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SOFTWARE

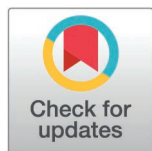
PEtab Select: Specification standard and supporting software for automated model selection

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Data availability statement: Code, data, and specific package versions for reproducing the reported results is available at Zenodo (<https://doi.org/10.5281/zenodo.17185040>). Code for the PEPtab Select package is maintained at GitHub (https://github.com/PEPtab-dev/pepab_select/), and documentation is hosted at

Abstract

A central question in mathematical modeling of biological systems is determining which processes are most relevant and how they can be described. There are often competing hypotheses, which yield different models. Model comparison requires parameter optimization and sampling methods. Yet, standards for the specification of model selection problems and the swift evaluation of a broad spectrum of approaches are not available. PEPtab Select addresses this challenge by providing a concise, standardized specification of model selection and its associated calibration problems through a new file format standard and software package. The standard facilitates the compact representation of even very large model selection problems; in one example, billions of model alternatives. PEPtab Select builds on the PEPtab standard for the specification of parameter estimation problems, and enables the use of state-of-the-art modelling and calibration workflows utilizing COPASI, Data2Dynamics, PEPtab.jl, and pyPESTO. PEPtab Select supports common model selection criteria (e.g., Akaike and Bayesian information criteria) and can be easily extended to use others. To ensure flexibility, PEPtab Select implements several model space exploration approaches, including basic brute-force, forward, and backward selection, and also advanced, flexible selection methods. PEPtab Select introduces the first standardization of model selection tasks, filling a critical gap in existing computational

ReadTheDocs (<https://petab-select.readthedocs.io/>).

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pipelines. It constitutes an essential contribution to FAIR research software in systems biology by promoting interoperability and reusability in model selection.

Author summary

Model selection is a crucial step in mathematical modeling, guiding the choice of components to include in a model. PETab Select automates this process across diverse modeling software frameworks and programming languages via (1) a new interoperable, language-agnostic standard for specifying large-scale model selection problems, and (2) a comprehensive software package that implements these selection methods. Developed through a community effort, PETab Select has been integrated into multiple modeling frameworks and is accessible to users of COPASI, Julia, MATLAB, and Python.

Introduction

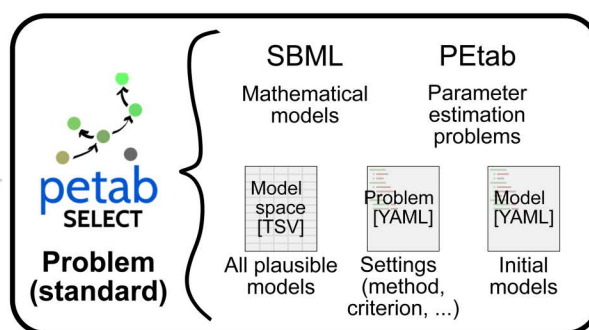
In systems biology, mechanistic models explain and predict dynamic processes, guide experimental design, and support hypothesis testing [1,2]. Because models encode biological assumptions in mathematical form, uncertainty arises both from incomplete hypotheses and from imperfect mathematical implementations. Model selection helps resolve these ambiguities by quantifying how well competing model formulations explain observed data [3].

The model-building cycle is increasingly supported by community standards. In this work, we primarily focus on ordinary differential equation (ODE) models; however, our work is designed to be adapted to other model classes as well. Models can be encoded in SBML [4], while simulations and parameterization workflows can be described using SED-ML [5] and PETab [6]. Indeed, PETab already allows one to specify measurement data, experimental conditions, observation models, and parameters, and thereby enables statistically-rigorous parameter estimation with noisy data via likelihood- or posterior-based objective functions. PETab additionally enables interoperable calibration and analysis pipelines across tools and programming languages. Building on this, several software tools also offer model selection capabilities, including information criteria (AIC, AICc, BIC) [7–9], Bayes factors [10], likelihood ratio tests [11], and cross-validation [12]. Related functionality includes feature selection and model reduction to improve identifiability [13–18], as well as multi-model inference [19]. Widely used and versatile tools include Data2Dynamics (D2D) [20], dMod [21], and pyPESTO [22]. However, while model selection is possible using these tools, model selection problems are typically specified in tool-specific or ad hoc ways, limiting reproducibility and interoperability. Furthermore, support for different model selection approaches remains fragmented.

