for a fixed power $\Pi = (10/\pi)\Omega k_B T_S$. The ‘ \times ’ indicates the suboptimal point associated with the parameters used in figures 4, 5, 6, 8 and 9, listed in table 2. The optimisation parameter ranges are $T_M/T_S \in [10^{-4}, 1]$, $\Delta E/k_B T_S \in [10^{-3}, 10^2]$, $\hbar\omega/k_B T_S \in [10^{-3}, 10^2]$, $g_{eff}^2/k_B T_S \in [10^{-6}, 10^6]$ and $\omega t_m/2\pi \in [10^{-3}, 1]$.

$T_M \ll T_S$. This agreement highlights that the approximation captures the essential physics of the system in the regime where performance is optimised.

Interestingly, for $\eta_{HE} < 0.5$, descending to the left from point *A* in figure 10(a), the measurement time t_m continues to decrease along the Pareto front, as shown in figure 11. This indicates that a finite, non-zero measurement time is always necessary to balance high power extraction with thermodynamic efficiency.

Note that the power-efficiency Pareto optimisation we discussed intrinsically depends on the exact description of the engine; ‘hidden’ or neglected processes influencing the performance metrics naturally change the shape of the fronts. One way to model such a neglected process is by explicitly taking into account the time required to extract work via stimulated emission with a π -pulse, given by $t_{st} = \hbar\pi/\Delta E$, which we previously did not account for. This influences the power that is extracted as follows:

$$\Pi^*(t_m) = \frac{\Pi(t_m)}{1 + t_{st}/t_m}. \quad (28)$$

The front obtained by performing the Pareto optimisation of Π^* and η_{HE} is shown in the bottom right corner of panel (a) in figure 10; an enlarged version is shown in panel (b). As anticipated, the resulting Pareto front of maximised thermodynamic efficiency and modified power Π^* , equation (28), lies globally below the previously discussed front. However, the newly obtained Pareto front shows the same trend for the measurement time and the system and meter parameters when moving along it.

We study next the trade-off between the power output and information efficiency in figure 12. A similar methodology as before can be used to determine the optimal system and meter parameters along the resulting Pareto front. The parameters corresponding to the points *D*, *E*, *F* and ‘ \times ’ are given

Table 2. Pareto-optimal engine parameters corresponding to the labelled points *D*, *E*, *F* and ‘ \times ’ in figure 12.

	η_{info}	$\Pi/\Omega k_{\text{B}} T_{\text{S}}$	$T_{\text{M}}/T_{\text{S}}$	$\Delta E/k_{\text{B}} T_{\text{S}}$	$\hbar\omega/k_{\text{B}} T_{\text{S}}$	$g_{\text{eff}}^2/k_{\text{B}} T_{\text{S}}$	Ωt_{m}
<i>D</i>	0.80	7.81	1.43×10^{-2}	2.30	6.45×10^{-1}	4.06×10^4	9.74×10^{-3}
<i>E</i>	0.96	3.18	1.59×10^{-1}	3.18	1.35	1.84×10^4	4.67×10^{-3}
<i>F</i>	1.0	0	1.31×10^{-1}	3.56	1.56	6.45×10^2	4.06×10^{-3}
\times	0.93	0.0107	2.00×10^{-1}	4.00	1.50	6.32×10^{-1}	1.05

in table 2, where the point ‘ \times ’ corresponds once again to the suboptimal set of parameters used in figures 4, 5, 6, 8, 9 in section 4 and figure 17 in appendix H.

In particular, we examine the measurement time weighted by the coupling strength between the system and the meter. In fact, \hbar/g_{eff}^2 can be understood as characteristic transfer time between the system and the meter. In maximising both power output and information efficiency, i.e. following the Pareto front from *D* \rightarrow *F* in figure 12, we observe that $g_{\text{eff}}^2 t_{\text{m}}/\hbar$ approaches zero for $\eta_{\text{info}} \rightarrow 1$. This configuration allows for the maximal conversion of information into useful work. To be concrete, a small value of $g_{\text{eff}}^2 t_{\text{m}}/\hbar$ implies that a minimal amount of information transferred during t_{m} can be completely converted into a correspondingly small amount of work. In this regime the power output vanishes.

As the value of $g_{\text{eff}}^2 t_{\text{m}}/\hbar$ increases, more information can be generated during t_{m} . However, only a portion of this information is converted to work, resulting in a reduced η_{info} while producing finite power. Interestingly, $g_{\text{eff}}^2 t_{\text{m}}/\hbar$ continues to increase even when minimising η_{info} while maximising Π , i.e. following the Pareto front $\eta_{\text{info}} \rightarrow 0$ starting from point *D* in figure 12. This underscores the necessity of a finite coupling between the system and the meter to ensure non-zero power output and enable the effective conversion of information into useful work within a finite measurement time t_{m} , before the energetic costs related to large g_{eff} limit this process.

6. Conclusions

We studied a cyclic information engine in which measurement and subsequent feedback are used to convert energy into useful work. Information is considered as a crucial *resource* that must be exchanged between the system and the meter over a finite time. This *measurement time* can be comparable to the engine’s operational time, especially in the nanoscale regime. Importantly, each measurement also incurs an intrinsic cost that depends on the measurement time and must be properly accounted for. In this work, we investigated the interrelation between information acquisition, extractable work, and the energetic cost of measurement—all as functions of the measurement time.

As a prototype, we formulated and analysed a quantum information engine cycle involving a TLS measured by a QHO—a setup inspired by experimental platforms such as nitrogen-vacancy centres or superconducting qubits coupled to resonators. Within this framework, we found that a finite measurement time is essential to transfer sufficient information about the system to the meter to achieve positive power output and high efficiency in the conversion of energy and information into work. We found that lower meter temperatures and stronger system–meter coupling enhance the meter’s sensitivity, thereby improving information transfer. While no information can be transferred in the absence of system–meter interaction, excessively strong coupling can become detrimental due to increased measurement costs, ultimately leading—under certain conditions—to zero and even negative net work. This highlights the fundamental fact that information, as the critical resource of information engines, cannot be acquired instantaneously and without cost. Information acquisition through measurement, the related energetic cost and the subsequent work extraction are highly interrelated by the measurement time.

Our results further show that achieving positive power output and high efficiency in the conversion of information and energy into useful work requires careful tuning of the measurement time and of other system and meter parameters. This reveals intrinsic trade-offs between these performance metrics, which we analysed using Pareto fronts—a global optimisation framework. Notably, we identified a global maximum in power output at a finite efficiency, occurring at a specific, finite measurement time for the prototype information engine.

Since the Pareto fronts naturally bound the trade-offs between the engine’s performance metrics, they identify the optimal combinations of system and meter parameters for maximising information engine performance. This offers practical guidance for experimentally selecting optimal engine configurations.

Exploiting measurement and information as a *resource* for controlling and optimising *outputs* can be vital not only in contexts such as energy transduction in nanoscale devices, but also in other research fields such as chemistry to improve reaction yields [18]. In particular, the consideration of measurement time is crucial to control and optimise time-dependent processes. Moreover, at the nanoscale of information driven processes, additional complexity may arise due to fluctuations in quantities such as the power output. This might lead to future investigations of, *inter alia*, the relation between the signal-to-noise ratio, the acquired information and the measurement time.

Data availability statement

The data that support the findings of this study are openly available at the following URL/DOI: [10.5281/zenodo.15646115](https://doi.org/10.5281/zenodo.15646115).

Acknowledgments

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Code availability

The code used to generate the data for this article is available on Zenodo (DOI: [http://doi.org/10.5281/zenodo.15646115](https://doi.org/10.5281/zenodo.15646115)) under a Creative Commons Attribution 4.0 International (CC BY 4.0) license.