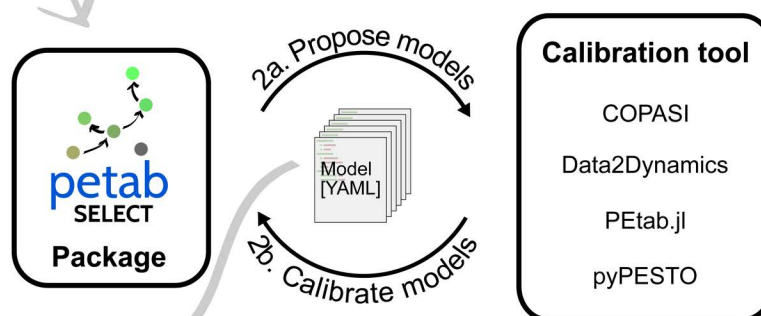
To address this gap, we introduce the PETab Select standard for encoding model selection problems in systems biology. Developed in a community effort, the standard extends SBML [4] and PETab [6] to provide a compact, interoperable

description of model spaces and associated calibration problems, enabling large-scale comparative analyses without requiring new toolchains. Alongside the standard, we provide a reference PETA Select software package that integrates into established calibration workflows. The package interfaces with PETA-compatible tools such as Data2Dynamics [20], PETA.jl [23], pyPESTO [22], and COPASI [24] via BasiCO [25]. It supports multiple exploration strategies—including brute force, forward, backward, and FAMoS [26]—while delegating model calibration to the selected backend tool. The following sections describe the standard and package and how they combine with existing workflows to streamline model selection (Fig 1).

1. Define problem



2. Select models



3. Analyze results



Fig 1. Model selection workflow with PETA Select. (1) The user defines the model selection **problem**, including the model space and the mathematical description of the set of possible process components, in the **standard**. (2) The user runs model selection via a **calibration tool** by sending the PETA Select problem to the PETA Select **package**, which initiates iterations of model selection. (2a) The package provides model candidates to the calibration tool based on the problem specification and the available calibration results. (2b) The calibration tool calibrates the proposed candidate models and sends the calibration results to the package. Iterations of (2a) and (2b) continue until the package sends a termination signal to indicate the end of model selection. The results are provided in the PETA Select model format and include all calibrated models with their calibration results. (3) The package can be used to perform subsequent analyses and visualizations of the results.

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Design and implementation

Scope

PEtab Select is designed to make model selection tasks portable across tools by separating (i) a standardized, tool-agnostic description of the model selection problem from (ii) the numerical calibration engine that evaluates candidate models. Concretely, PEPtab Select provides (1) a concise specification (standard) that describes a model selection task in terms of candidate model definitions and associated calibration problems, (2) a reference software package that orchestrates model space exploration and model comparison, and (3) standardized output that records calibrated models and selection results for downstream analysis (Fig 1). Calibration itself is performed by an external PEPtab-compatible tool, allowing users to retain their preferred solvers, optimizers, and workflow-specific features.

The limitations of PEPtab and the calibration tools are mostly inherited by PEPtab Select. For example, although there is good support for ordinary differential equation (ODE) models, there is little support for partial differential equation (PDE) models. Furthermore, although the supported model format SBML supports stochastic models in addition to ODEs, PEPtab Select provides no direct support for stochastic models – one reason is that model selection becomes complicated due to the (in general) intractable likelihood. However, we provide an example of model selection with a non-ODE model (with a user-supplied calibration tool) in the documentation.

The PEPtab Select standard

The standard extends **PEtab** using the same TSV/YAML-based structure while adding model-selection-specific configuration. PEPtab enables maximum likelihood computation that is required for model selection with PEPtab Select. The likelihood information is encoded in the PEPtab file format, which comprises tabular (TSV) data that specify experimental data and conditions, the observation and noise models, and parameters to be estimated, as well as the mathematical (structural) model.

PEtab Select builds upon PEPtab with a layer for defining the candidate model set and selection settings (e.g., exploration method and selection criterion). This ensures existing PEPtab workflows remain valid, while enabling large and complex model selection problems to be specified compactly and exchanged between tools.

Model space (TSV) The model space specifies which candidate models are admissible for selection. In PEPtab Select, model spaces are represented as a combination of (i) explicitly listed single models and (ii) *superset models* from which multiple candidates are derived by varying designated components through a table of plausible parameter values. This permits compact specifications of large combinatorial spaces. In the current scope, candidate models are derived by parameter-level switches and value assignments (e.g., “estimate” versus fixed values), which covers common use cases such as including/excluding processes, reactions, or effects via parameterization.

An example of defining a model space based on two superset models is given in Fig 2. Each superset model has an associated mathematical model and parameter estimation problem specified in the `model_subspace_petab_yaml` column. The set of submodels is constructed by customizing the superset model with all combinations of *plausible parameter values* in the additional table columns; for this specific example, subspaces `supersetA_models` and `supersetB_models` encode 16 and 8 models (Fig 2c'), respectively. Note that for the example superset models in Fig 2b and 2c, processes are turned “off” by setting parameters to 0, which is not always the case. For example, a fold-change effect parameter might be turned off by setting it to 1.

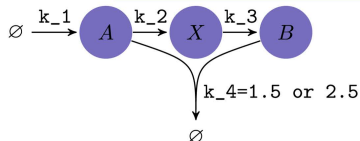
An additional feature is “metaparameters”, which we designed for model selection hypotheses that require multiple parameters to be turned on or off simultaneously. For example, a hypothesis involving the Michaelis-Menten kinetic, which involves the V_{max} and K_m parameters, requires that either both or neither of the parameters are in the model, to toggle the hypothesis on or off, respectively. This example is provided, with additional details, in the online documentation.

Model files (YAML) Given mathematical models, parameter estimation problems, and the model space, the package can run model selection methods. As the methods require calibrated models, the package sends the uncalibrated models

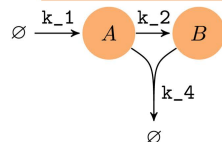
(a) The P_{ETab} Select model space table.

Model subspace metadata		Plausible parameter values			
model_subspace_id	model_subspace_petab_yaml	k ₁	k ₂	k ₃	k ₄
supersetA_models	problem1.yaml	0;estimate	0;estimate	0;estimate	1.5;2.5
supersetB_models	problem2.yaml	0;estimate	0;estimate	0	0;estimate

(b) The superset model for the subspace **supersetA_models**.



(c) The superset model for the subspace **supersetB_models**.



(c') All models in the subspace **supersetB_models**.

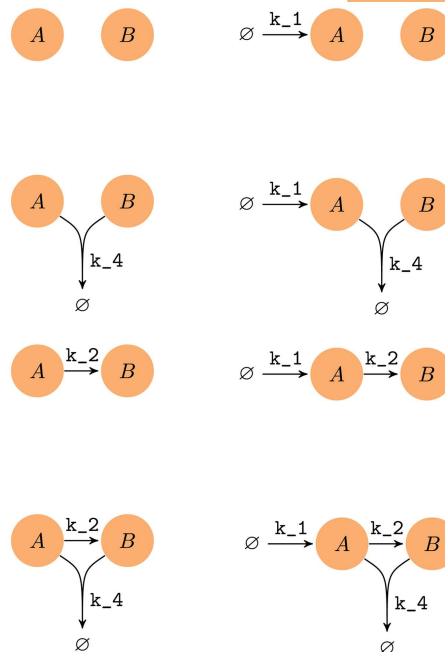


Fig 2. Example model space. (a) The model space table encodes model subspaces as rows. Each model subspace has an ID and an associated superset P_{ETab} problem, which includes the mathematical model. This superset problem is customized into single models according to the remaining columns, which contain semicolon-delimited lists of values that parameters (column headers) can take in the subspace. The next subfigures represent models as graphs. Nodes (colored circles) are variables (e.g., biochemical species), and arrows are processes, e.g., conversion ($\bullet \rightarrow \bullet$), import ($\emptyset \rightarrow \bullet$), or export ($\bullet \rightarrow \emptyset$) of the variables. The arrows are annotated with their associated parameters, e.g., k_4 is the rate constant associated with export of variables A and B due to an interaction between A and B. (b,c) Each subspace is associated with a superset model, where all possible parameters are estimated. Based on the superset models, candidate models are encoded by turning (estimation of unknown) parameters on or off. The total number of models in this example is 16 in subspace **supersetA_models**, plus (c') 8 in subspace **supersetB_models**.