Appendix A. Mutual Information

For a non-demolishing measurement, i.e. $[\hat{H}_S, \hat{V}_I] = 0$, we find the mutual information to be

$$I(t_m) \equiv S(0) - S(t_m) \quad (\text{A1})$$

$$= -k_B \sum_n \sum_{i=0}^1 P(i, n, 0) \ln P(i|n, 0) \quad (\text{A2})$$

$$+ k_B \sum_n \sum_{i=0}^1 P(i, n, t_m) \ln P(i|n, t_m),$$

$$= -k_B \sum_n \sum_{i=0}^1 P(i, n, t_m) \ln P(i|n, 0) \quad (\text{A3})$$

$$+ k_B \sum_n \sum_{i=0}^1 P(i, n, t_m) \ln \frac{P(i, n, t_m)}{P(n, t_m)},$$

$$= k_B \sum_n \sum_{i=0}^1 P(i, n, t_m) \ln \frac{P(i, n, t_m)}{P(n, t_m) P(i|n, 0)} \quad (\text{A4})$$

$$= k_B \sum_n \sum_{i=0}^1 P(i, n, t_m) \ln \frac{P(i, n, t_m)}{\sum_i P(i, n, t_m) \sum_n P(i, n, t_m)} \geq 0. \quad (\text{A5})$$

In equation (A3), we have used the fact that $P(i|n, 0)$ is independent of n and gives $P(0|n, 0) = a$ and $P(1|n, 0) = b$ and that we have a non-demolishing measurement, i.e. the system-meter coupling has the form $\hat{V}_I \propto \sum_i |i\rangle \langle i|$ such that one couples to the eigenstates of the system. Therefore we have

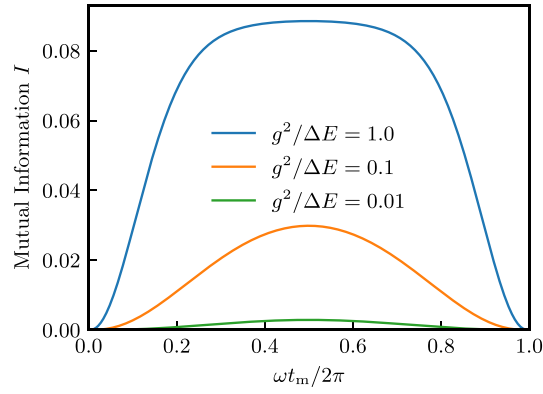


Figure 13. Information, equation (10), as a function of time for $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The other parameters are $T_M/T_S = 0.2$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$.

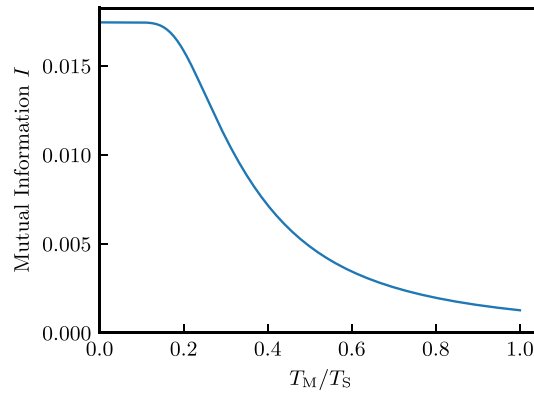


Figure 14. Information, equation (10), as a function of relative temperature T_M/T_S . The chosen parameters are $g_{\text{eff}}^2/\Delta E = 0.1$, $\Delta E = 4k_B T_S$, $\omega t_m = \pi/2$, and $\hbar\omega = 1.5k_B T_S$.

$\sum_n P(0, n, t_m) = a$ and $\sum_n P(1, n, t_m) = b$ which is equal to the marginal probabilities by tracing out the meter. Equation (A4) is the mutual information expression associated with the measurement process.

Figures 13 and 14 display mutual information for a chosen set of parameters of the system meter as a function of the measurement time and temperature ratio T_M/T_S respectively.

Appendix B. Extracted work by ergotropy

Figure 15 displays the extracted work by ergotropy, equation (24), as function of measurement time and figure 16 portrays the power output, equation (15), as a function of relative temperature T_M/T_S , for a chosen set of system-meter parameters.

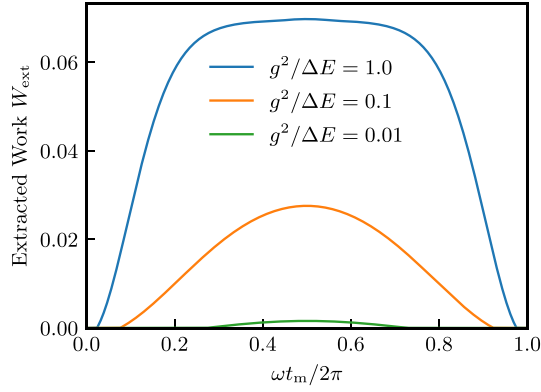


Figure 15. Extracted work, W_{ext} , equation (24), as a function of time for $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The other parameters are $T_M/T_S = 0.2$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$. Note that for small times (and at the end of the period) W_{ext} is vanishing small but non-zero so that η_{info} is non-zero.

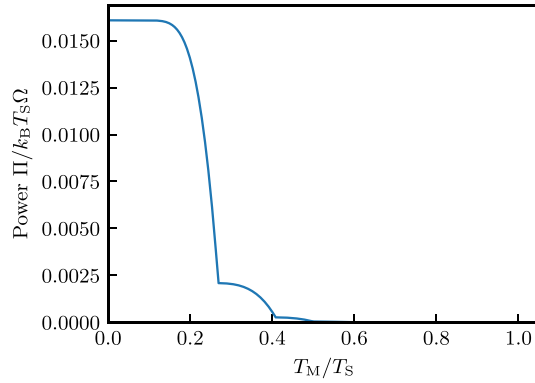


Figure 16. Power, equation (15), as a function of relative temperature T_M/T_S . The chosen parameters are $g_{\text{eff}}^2/\Delta E = 0.1$, $\Delta E = 4k_B T_S$, $\omega t_m = \pi/2$, and $\hbar\omega = 1.5k_B T_S$.

Appendix C. Bound on Maximum Extractable Work by Mutual Information

Here we investigate the free energy difference of a system-meter setup in three steps: (1) starting in the initial state $\hat{\rho}_0 = \hat{\rho}_S \otimes \hat{\rho}_M$, (2) undergoing unitary evolution $\hat{\rho}(t) = \hat{U}\hat{\rho}_0\hat{U}^\dagger$, (3) after projection on the eigenstate of the meter $\langle n|\hat{\rho}(t)|n\rangle$. We assume that the Hamiltonian takes the form $\hat{H}(t) = \hat{H}_S + \hat{H}_M + \hat{V}_I(t)$ where $\hat{V}_I(t) \neq 0$, $t \in (0, t_m)$ where in general $[\hat{H}_S, \hat{V}_I] \neq 0$.

The free energy F is

$$F = \text{tr}\{\hat{\rho}\hat{H}\} - TS(\hat{\rho}) = \text{tr}\{\hat{\rho}\hat{H}\} + k_B T \text{tr}\{\hat{\rho} \ln \hat{\rho}\}. \quad (\text{C1})$$

The free energy difference going from the initial state $\hat{\rho}_0$ to a unitarily evolved state $\hat{\rho}(t_m)$ is

$$\begin{aligned} F_2 - F_1 &= \text{tr}\{(\hat{H}_S + \hat{H}_M)(\hat{\rho}(t_m) - \hat{\rho}_0)\} - T(S(\hat{\rho}(t_m)) - S(\hat{\rho}_0)) \\ &= \text{tr}\{(\hat{H}_S + \hat{H}_M)(\hat{\rho}(t_m) - \hat{\rho}_0)\}, \end{aligned} \quad (\text{C2})$$

where we used the property that unitary evolution is isentropic. The measurement work, defined in equation (4), is

$$\begin{aligned} W_{\text{meas}} &= \int_0^{t_m} dt \text{tr}\{\hat{\rho}(t)\dot{\hat{H}}(t)\} = \text{tr}\{(\hat{\rho}(t_m) - \hat{\rho}_0)(\hat{H}_S + \hat{H}_M)\} - \int_0^{t_m} dt \text{tr}\{\dot{\hat{\rho}}(t)\hat{H}(t)\} \\ &= \text{tr}\{(\hat{\rho}(t_m) - \hat{\rho}_0)(\hat{H}_S + \hat{H}_M)\}. \end{aligned} \quad (\text{C3})$$

This is the work invested in order to correlate the meter and system with each other.