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to a calibration tool, which calibrates the models and then sends the results back to the package (step 2 in Fig 1). The standard model file format is used to transmit all individual model information at all steps of the workflow (Fig 1). These files are generated automatically by the package, but can also be supplied manually, for example to specify initial models (as done in test case 0009 of the P_{ETab} Select test suite).

Model selection problem file (YAML) As in P_{ETab}, a single YAML-based “problem” file bundles the complete model selection task so compatible tools can load it from one entry point. The problem file links the relevant inputs (e.g., model space and P_{ETab} problems) and specifies the selection configuration, including the exploration method and the selection criterion.

The P_{ETab} Select package

The P_{ETab} Select package extends calibration workflows by providing an API that enables model selection while leaving model calibration to the backend tool. Users provide P_{ETab}/P_{ETab} Select files, initiate model selection, and obtain

standardized output in the PETab Select model format for analysis and visualization (Fig 1). Basic usage is typically with the calibration environment directly, rather than with the package. However, the pipelines are flexible, and more fine-grained interaction with the calibration tool and the package directly is supported during each iteration of model selection.

Calibration tools To support PETab Select, a calibration tool must be able to calibrate PETab problems and interface with the package API. The package is written in Python 3 and can be accessed via a Python API or via the command line for non-Python tools. A dedicated test suite supports validation of tool integrations. Model selection with PETab Select can currently be performed by COPASI [24] via BasiCO [25], Data2Dynamics [1,20], PETab.jl [23], and pyPESTO [22].

Model selection methods

The PETab Select package supports global and local model selection methods to explore a user-defined model space. In each iteration, the package proposes one or more candidate models, obtains their calibration results from the backend tool, evaluates the chosen selection criterion, and decides which model(s) to consider next. Bold terms below denote methods and features implemented in the package.

Global methods For exhaustive exploration, the package provides a **brute-force** mode that calibrates and scores every model in the specified space. This mode is useful for small or moderate model spaces and for benchmarking, but becomes impractical for combinatorial spaces (e.g., when n components can be switched on/off, yielding up to 2^n candidates).

Local methods For larger spaces, the package implements stepwise local exploration. The **forward** method iteratively adds components (or releases fixed parameters for estimation), the **backward** method removes them, and the **lateral** method performs swap moves that add and remove in the same step. These local methods operate from an initial model, which can be provided by the user or generated automatically by the package.

The package also supports **FAMoS** [26], a metaheuristic local strategy that switches between forward, backward, and lateral moves according to a customizable switching scheme. In addition, FAMoS supports a “**jump to most distant**” move to escape local neighborhoods [26].

In general, if brute-force is computationally feasible, then we recommend it. Otherwise, we recommend the FAMoS method. This is because more of the model space is reachable, than with classical backward or forward searches. However, FAMoS itself is primarily a sequence of local searches, which can result in longer runtimes in practice, compared to forward or backward searches. As the lateral method cannot reach models that differ in size to the initial model, we recommend only using it via FAMoS.

Model selection criteria All methods rely on a model selection criterion provided in the PETab Select problem specification. The package supports the popular information criteria **AIC** [7], **AICc** [8], and **BIC** [9]. Criteria are used consistently across candidate models by evaluating the calibrated fit while accounting for model complexity, enabling automated ranking and decision-making during exploration [3].

Other features The package provides several other features to enable flexible model selection. This includes automated summaries of the model selection run, custom or automated selection of initial models, limits on the number of models calibrated in any iteration, restarting of model selection runs with previous model selection results, and object-oriented programming such that other methods and selection criteria can be easily implemented.

FAIR data principles

The FAIR principles emphasize machine-actionable interoperability and reuse [27]. PETab Select supports these goals by: using machine-readable TSV/YAML formats; defining a documented controlled vocabulary; providing schemas (JSON Schema) for YAML-based files; and, enabling end-to-end reproducibility of model selection tasks across tools by building on community standards (SBML and PETab). Results are stored in the same standardized format, enabling consistent downstream analysis independent of the calibration backend (e.g., via package-provided visualization utilities).