The free energy of the system after projection on the eigenstates of the meter is given by

$$\begin{aligned}
 F_3(t_m) - F_3(0) &= \sum_n P(n, t_m) \text{tr} \left\{ \hat{H}_S \frac{\langle n | \hat{\rho}(t_m) | n \rangle}{P(n, t_m)} \right\} - \sum_n P(n, 0) \text{tr} \left\{ \hat{H}_S \frac{\langle n | \hat{\rho}_0 | n \rangle}{P(n, 0)} \right\} \\
 &\quad + k_B T \sum_n P(n, t_m) \text{tr} \left\{ \frac{\langle n | \hat{\rho}(t_m) | n \rangle}{P(n, t_m)} \ln \frac{\langle n | \hat{\rho}(t_m) | n \rangle}{P(n, t_m)} \right\} \\
 &\quad - k_B T \sum_n P(n, 0) \text{tr} \left\{ \frac{\langle n | \hat{\rho}_0 | n \rangle}{P(n, 0)} \ln \frac{\langle n | \hat{\rho}_0 | n \rangle}{P(n, 0)} \right\} \\
 &= \text{tr} \left\{ \hat{H}_S \left(-\hat{\rho}_S + \sum_n \langle n | \hat{\rho}(t_m) | n \rangle \right) \right\} \\
 &\quad + k_B T \sum_n \text{tr} \{ \langle n | \hat{\rho}(t_m) | n \rangle (\ln \langle n | \hat{\rho}(t_m) | n \rangle - \ln P(n, t_m)) \} \\
 &\quad - k_B T \text{tr} \{ \hat{\rho}_S \ln \hat{\rho}_S \}.
 \end{aligned} \tag{C4}$$

In the final expression, the first term corresponds to the \hat{H}_S -term in the measurement work (equation (C3)). Hence, that part of the energy difference is less interesting as it always has to be paid for through coupling and decoupling. However, for a non-demolishing measurement, i.e. $[\hat{H}_S, \hat{V}_I] = 0$, we find that $\hat{\rho}_S(t_m) = \hat{\rho}_S(0)$ making the free energy difference

$$\Delta F = k_B T \sum_n \text{tr} \{ \langle n | \hat{\rho}(t_m) | n \rangle (\ln \langle n | \hat{\rho}(t_m) | n \rangle - \ln P(n, t_m)) \} - k_B T \text{tr} \{ \hat{\rho}_S \ln \hat{\rho}_S \} \tag{C5}$$

$$= T_S (S(t_m) - S(0)) = T_S I(t_m). \tag{C6}$$

Appendix D. Maximum Extractable Work by Measurement

This section builds on the original idea and method on bounds on the maximum extractable work using measurement, used in appendices E–F of [25], applying them here to a system utilising a QHO as a meter, in contrast to the free particle used in the original work of [25].

Assuming that we follow the scheme laid out in section 3 we extract work from our system by some unitary transformation leaving the system in a passive state. However, this passive state does not necessarily correspond to the thermal state given by the temperature T_S of the thermal bath coupled to the TLS. As such, we may imagine that we insert a heat engine and extract work from the rethermalisation process going from some arbitrary passive state to the thermal state specified by the temperature T_S . The heat capacity is given by

$$C(T) = k_B \beta^2 \frac{d^2}{d\beta^2} \ln Z_S = \frac{\Delta e^2}{k_B T^2} \frac{e^{-\Delta E/k_B T}}{(1 + e^{-\Delta E/k_B T})^2}, \tag{D1}$$

where $\beta = (k_B T)^{-1}$ is the inverse temperature and $Z_S = \sum_i e^{-\beta E_i}$ is the partition function with E_i the i th eigenenergy.

Using the conditional probabilities of obtaining $|1\rangle$ or $|0\rangle$ given the measurement outcome n at time t_m we are either in a passive ($P(0|n, t_m) > P(1|n, t_m)$) or active state ($P(1|n, t_m) > P(0|n, t_m)$). If one is in an active state, one can apply a π -pulse to unitarily extract work from it to end in a passive state. Once in a passive state, either immediately after measurement or after work extraction, we can define the temperature:

$$T_p(n, t_m) = \frac{\Delta E}{k_B} \left[\ln \left(\frac{P(1|n, t_m)}{P(0|n, t_m)} \right)^{-1} \Theta(P(1|n, t_m) - P(0|n, t_m)) + \ln \left(\frac{P(0|n, t_m)}{P(1|n, t_m)} \right)^{-1} \Theta(P(0|n, t_m) - P(1|n, t_m)) \right]. \quad (D2)$$

The Carnot efficiency gives the maximum amount of work that can be extracted through heat transfer as

$$W = Q \left(1 - \frac{T_C}{T_H} \right) \Rightarrow dW = dQ \left(1 - \frac{T_C}{T_H} \right), \quad (D3)$$

where T_C and T_H are the temperatures of the cold and hot reservoirs, respectively. There are two scenarios; (a) the passive state is hotter than the thermal state, that is, $T_p > T_s$, or (b) the passive state is colder than the thermal state, that is, $T_p < T_s$.

First investigate scenario (a), $T_p > T_s$. In this case $T_C = T_s$, and $T_H = T$ varying from T_p to T_s yielding the thermal work

$$W_{th}^{(a)} = - \int_{T_p}^{T_s} dT C(T) \left(1 - \frac{T_s}{T} \right). \quad (D4)$$

Next, investigate scenario (b), $T_p < T_s$. In this case we have $T_H = T_s$, and $T_C = T$ varying from T_p to T_s . The difference between scenarios (a) and (b) is that in scenario (b), part of the heat must be expended to heat up the TLS:

$$dQ_{sys} = dQ \frac{T}{T_s} \quad (D5)$$

which raises the temperature by

$$dT = \frac{dQ_{sys}}{C(T)} = dQ \frac{T}{T_s C(T)}. \quad (D6)$$

Hence, the work that can be extracted is

$$dW = dQ \left(1 - \frac{T}{T_s} \right), \quad (D7)$$

and

$$\begin{aligned} W_{th}^{(b)} &= \int_{T_p}^{T_s} dT C(T) \left(1 - \frac{T}{T_s} \right) \\ &= \int_{T_p}^{T_s} dT C(T) \left(\frac{T_s}{T} - 1 \right) \\ &= - \int_{T_p}^{T_s} dT C(T) \left(1 - \frac{T_s}{T} \right) \\ &= W_{th}^{(a)}, \end{aligned} \quad (D8)$$

meaning that in either case the extracted work is the same. On average then, the extracted work is

$$W_{th} = \sum_{n=0}^{\infty} P(n, t_m) \int_{T_p}^{T_s} dT C(T) \left(\frac{T_s}{T} - 1 \right). \quad (D9)$$

Evaluating the integral

$$W_{th} = \int_{T_p}^{T_s} dT C(T) \left(\frac{T_s}{T} - 1 \right) \quad (D10)$$

by making the variable substitution $y = \Delta E/k_B T$ yields

$$W_{th} = \frac{\Delta E \left(1 - \frac{T_s}{T_p} \right)}{1 + e^{\Delta E/k_B T_p}} - k_B T_s \ln \left(\frac{1 + e^{-\Delta E/k_B T_p}}{1 + e^{-\Delta E/k_B T_s}} \right). \quad (D11)$$

Inserting the expression for T_p into equation (D11) yields

$$\begin{aligned} W_{\text{th}} = & k_B T_S \left[P(0|n, t_m) (\ln P(0|n, t_m) - \ln b) + P(1|n, t_m) (\ln P(1|n, t_m) - \ln a) \right] \\ & \times \Theta [P(1|n, t_m) - P(0|n, t_m)] + k_B T_S \left[P(0|m, t_m) (\ln P(0|n, t_m) - \ln a) \right. \\ & \left. + P(1|n, t_m) (\ln P(1|n, t_m) - \ln a) \right] \times \Theta [P(0|n, t_m) - P(1|n, t_m)]. \end{aligned} \quad (\text{D12})$$

Adding and subtracting the term

$$k_B T_S \left[P(0|m, t_m) (\ln P(0|n, t_m) - \ln a) + P(1|n, t_m) (\ln P(1|n, t_m) - \ln a) \right] \Theta [P(1|n, t_m) - P(0|n, t_m)], \quad (\text{D13})$$

simplifying, and inserting the resulting expression into the average work defined in equation (D9) yields

$$\begin{aligned} W_{\text{th}} = & \sum_{n=0}^{\infty} k_B T_S \left\{ [P(1|n, t_m) - P(0|n, t_m)] \ln \left(\frac{b}{a} \right) \times \Theta [P(1|n, t_m) - P(0|n, t_m)] \right. \\ & \left. + P(0|n, t_m) (\ln P(0|n, t_m) - \ln a) + P(1|n, t_m) (\ln P(1|n, t_m) - \ln b) \right\}. \end{aligned} \quad (\text{D14})$$

Noting that $\ln(b/a) = -\Delta E/k_B T_S$ and using the ergotropy as defined in equation (25) we see that the first term is the average ergotropy, $-W_{\text{erg}}$. Further, noting that the two last terms make up the mutual information defined in equation (10) we can write the average thermal work as

$$W_{\text{th}}(t_m) = -W_{\text{erg}}(t_m) + T_S I(t_m). \quad (\text{D15})$$

Appendix E. Evaluation of the Measurement Work

We assume a Hamiltonian of the form

$$\hat{H}(t) = \hat{H}_S + \hat{H}_M + \hat{V}_I(t) \quad (\text{E1})$$

as per the main text where \hat{H}_S is the system from which work is to be extracted, \hat{H}_M is the meter used to probe the state of the system, and \hat{V}_I is the interaction Hamiltonian which in this case has the form

$$\hat{V}_I(t) = \begin{cases} g|1\rangle\langle 1| \otimes \hat{p}, & t \in (0, t_m) \\ 0, & t \notin (0, t_m) \end{cases}. \quad (\text{E2})$$

The time-evolution of the system is described by the density matrix $\hat{\rho}(t) = \exp(-\frac{i}{\hbar} \int_0^t dt' \hat{H}(t')) \hat{\rho}(0) \exp(-\frac{i}{\hbar} \int_0^t dt' \hat{H}(t'))$ and we note that $\dot{\hat{\rho}}(t) = -\frac{i}{\hbar} [\hat{H}(t), \hat{\rho}(t)]$. The system energy is given by $E(t) = \langle \hat{H}(t) \rangle = \text{tr} \{ \hat{\rho}(t) \hat{H}(t) \}$ and the time derivative is

$$\begin{aligned} \dot{E}(t) &= \text{tr} \left\{ \dot{\hat{\rho}}(t) \hat{H}(t) \right\} + \text{tr} \left\{ \hat{\rho}(t) \dot{\hat{H}}(t) \right\} = \text{tr} \left\{ -\frac{i}{\hbar} [\hat{H}(t), \hat{\rho}(t)] \hat{H}(t) \right\} + \text{tr} \left\{ \hat{\rho}(t) \dot{\hat{H}}(t) \right\} \\ &= \text{tr} \left\{ \hat{\rho}(t) \dot{\hat{H}}(t) \right\} \end{aligned} \quad (\text{E3})$$

where we used that $[\hat{H}(t), \hat{\rho}(t)] = i\dot{\hat{\rho}}/\hbar$. Thus the energy difference between time $t=0$ and time $t=t_m$ is

$$E(t_m) - E(0) = \int_0^{t_m} dt \dot{E}(t) = \int_0^{t_m} dt \text{tr} \left\{ \hat{\rho}(t) \dot{\hat{H}}(t) \right\}. \quad (\text{E4})$$

Here we may note that \hat{H}_S, \hat{H}_M are both time-independent and thus $\dot{\hat{H}}(t) = \dot{\hat{V}}_I(t)$. We write the interaction Hamiltonian as

$$\hat{V}_I(t) = g \Theta(t_m - t) \Theta(t) (|1\rangle\langle 1| \otimes \hat{p}) = g \Theta(t_m - t) \Theta(t) \hat{V}_I \quad (\text{E5})$$

$$\Rightarrow \dot{\hat{V}}_I(t) = g(-\delta(t_m - t) \Theta(t) + \Theta(t_m - t) \delta(t)) \hat{V}_I. \quad (\text{E6})$$

Inserting the time-derivative from equation (E5) into equation (E4) yields

$$\begin{aligned} E(t_m) - E(0) &= \int_0^{t_m} dt \operatorname{tr} \{ \hat{\rho}(t) g(-\delta(t_m - t) \Theta(t) + \Theta(t_m - t) \delta(t)) \hat{V}_I \} \\ &= \operatorname{tr} \{ \hat{\rho}(0) \hat{V}_I \} - \operatorname{tr} \{ \hat{\rho}(t_m) \hat{V}_I \} \end{aligned} \quad (\text{E7})$$

which is the result used in equation (20). Hence, the energy difference created simply by coupling and decoupling the system and meter is exactly what we defined as W_{meas} .

We can further expand this by evaluating each of the traces on their own. Expressing the initial density matrix as $\hat{\rho}(0) = [a|0\rangle\langle 0| + b|1\rangle\langle 1|] \otimes \sum_m P_m |m\rangle\langle m|$ where $\sum_m P_m = 1$ are the probabilities associated with the eigenstates of the meter. Thus the first of the traces can be evaluated as

$$\begin{aligned} \operatorname{tr} \{ \hat{\rho}(0) \hat{V}_I \} &= \sum_{n=0}^{\infty} \sum_{i=0}^1 \langle n|i| (a|0\rangle\langle 0| + b|1\rangle\langle 1|) \\ &\quad \otimes \sum_{m=0}^{\infty} P_m |m\rangle\langle m| g|1\rangle\langle 1| \otimes \hat{p}|i\rangle\langle n| \\ &= bg \sum_n \sum_m P_m \langle n|m\rangle \langle n|\hat{p}|m\rangle \\ &= bg \sum_m P_m \langle m|\hat{p}|m\rangle = 0 \end{aligned} \quad (\text{E8})$$

where we have used the completeness relation to eliminate the sum over n . The conclusion is that, for this particular model, turning the coupling on has no cost.

The second trace can similarly be evaluated, however this time the density matrix is no longer the initial density matrix but is rather time-evolved. Performing the same type of polaron transform used in appendix G, we may insert shift operators $\hat{D}^\dagger \hat{D}$ in strategic places, use the completeness relation, and observe that just as for the first trace only the $i=1$ term contributes to yield

$$\begin{aligned} \operatorname{tr} \{ \hat{\rho}(t) \hat{V}_I \} &= bg \sum_m P_m \langle m| e^{i\hat{H}'t/\hbar} \hat{p} e^{-i\hat{H}'t/\hbar} |m\rangle \\ &= bg \sum_m P_m \langle m| \hat{D}^\dagger(t) \hat{D} \hat{p} \hat{D}^\dagger(t) |m\rangle. \end{aligned} \quad (\text{E9})$$

Here we use commutators and the commutation relation $[f(\hat{x}), \hat{p}] = i\hbar \frac{df(\hat{x})}{d\hat{x}}$ to migrate the momentum operator from the centre to the left hand side, and the shift operators should cancel due to being Hermitian. In practice this becomes

$$\begin{aligned} bg \sum_m P_m \langle m| \hat{D}^\dagger(t) \hat{D} \hat{p} \hat{D}^\dagger(t) |m\rangle &= bg \sum_m P_m \langle m| \hat{D}^\dagger(t) (-Mg + \hat{p}) \hat{D} \hat{D}^\dagger(t) |m\rangle \\ &= -bg^2 M + bg \sum_m P_m \langle m| \hat{D}^\dagger(t) \hat{p} \hat{D}(t) |m\rangle \\ &= -bg^2 M + \sum_m P_m \langle m| (Mg \cos(\omega t) + \hat{p}) \hat{D}^\dagger(t) \hat{D}(t) |m\rangle \\ &= -bg_{\text{eff}}^2 (1 - \cos(\omega t)). \end{aligned} \quad (\text{E10})$$

Here $g_{\text{eff}}^2 = g^2 M$ and M is the mass of the harmonic oscillator. All in all the measurement work is then

$$W_{\text{meas}} = \operatorname{tr} \{ \hat{\rho}(0) \hat{V}_I \} - \operatorname{tr} \{ \hat{\rho}(t_m) \hat{V}_I \} = bg_{\text{eff}}^2 (1 - \cos(\omega t_m)). \quad (\text{E11})$$

Appendix F. Explicit Forms of the Joint Probabilities

The joint probabilities of finding the TLS in state $|i\rangle$ and the meter in state $|n\rangle$ at time t_m is given by

$$P(i, n, t_m) = \langle i| \langle n| \hat{\rho}(t_m) |n\rangle |i\rangle \quad (\text{F1})$$

according to equation (7). Here we present the calculations that result in explicit forms of these probabilities for our given system in section 3.