Results

PEtab Select enables model selection in existing workflows, each with unique tool-specific features

To assess the interoperability of PESTab Select with different software suites, we tested its functionality in four PESTab-compatible tools: BasiCO (built on COPASI), Data2Dynamics, PESTab.jl, and pyPESTO. Each tool successfully passed the tests in the test suite, confirming that they can parse and execute model selection tasks defined in the PESTab Select standard. While the software tools have a broad spectrum of overlapping features, there are a few distinctive characteristics.

BasiCO (COPASI) provides the possibility of custom evaluation functions in place of the standard information criteria. Moreover, its programmable interface enables model-specific optimizer settings, so callbacks or post-processing steps can be incorporated into the model selection workflow. This flexibility allows users to adjust parameters on a per-model basis or to visualize results automatically after each calibration step.

Data2Dynamics supports transferring parameter estimates from one calibrated model to another, potentially reducing computation time when new models are introduced. Additionally, users can define custom calibration routines to adjust the workflow before, during, or after parameter fitting. For example, the number of multi-starts in an optimizer can be dynamically set based on the size of the parameter space, or diagnostic plots can be automatically generated to assess calibration quality.

PEtab.jl integrates with the Julia SciML ecosystem, tapping into highly efficient ODE solvers provided by `DifferentialEquations.jl` [28] and automatic differentiation routines [29]. These capabilities enable rapid prototyping of novel approaches and runtime-efficient parameter estimation [23].

pyPESTO supports ensemble-based approaches, for instance, using Akaike-weighted ensembles to combine the results from multiple candidate models. Its ready-to-use post-processing tools also facilitate structured output of calibration results and automated generation of diagnostic figures, streamlining the analysis of potentially large model spaces.

PEtab Select enables reproducible model selection across workflows

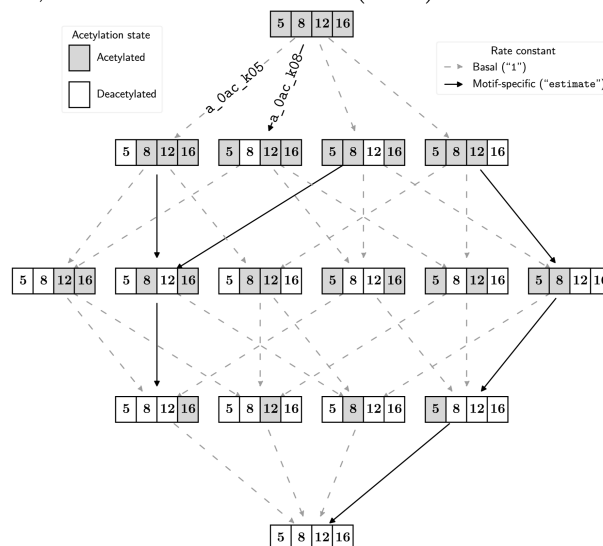
To assess the comparability of results across workflows, we consider an exemplary model selection problem from the work of Blasi et al. (2016) [13] that studied the acetylation of the histone H4 protein, which can be acetylated independently at 4 positions, yielding 16 possible acetylation patterns (motifs). The mathematical model is an ordinary differential equation (ODE) model that describes the acetylation and deacetylation reactions that convert one histone H4 motif into another. The ODE has 16 state variables that describe the abundance of the different histone motifs. The experimental data are taken from the original publication. Briefly, the experiment begins with an initial amount of the unacetylated histone H4 motif, and measurement data are the relative concentrations of 15 motifs at a single later time point. As the acetylation and deacetylation reactions are assumed to be fast compared to the experiment timescale, the measurements are assumed to be at steady state. Further details on the mathematical model and experimental data are provided in the original publication [13] and in the PESTab Select documentation.

A visualization of all 16 motifs, and the 32 acetylation reactions between them, is provided in Fig 3a. Deacetylation reactions are not depicted and are assumed to occur with the same rate constant. The same assumption serves as the null hypothesis for the acetylation reactions. The model selection problem is therefore to identify those acetylation reactions that require motif-specific, i.e., reaction-specific, rate constant parameters.