F.1. Joint Probability in the Absence of Interaction

The coupling (equation (17c)) is active only when the TLS is in the excited state. We begin with the easier case of examining the joint probability $P(i = 0, n, t_m)$ where the coupling is inactive. With $\hat{H}_0 = \Delta E|1\rangle\langle 1| + \frac{\mathcal{M}\omega^2}{2}\hat{x}^2 + \frac{1}{2\mathcal{M}}\hat{p}^2$ the joint probability is

$$\begin{aligned}
 P(0, n, t_m) &= \langle 0 | \langle n | \hat{\rho}(t_m) | n \rangle | 0 \rangle \\
 &= \langle 0 | \langle n | e^{-it_m \hat{H}_0 / \hbar} (a|0\rangle\langle 0| + b|1\rangle\langle 1|) \\
 &\quad \otimes \sum_m P_m |m\rangle\langle m| e^{it_m \hat{H}_0 / \hbar} |n\rangle\langle 0| \\
 &= a \sum_m P_m \langle n | m \rangle \langle m | n \rangle = a P_n \\
 &= a \frac{1}{Z_0} e^{-\beta_M \hbar \omega (n+1/2)} \\
 &= a (1 - e^{-\beta_M \hbar \omega}) e^{-\beta_M \hbar \omega n}
 \end{aligned} \tag{F2}$$

with the thermal distribution $P_n = e^{-\beta_M \hbar \omega (n+1/2)} / \sum_n e^{-\beta_M \hbar \omega (n+1/2)} = e^{-\beta_M \hbar \omega (n+1/2)} / Z_0$ and β_M being the inverse temperature of the meter.

F.2. Joint Probability in the Presence of Interaction

In this case the coupling is active and evaluation is less straightforward. We again make use of the polaron transformation described in appendix G and write

$$\begin{aligned}
 P(1, n, t) &= \langle 1 | \langle n | e^{-it \hat{H}_0 / \hbar} \hat{D}(\alpha) \hat{\rho}_0 \hat{D}^\dagger(\alpha) e^{it \hat{H}_0 / \hbar} | n \rangle | 1 \rangle \\
 &= b \sum_m P_m \langle n | \hat{D}(\alpha) | m \rangle \langle m | \hat{D}^\dagger(\alpha) | n \rangle \\
 &= b \sum_m P_m |\langle n | \hat{D}(\alpha) | m \rangle|^2.
 \end{aligned} \tag{F3}$$

The displacement operator has here been rewritten in the form

$$\hat{D}(\alpha) = e^{\alpha(t_m) \hat{a}^\dagger - \alpha^*(t_m) \hat{a}} \tag{F4}$$

$$\alpha \equiv \alpha(t_m) = g \sqrt{\frac{\mathcal{M}}{2\hbar\omega}} (\sin(\omega t_m) - i(\cos(\omega t_m) - 1)). \tag{F5}$$

The identity from [62]

$$\langle m | \hat{D}(\alpha) | n \rangle = \left(\frac{n!}{m!} \right)^{1/2} \alpha^{m-n} e^{-|\alpha|^2/2} L_n^{(m-n)}(|\alpha|^2) \tag{F6}$$

yields

$$P(1, n, t_m) = b \sum_m P_m \left| \left(\frac{m!}{n!} \right)^{1/2} \alpha^{n-m} e^{-|\alpha|^2/2} L_m^{(n-m)}(|\alpha|^2) \right|^2 \tag{F7}$$

where $L_m^{(n-m)}(x)$ are the generalised Laguerre polynomials and the thermal occupation $P_m = e^{-\beta_M \hbar \omega (m+1/2)} / \sum_n e^{-\beta_M \hbar \omega (m+1/2)} = e^{-\beta_M \hbar \omega (m+1/2)} / Z_0$ with β_M being the inverse temperature of the meter.

In the limit $\hbar\omega \gg k_B T_M$, we can assume that only the ground state of the oscillator is occupied, that is, $m = 0$ and $P_{m=0} = 1$. Equation (F7) can then be written as

$$\begin{aligned}
 P(1, n, t_m) &= b \left(\frac{1}{n!} \right) |\alpha|^{2n} e^{-|\alpha|^2} \\
 &= b \left(\frac{1}{n!} \right) \left[\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m)) \right]^n e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))}.
 \end{aligned} \tag{F8}$$

Appendix G. Work Extraction in the Zeno Limit

The quantum Zeno effect is essentially a freezing of the system dynamics through fast, repeated measurement [63, 64]. Referring to the engine in the main text, we may then ask how it behaves in the Zeno limit and if net positive work extraction is possible.

The net work output of the engine is $W_{\text{net}} = W_{\text{ext}} - W_{\text{meas}}$, hence the condition to fulfill is $W_{\text{ext}} > W_{\text{meas}}$. Using equations (4) and (25), the condition is

$$\Delta E \sum_{n=0}^{\infty} P(n, t_m) [P(1|n, t_m) - P(0|n, t_m)] \Theta(P(1|n, t_m) - P(0|n, t_m)) > b g_{\text{eff}}^2 (1 - \cos(\omega t_m)) \quad (\text{G1})$$

and we remind ourselves that a, b are the initial ground and excited state populations of the TLS

$$a = \frac{1}{1 + e^{-\beta_S \Delta E}} \quad (\text{G2})$$

$$b = \frac{e^{-\beta_S \Delta E}}{1 + e^{-\beta_S \Delta E}} \quad (\text{G3})$$

where β_S is the inverse temperature.

When the system evolves unitarily there are essentially two timescales; the time scale of the harmonic oscillator ωt_m and the time scale of information transfer $g_{\text{eff}} t_m$. We would argue that in the Zeno limit both of these timescales must be small. Expanding the measurement work, W_{meas} , equation (20), around $\omega t_m = 0$ yields

$$W_{\text{meas}} \approx b g_{\text{eff}}^2 \frac{\omega^2 t_m^2}{2}. \quad (\text{G4})$$

We rewrite the extracted work in the following way: let $n' = \min_n (P(1|n t_m) > P(0|n, t_m))$ and find

$$W_{\text{ext}} = \Delta E \sum_{n=n'}^{\infty} [P(1, n, t_m) - P(0, n, t_m)], \quad (\text{G5})$$

where Bayes' rule was used. The joint probabilities of TLS state i and QHO state n at time t_m are given by $\langle i | \langle n | \hat{\rho}(t_m) | n \rangle | i \rangle$. The density matrix is $\hat{\rho}(t_m) = e^{-i t_m \hat{H}/\hbar} \hat{\rho}_S(0) \otimes \hat{\rho}_M(0) e^{-i t_m \hat{H}/\hbar}$ with

$$\hat{\rho}_S(0) = a |0\rangle\langle 0| + b |1\rangle\langle 1| \quad (\text{G6})$$

$$\hat{\rho}_M(0) = \sum_{n=0}^{\infty} \frac{1}{Z_M} e^{-\beta_M \hbar \omega (n+1/2)} |n\rangle\langle n| \quad (\text{G7})$$

and Z_M is the partition function. We can also diagonalise the Hamiltonian by way of the displacement operator $\hat{D} = e^{i M g |1\rangle\langle 1| \otimes \hat{x}/\hbar}$ to get

$$\hat{\rho}(t_m) = e^{-i t_m \hat{H}'/\hbar} \hat{D}^\dagger(t_m) \hat{D} \hat{\rho}(0) \hat{D}^\dagger(t_m) e^{i t_m \hat{H}'/\hbar} \quad (\text{G8})$$

$$\hat{H}' = \left(\Delta E - \frac{g_{\text{eff}}^2}{2} \right) |1\rangle\langle 1| + \frac{1}{2\mathcal{M}} \hat{p}^2 + \frac{\mathcal{M}\omega^2}{2} \hat{x}. \quad (\text{G9})$$

Here we also remind ourselves that $g_{\text{eff}}^2 = g^2 \mathcal{M}$ where \mathcal{M} is the mass of the harmonic oscillator.

With these preliminaries out of the way we may now write the average work extracted as

$$W_{\text{ext}} = \Delta E \sum_{n=n'}^{\infty} \left[b \sum_{m=0}^{\infty} \left(\frac{1}{Z_M} e^{-\beta_M \hbar \omega (m+1/2)} \langle n | \hat{D}^\dagger(t_m) \hat{D} | m \rangle \langle m | \hat{D}^\dagger \hat{D}(t_m) | n \rangle \right) - a \frac{1}{Z_M} e^{-\beta_M \hbar \omega (n+1/2)} \right]. \quad (\text{G10})$$

Using the Zassenhaus formula [65], evaluating the sum of the second term in W_{ext} , equation (G10), and simplifying now yields the result for the condition $W_{\text{ext}} > W_{\text{meas}}$

$$\sum_{n=n'}^{\infty} b \sum_{m=0}^{\infty} e^{-\beta_M \hbar \omega m} \langle n | e^{-i g t_m \hat{p}/\hbar} | m \rangle \langle m | e^{i g t_m \hat{p}/\hbar} | n \rangle > \frac{a e^{-\beta_M \hbar \omega n'}}{1 - e^{-\beta_M \hbar \omega}} + \frac{b g_{\text{eff}}^2 \omega^2 t_m^2}{2 \Delta E (1 - e^{-\beta_M \hbar \omega})}. \quad (\text{G11})$$

At this time we make use of the second condition, $gt \ll 1$, expand to order 2, and simplify further to get

$$\sum_{n=n'}^{\infty} e^{-\beta_M \hbar \omega n} \left[-\left(\frac{gt_m}{\hbar}\right)^2 \langle n | \hat{p}^2(0) | n \rangle + \sum_{m=0}^{\infty} e^{-\beta_M \hbar \omega m} \left(\frac{gt_m}{\hbar}\right)^2 \langle n | \hat{p}(0) | m \rangle \langle m | \hat{p}(0) | n \rangle \right] \\ > \frac{(g_{\text{eff}} \omega t_m)^2}{2\Delta E(1 - e^{-\beta_M \hbar \omega})} + \frac{(a-b)e^{-\beta_M \hbar \omega n'}}{b(1 - e^{-\beta_M \hbar \omega})}. \quad (\text{G12})$$

Here, a useful trick is to rewrite the momentum operator in terms of the creation and annihilation operators. Doing this and simplifying results in the final condition of equation (G12)

$$4n' \sinh^2\left(\frac{\beta_M \hbar \omega}{2}\right) > \frac{\hbar \omega}{\Delta E} e^{\beta_M \hbar \omega n'} + \frac{2\hbar(a-b)}{g_{\text{eff}}^2 \omega t_m^2 b}. \quad (\text{G13})$$

Now, n' which we may call an activation threshold for when we choose to extract work will be a function of t_m since it depends on where $P(1|n, t_m) > P(0|n, t_m)$. Nevertheless, for our model equation (G13) provides a condition for when positive work can be extracted from the engine.

We may also use equation (G13) to investigate the behaviour of W_{ext} as a function of t_m . First we identify that the first term on the right hand side comes from the measurement work, W_{meas} , and ignore this term to yield to condition $W_{\text{ext}} > 0$:

$$4n' \sinh^2\left(\frac{\beta_M \hbar \omega}{2}\right) > \frac{2\hbar(a-b)}{g_{\text{eff}}^2 \omega t_m^2 b}. \quad (\text{G14})$$

Solving for ωt_m gives

$$\omega t_m > \sqrt{\frac{2\hbar \omega (a-b)}{2n' \sinh^2\left(\frac{\beta_M \hbar \omega}{2}\right) g_{\text{eff}}^2 b}}, \quad (\text{G15})$$

where we see that a higher activation threshold n' allows for shorter measurement times. Or, conversely, going to shorter measurement times pushes the activation threshold higher, meaning that lower meter states will not contribute to the extracted work W_{ext} ,

$$n' > \frac{\hbar \omega (a-b)}{2 \sinh^2\left(\frac{\beta_M \hbar \omega}{2}\right) g_{\text{eff}}^2 b (\omega t_m)^2} \quad (\text{G16})$$

where $n' \in \mathbb{N}^0$.

Appendix H. Power as a Function of Time

In figure 7, the power shows an oscillatory behaviour, alternating between positive and negative values over time. This effect becomes more pronounced as the coupling strength increases. However, there are other parameters besides measurement time and coupling strength that influence this behaviour. To illustrate this, figure 17 shows the normalised power as a function of time for a higher temperature ratio $T_M/T_S = 0.2$, in contrast to the lower temperature ratio $T_M/T_S = 0.1$ used in figure 7. With higher meter temperature the non-smooth behaviour due to W_{ext} , see discussion in section 4, becomes more pronounced. Increasing the meter temperature, T_M , makes the meter less sensitive, thus, reducing the net extracted work. As shown in figure 6, when $T_M/T_S = 0.2$ the engine approaches the boundary of the power-producing region, particularly at both the lowest and highest coupling strengths. For both the lowest and highest coupling strengths, the information engine oscillates between the two modes of operation—the heat engine and heat valve. This reiterates the importance of the measurement time, t_m , as an engine parameter.

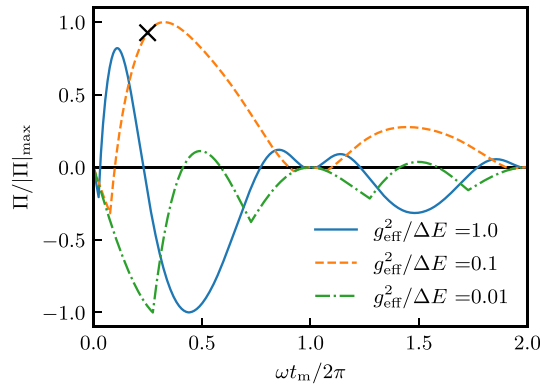


Figure 17. Power output normalised with its maximal absolute value, see equation (15), as a function of time for three values of the effective coupling strength, $g_{\text{eff}}^2/\Delta E = 0.01, 0.1, 1.0$. The chosen parameters are $T_M/T_S = 0.2$, $\Delta E = 4k_B T_S$, $\hbar\omega = 1.5k_B T_S$. The \times denotes a specific operating point, serving as reference in figures 10(a) and 12.