This model selection problem differs from the original publication in that we omit the additional 11 “site-specific” models in the original publication, which add a negligible computational cost and are not amongst the best models. Our model selection problem of 32 plausible motif-specific parameters therefore involves a model space of $2^{32} \approx 4.3$ billion plausible models.

The corresponding PESTab Select model space table is shown in Fig 3b. The problem files and all technical details of the experiments in this section are provided in the Zenodo repository (see Availability and future directions).

(a) Published best model, taken from Blasi et al. (2016).



(b) PETab Select model space table for the Blasi et al. (2016) model selection problem.

Model subspace metadata		Plausible parameter values		
model_subspace_id	model_subspace_petab_yaml	a_0ac_k05	a_0ac_k08	...
M	petab_problem.yaml	1;estimate	1;estimate	...

Fig 3. The Blasi et al. (2016) [13] model selection problem in PETab Select. (a) The reaction network for the published best model, represented as a graph similarly to Figs 2b-2c'. The histone chemical species can undergo acetylation reactions at four different positions (5, 8, 12, and 16). Nodes are acetylation states (motifs) of the histone, and arrows are acetylation reactions. The model selection problem involves two different possibilities for the rate constant of each reaction; it is either: the shared basal rate constant (the value is fixed to 1), or an estimated motif-specific rate constant (the value is estimated). The model selection problem is to identify the reactions with motif-specific rate constants, and the published best model contains seven (solid arrows). (b) There are 32 reactions, and therefore 32 independent hypotheses for motif-specific rate constants, and the published best model contains seven (a_0ac_k05 and a_0ac_k08) are shown here for brevity, with the remaining 30 parameters represented by the ellipses. This two-row, 34-column table encodes the full model space of ≈ 4.3 billion models.

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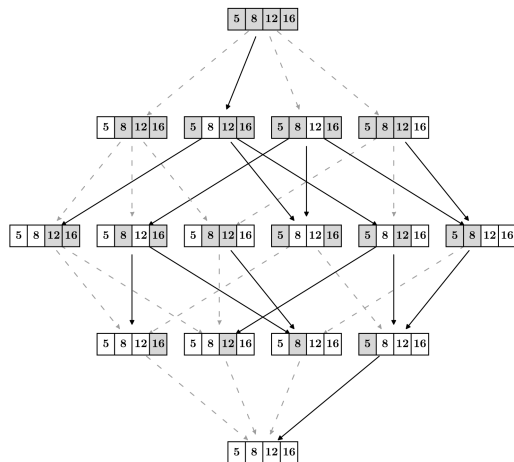
In the original publication, all ≈ 4.3 billion models were calibrated then compared, and the best model (Table S1 in the Supplemental Information of [13]) selected 7 reactions with motif-specific rate constants (Fig 3a, solid black arrows).

To solve our implementation of the model selection problem, we ran the PETab Select implementation of the FAMoS method [26] 100 times, and each run was initialized at a randomly chosen model in the model space that had on average 16 motif-specific parameters (Fig 4b). This first experiment with 100 FAMoS runs was to determine whether PETab Select can find the same published best model, and was conducted using only pyPESTO as the calibration tool. The best model across the 100 searches matched the published best model, and the FAMoS algorithm found it three times in the 100 runs (Fig 4c). In total, there were 83,125 ($\approx 0.00194\%$ of 2^{32} ; 58,858 unique) model calibrations across the 100 runs, which took 655.8 CPU hours.

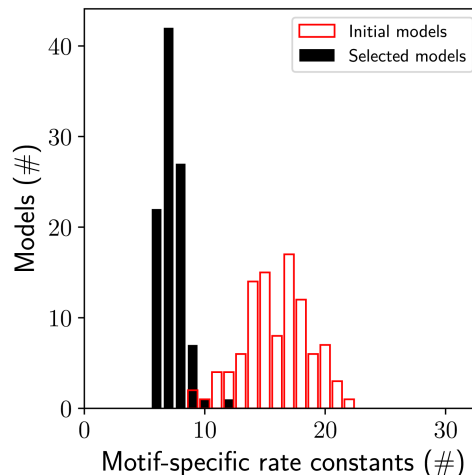
Extrapolating to the full model space, this saved $\frac{2^{32}}{83125} \cdot \frac{655.8}{24 \cdot 365} = 3868$ CPU years; hence, FAMoS rendered the standardized PETab Select approach computationally feasible, meaning that tailoring the simulation and optimization routines to the problem, as was done in the original publication, is not necessary.

One of the three successful runs involved 339 model calibrations with pyPESTO, and its initial model is given in Fig 4a. To assess reproducibility of model selection results generated with PETab Select across all calibration tools, we repeated this FAMoS run with each tool.

(a) Initial model.



(b) Model sizes across all 100 searches.



(c) Waterfall plot of the 100 search results.

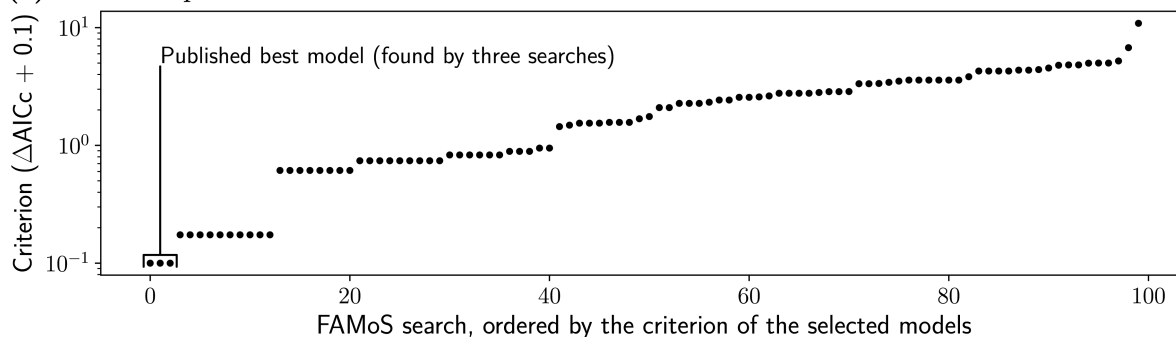


Fig 4. Multi-start FAMoS searches solve the Blasi et al. (2016) model selection problem. (a) An initial model, visualized as in Fig 3a, that was used to initialize one of the FAMoS searches. This is the initial model that was used later to assess reproducibility with all calibration tools. (b) The sizes of models before and after model selection. The published best model had seven motif-specific rate constants. (c) The criterion of the selected model from each of the 100 FAMoS searches.

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All runs, i.e., with COPASI (BasiCO), Data2Dynamics and PETA.jl, reproduced the same sequence of local search methods and calibrated similar sets of 339 models. Importantly, the same best model (Fig 3a) was found with each of the calibration tools.

Model selection for the considered problem is inherently challenging. The search space is vast and populated by many candidate models whose information criterion values differ only within numerical precision, so minute floating-point variations render the ranking effectively non-deterministic across machines. Although the reproduced single FAMoS search (with 339 model calibrations) takes slightly different trajectories through the model space on repeated executions within and between calibration tools (Fig 5, calibration tool rows), each trajectory delivers the same overall improvement within simulator and optimizer tolerances (Fig 5, row “Criterion ($\Delta AICc$)”), with negligible differences (< 0.01) in criterion across calibration tools.

Indeed, classical forward and backward selection mostly failed to arrive at the optimal solution. By contrast, the FAMoS algorithm [26] reproducibly converged on models with markedly better criterion scores. Overall, this example highlights that, in large model spaces where brute-force is intractable, multi-start local searches can be a useful alternative. Although no guarantees can be made about multi-start local searches, they can be performed similarly to multi-start optimization in