Appendix I. Thermodynamic efficiency and power at low meter temperatures

In the limit $\hbar\omega \gg k_B T_M$, we can assume that initially only the ground state of the oscillator is occupied. The extracted work W_{ext} , equation (G10), together with equations (F8) and (F2), can be written as

$$W_{\text{ext}} = \Delta E \left[b \sum_{n=n'}^{\infty} \left(\frac{1}{n!} \right) \left[\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m)) \right]^n \times e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))} \right] - \Delta E a e^{-\hbar\omega n'/k_B T_M}. \quad (\text{I1})$$

Note that for low meter temperatures $\hbar\omega \gg k_B T_M$ one needs to have at least $n' = 1$ to have $W_{\text{ext}} \geq 0$ while the second term in equation (I1) then vanishes. We note that n' depends on the underlying system and meter parameters. For $n' = 1$, equation (I1) reads

$$W_{\text{ext}} = \Delta E b \left[1 - e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))} \right]. \quad (\text{I2})$$

We calculate next the thermodynamic efficiency equation (16) in this limit. As we only consider the heat engine regime, we need to have $W_{\text{ext}} > W_{\text{meas}}$. Comparing equations (I2) and (E11) leads to the condition for all ωt_m

$$1 - e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))} > \frac{g_{\text{eff}}^2}{\Delta E} (1 - \cos(\omega t_m)). \quad (\text{I3})$$

By realising that the argument in equation (I3) $0 \leq 1 - \cos(\omega t_m) \leq 2$, we can further refine the condition equation (I3) to

$$\frac{2g_{\text{eff}}^2}{\hbar\omega} > \ln \frac{1}{1 - 2g_{\text{eff}}^2/\Delta E} \geq \frac{2g_{\text{eff}}^2}{\Delta E}. \quad (\text{I4})$$

The thermodynamic efficiency equation (16) can then be written with equations (I2) and (E11) as

$$\begin{aligned} \eta_{\text{HE}} &= 1 - \frac{W_{\text{meas}}}{W_{\text{ext}}} \\ &= 1 - \frac{g_{\text{eff}}^2 (1 - \cos(\omega t_m))}{\Delta E \left[1 - e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))} \right]}. \end{aligned} \quad (\text{I5})$$

The thermodynamic efficiency η_{HE} in equation (I5) reaches its maximum value for $\omega t_m \rightarrow 0$ which reads

$$\eta_{\text{HE}}(\omega t_m \rightarrow 0) = 1 - \frac{\hbar\omega}{\Delta E}, \quad (\text{I6})$$

which together with the condition $\Delta E \geq \hbar\omega$ in equation (I4) is bounded by 1. In fact, the condition $\Delta E \geq \hbar\omega$ is fulfilled along the whole Power-thermodynamic efficiency Pareto front as shown in figure 18.

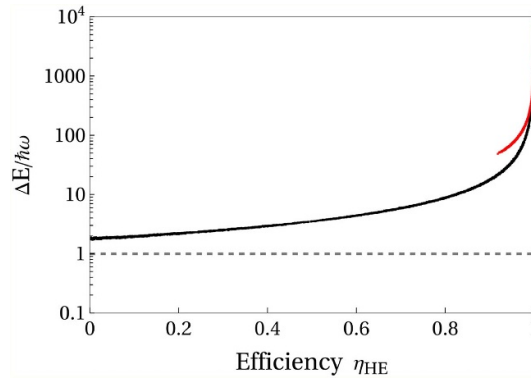


Figure 18. The ratio $\Delta E/\hbar\omega$ along the power-thermodynamic efficiency Pareto front in figure 10 by including the time for application of the π -pulse (red line) and neglecting it (black line) in the power, plotted as a function of thermodynamic efficiency η_{HE} .

However, this optimisation must be approached with care. The summation in equation (I1) begins at n' , the smallest value for which $P(1|n, t_m) > P(0|n, t_m)$. Our derivation of equations (I2) and (I5) specifically assumed that $n' = 1$. As shown in equation (F8), $P(1, n, t_m)$ depends on $b = (1 + e^{\beta_S \Delta E})^{-1}$ the excited state population of the TLS. Here $\beta_S = (k_B T_S)^{-1}$ is the inverse temperature of the system bath. If one sends ΔE to a large number, b approaches zero, which in turn means that n' must tend to infinity for the criterion $P(1|n', t_m) > P(0|n', t_m)$ to hold. A similar issue of $n' \rightarrow \infty$ occurs when taking $\hbar\omega \rightarrow \infty$. Therefore, to preserve the validity of equation (I5), the system temperature T_S must simultaneously increase with ΔE , thereby keeping the initial state populations a and b constant. As a result, the relative temperature $\frac{T_M}{T_S}$ vanishes, $\frac{T_M}{T_S} \rightarrow 0$ and $\eta_{HE} = \eta_{CA} = \eta_C$.

The power, equation (I5), can be written with equations (I2) and (E11) as

$$\Pi = \frac{b\Delta E \left[1 - e^{-\frac{g_{\text{eff}}^2}{\hbar\omega} (1 - \cos(\omega t_m))} \right] - b g_{\text{eff}}^2 (1 - \cos(\omega t_m))}{t_m}. \quad (\text{I7})$$

At maximum efficiency in the limit of $\omega t_m \rightarrow 0$, the power in equation (I7) vanishes as expected

$$\lim_{\omega t_m \rightarrow 0} \Pi = b g_{\text{eff}}^2 \omega^2 t_m \frac{\frac{\Delta E}{\hbar\omega} - 1}{2} \rightarrow 0. \quad (\text{I8})$$

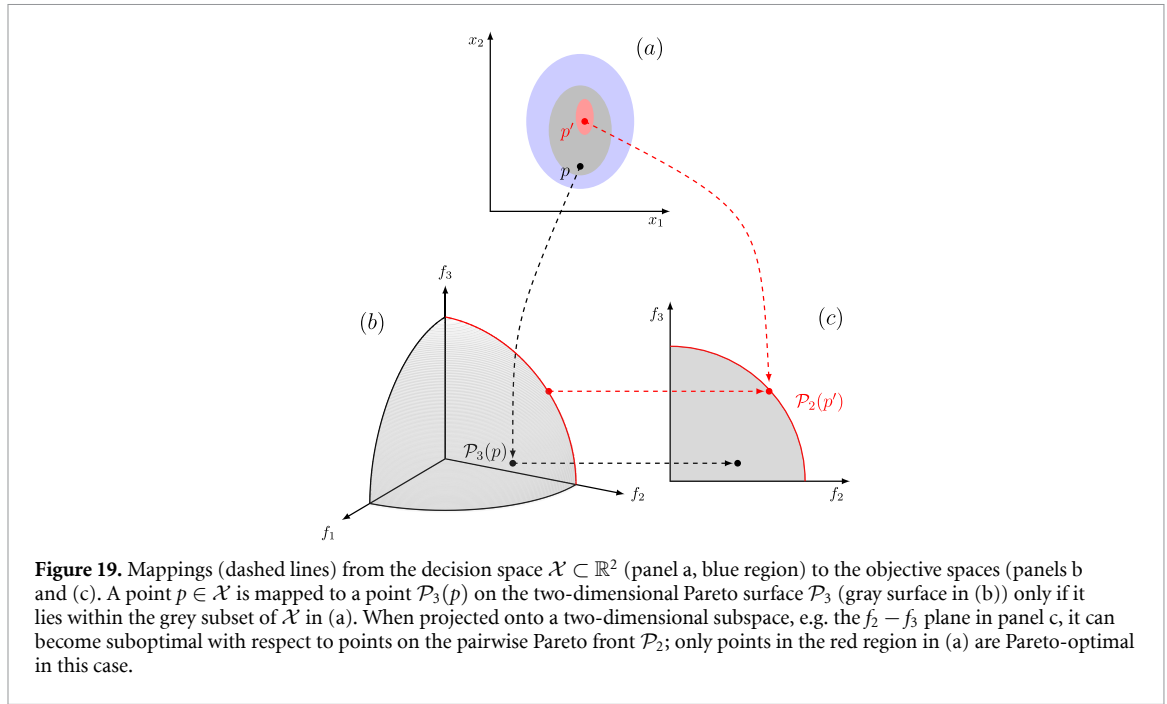
Appendix J. Pareto optimisation and genetic algorithms

Assume we have a system with a compact set of m governing parameters $\mathcal{X} = \{x_1, x_2, \dots, x_m\} \subset \mathbb{R}^m$ that fully describes the system at hand, and a set of n feasible objectives $\mathcal{Y} = \{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^n$, where each objective is a function $f_i : \mathcal{X} \rightarrow \mathbb{R}$ of the governing parameters, i.e. $y_i = f_i(x_1, x_2, \dots, x_m)$. To compute mutually optimal relations between the different objectives we make use of multi-function optimisation to find the parameter values \mathcal{X} that correspond to Pareto-optimal configurations. A configuration is said to be Pareto-optimal if the improvement of any objective is necessarily detrimental to at least one of the others, where we always assume that improving an objective means minimisation; other types of optimisation can always be written in this form. Mathematically, this condition can be encoded through the concept of Pareto dominance [31]. A vector $\mathbf{y} \in \mathcal{Y}$ is said to *dominate* another vector $\mathbf{y}' \in \mathcal{Y}$, expressed by $\mathbf{y} \succ \mathbf{y}'$, iff

$$\forall i \in \{1, \dots, n\} : y_i \leq y'_i, \text{ and } \exists j \in \{1, \dots, n\} : y_j < y'_j. \quad (\text{J1})$$

The minimal elements of the Pareto dominance partial ordering are called the Pareto-optimal objective vectors, and the subset of all such non-dominated objective vectors in \mathcal{Y} then constitutes the Pareto front, denoted by $\mathcal{P}(\mathcal{Y}) \subset \mathcal{Y}$.