	Iteration													
	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Local search method	→	→	←	←	←	←	←	←	←	←	←	←	→	⇒
Candidate models (#)	17	16	16	15	14	13	12	11	10	9	8	7	23	168
Criterion (ΔAICc)	20	•	•	•	•	•	•	•	•	•	•	•	•	•
New model selected	✓	✗	✓	✓	✓	✓	✓	✓	✓	✓	✓	✗	✗	✗
Selected parameters (#)	16	16	15	14	13	12	11	10	9	8	7	7	7	7
Change in selected parameters. θ_i : added. θ_i : removed. $\emptyset$: no change.														
BasiCO (COPASI)	θ_6	$\emptyset$	θ_{12}	θ_{26}	θ_{22}	θ_{20}	θ_9	θ_8	θ_{10}	θ_{25}	θ_{13}	$\emptyset$	$\emptyset$	$\emptyset$
Data2Dynamics	θ_6	$\emptyset$	θ_{12}	θ_{26}	θ_{22}	θ_{20}	θ_9	θ_8	θ_{10}	θ_{25}	θ_{13}	$\emptyset$	$\emptyset$	$\emptyset$
PEtab.jl	θ_6	$\emptyset$	θ_{26}	θ_9	θ_{22}	θ_{20}	θ_{12}	θ_8	θ_{10}	θ_{25}	θ_{13}	$\emptyset$	$\emptyset$	$\emptyset$
pyPESTO	θ_6	$\emptyset$	θ_{10}	θ_{22}	θ_9	θ_{20}	θ_{12}	θ_{26}	θ_8	θ_{25}	θ_{13}	$\emptyset$	$\emptyset$	$\emptyset$
Same model across tools	✓	✓	✗	✗	✗	✗	✗	✗	✓	✓	✓	✓	✓	✓

Fig 5. Reproducibility of model selection across calibration tools. Local search methods are the forward (→), backward (←), and lateral (⇒) methods. All calibration tools reproduced the same criterion value in each iteration, within 0.01 ΔAICc . The only difference between tools in each iteration is in the change in selected parameters. θ_i is the i th motif-specific parameter; see the Zenodo repository for details.

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order to increase the chance of finding the best model(s). We recommend running local searches until (i) the goodness-of-fit (and other standard checks) of the selected model(s) are acceptable [2], and (ii) those selected model(s) have been found by multiple independent local searches.

Availability and future directions

Code, data, and specific package versions for reproducing the reported results is available at Zenodo (<https://doi.org/10.5281/zenodo.17185040>). Code for the PESTab Select package is maintained at GitHub (https://github.com/PEtab-dev/peatab_select/), and documentation is hosted at ReadTheDocs (<https://peatab-select.readthedocs.io/>).

There are several useful directions in which PESTab Select can be improved. Currently, PESTab Select only provides support for the SBML mathematical model format, as this is the only model format supported by PESTab. However, PESTab Select has no direct dependency on the model format. Hence, this is expected to improve with the next version of PESTab, which will support non-SBML model formats. An important issue in model selection is parameter identifiability, which is required for many of the popular model selection criteria including the AIC. Accurate identifiability analysis is computationally costly and therefore infeasible in large model spaces; hence, a potential improvement for PESTab Select is automated identifiability analysis, e.g., for a subset of models as a heuristic to ensure model selection is accurate. Further implementation improvements include shifting calibration-tool specific features into the package directly, such that those features can be used with any calibration tool. One example would be the termination of a model selection iteration as soon as a better model is found.

Several opportunities for the improvement of model selection methodology were identified when working with the problem published by Blasi et al. (2016) [13]. On one hand, the analysis revealed that reproducibility could be boosted by developing tailored strategies for handling the case that multiple models are equivalent in best criterion value (up to numerical noise). If performing a backward search, one possibility is to branch the backward search into multiple backward searches, one per equivalent model. On the other hand, a further improvement of search algorithms would be beneficial, in particular for large model spaces, e.g., an automatic tuning of metaheuristics in the FAMoS method across runs.

In summary, PETab Select establishes, for the first time, a unified standard and reference implementation for large-scale, reproducible model selection. By decoupling the description of a model selection task from the calibration engine that solves it, the framework enables researchers to tackle search spaces of billions of candidates in whichever environment—COPASI, Data2Dynamics, pyPESTO, PETab.jl, or future tools—best suits their workflows. This interoperability not only accelerates day-to-day practice, but also lowers the barrier for methodological innovation, allowing new inference algorithms to be benchmarked immediately on realistic problems. We therefore expect PETab Select to become a cornerstone for transparent, comparable, and scalable model selection across the life and physical sciences.

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