A simple representation is shown in figure 19, where the full set of feasible, i.e. physically allowed governing parameters (blue region) is mapped onto a three-dimensional objective space ($m = 2, n = 3$). Only a particular subset of these parameters (gray region) is associated with the Pareto hypersurface (grey surface in (b)). Note that projecting the Pareto hypersurface down results in the majority of the previously Pareto-optimal points not being optimal any more. However, the pairwise Pareto front can



then either be computed through marginalisation or through a new Pareto optimisation directly onto that lower-dimensional objective space.

To compute numerically the Pareto fronts, we use the controlled elitist NSGA-II genetic algorithm [61] to perform the optimisation. Unlike, e.g. reinforcement learning approaches for determining Pareto fronts [39], which often require extensive model tuning and hyperparameter optimisation, our genetic algorithms heuristically explore the parameter space without the need for such adjustments.

Appendix K. Metric profiles near Pareto front

To illustrate the information efficiency, thermodynamic efficiency and power for the information engine operation near the Pareto front, we consider the system and meter parameters at point A on the Pareto front of power-thermodynamic efficiency and selectively vary one parameter, similar to our figures 4, 5, 6, 8 and 9. In general, we observe qualitatively similar behaviour in the metric profiles with respect to the parameters as in the non-optimal case (as studied with point ‘ \times ’ in tables 1 and 2). However, there is also a notable difference. For the thermodynamic efficiency figure 24 and information efficiency figure 21 as functions of measurement time, non-vanishing values appear only at very short times (or at $\omega t_m = 1$, due to the time periodicity given the harmonic oscillator as meter), after which they drop abruptly. This raises the question of experimental feasibility given the need for such precise, short-time measurements of an engine operating close the Pareto front.

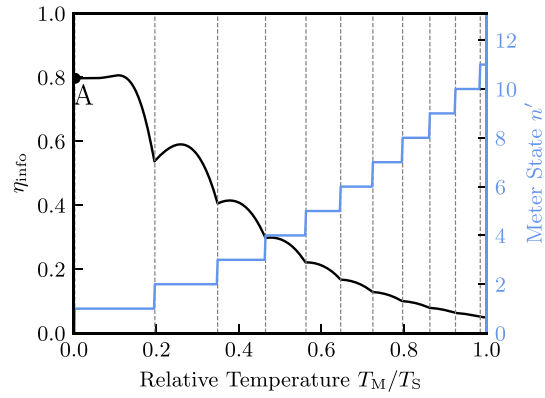


Figure 20. Information efficiency, η_{info} (solid black line), equation (13), on the left vertical axis, and the lowest lying meter level n' (solid blue line) at which the condition $P(1|, t_m) > P(0|n, t_m)$ is first satisfied on the right vertical axis. Both are plotted as functions of the relative temperature T_M/T_S . The chosen parameters correspond to point A in table 1.

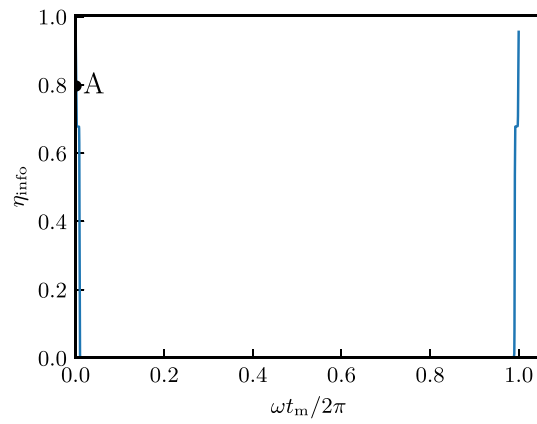


Figure 21. Information efficiency, equation (13), as a function of time. The chosen parameters correspond to point A in table 1.

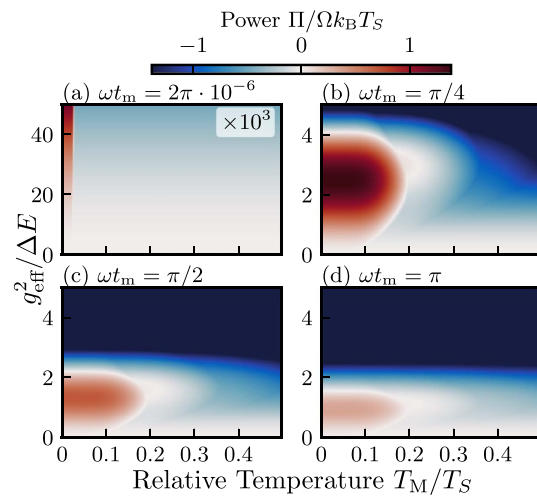


Figure 22. Power output (equation (15)) as a function of the relative temperature T_M/T_S and the effective relative coupling strength $g_{\text{eff}}^2/\Delta E$, shown at different measurement times. The fixed parameters $\hbar\omega$ and ΔE correspond to the values of point A in table 1. Panels (a)–(d) correspond to $\omega t_m = 2\pi \cdot 10^{-6}$, $\pi/4$, $\pi/2$, π , respectively. Red regions indicate positive power output (heat engine regime), while the blue regions indicate negative power output (heat valve regime). The data in panel (a) has been multiplied by a factor 10^3 to enhance visibility.

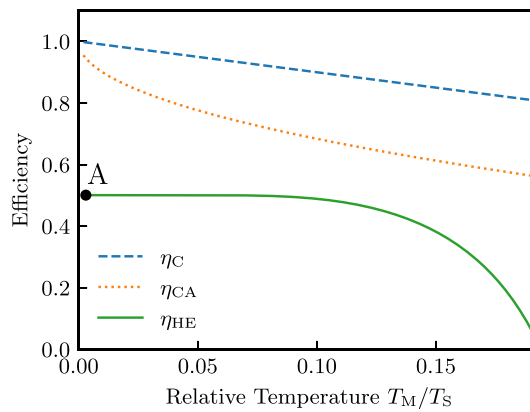


Figure 23. Efficiency, equation (16), as a function of relative temperature in the heat engine regime, defined by $T_M < T_S$ and $W_{\text{ext}} - W_{\text{meas}} > 0$. The Carnot efficiency, η_C , and Curzon–Ahlborn efficiency, η_{CA} , are shown for reference. Parameters are fixed corresponding to point A in table 1.

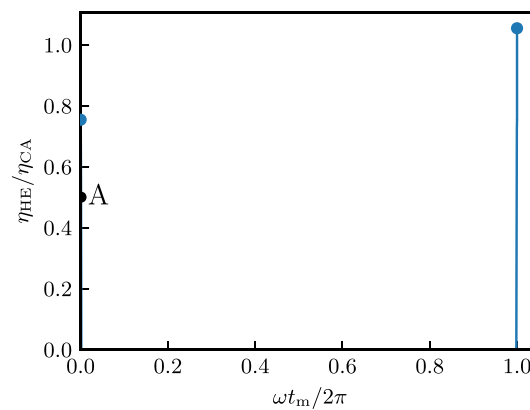


Figure 24. Thermodynamic efficiency, equation (16), as a function of time. Parameters are fixed corresponding to point A in table 1.

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